

RATIONAL POINTS ON TWISTED K3 SURFACES AND DERIVED EQUIVALENCES

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ABSTRACT. Using a construction of Hassett and Várilly-Alvarado, we produce derived equivalent twisted K3 surfaces over \mathbf{Q} , \mathbf{Q}_2 , and \mathbf{R} , where one has a rational point and the other does not. This answers negatively a question recently raised by Hassett and Tschinkel.

1. INTRODUCTION

A twisted K3 surface is a pair (X, α) , where X is a K3 surface and $\alpha \in \text{Br}(X)$ is a Brauer class. In a recent survey paper [5], Hassett and Tschinkel asked whether the existence of a rational point on a twisted K3 surface is invariant under derived equivalence. More precisely, they asked:

Question. *Let (X_1, α_1) and (X_2, α_2) be twisted K3 surfaces over a field k . Suppose there is a k -linear equivalence*

$$D^b(X_1, \alpha_1) \simeq D^b(X_2, \alpha_2)$$

of twisted derived categories. Then is the existence of a k -point of (X_1, α_1) equivalent to the existence of a k -point of (X_2, α_2) ?

By definition, a k -point of a twisted K3 surface (X, α) is a point $x \in X(k)$ such that the evaluation $\alpha(x) = 0 \in \text{Br}(k)$. Equivalently, it is a k -point of the \mathbf{G}_m -gerbe over X associated to α .

In [5], it is shown that for the untwisted case of the question where α_1, α_2 vanish, the answer is positive over certain fields k , e.g. \mathbf{R} , finite fields, and p -adic fields (provided the X_i have good reduction, or $p \geq 7$ and the X_i have ADE reduction). The purpose of this paper is to show that if α_1, α_2 are allowed to be nontrivial, the answer to the question is negative for $k = \mathbf{Q}, \mathbf{Q}_2$, and \mathbf{R} .

We work over a field k of characteristic not equal to 2, and consider a double cover $Y \rightarrow \mathbf{P}^2 \times \mathbf{P}^2$ ramified over a divisor of bidegree $(2, 2)$. The projection $\pi_i : Y \rightarrow \mathbf{P}^2$ onto the i -th \mathbf{P}^2 factor, $i = 1, 2$, realizes Y as a quadric fibration. Provided that the discriminant divisor of π_i is smooth, the Stein factorization of the relative Fano variety of lines of π_i is a K3 surface X_i , which comes with a natural Brauer class α_i . In this setup, we prove the following result.

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Theorem 1.1. *There is a k -linear equivalence $D^b(X_1, \alpha_1) \simeq D^b(X_2, \alpha_2)$.*

We note that this result seems to be known to the experts (at least for $k = \mathbf{C}$), but we could not find a proof in the literature.

Hassett and Várilly-Alvarado studied the above construction of twisted K3s in relation to rational points [6]. They show that over $k = \mathbf{Q}$, if certain conditions are imposed on the branch divisor $Z \subset \mathbf{P}^2 \times \mathbf{P}^2$ of Y , the class α_1 gives a (transcendental) Brauer–Manin obstruction to the Hasse principle on X_1 . A priori, α_2 need not obstruct the existence of rational points on X_2 . In fact, it is possible that X_2 has rational points, but the conditions imposed on Z result in very large coefficients of the defining equation of X_2 , making a computer search for points infeasible.

In this paper, we observe that the 2-adic condition imposed by Hassett and Várilly-Alvarado can be relaxed, while still guaranteeing α_1 gives a Brauer–Manin obstruction (see Lemma 4.5). The upshot is that the defining coefficients of X_2 are much smaller, making it easy to find rational points with a computer. Up to modifying the α_i by a Brauer class pulled back from $k = \mathbf{Q}$, we obtain the desired example over \mathbf{Q} . We also check the example “localizes” over \mathbf{Q}_2 and \mathbf{R} . More precisely, we prove:

Theorem 1.2. *For $k = \mathbf{Q}, \mathbf{Q}_2$, or \mathbf{R} , the divisor $Z \subset \mathbf{P}^2 \times \mathbf{P}^2$ can be chosen so that there are Brauer classes $\alpha'_i \in \text{Br}(X_i)$, congruent to α_i modulo $\text{Im}(\text{Br}(k) \rightarrow \text{Br}(X_i))$, such that:*

- (1) *There is a k -linear equivalence $D^b(X_1, \alpha'_1) \simeq D^b(X_2, \alpha'_2)$,*
- (2) *(X_1, α'_1) has no k -point,*
- (3) *(X_2, α'_2) has a k -point.*

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2. CONSTRUCTION OF THE TWISTED K3 SURFACES

In this section, k denotes a base field of characteristic not equal to 2.

2.1. Quadric fibrations. We start by reviewing some terminology on quadric fibrations. Let S be a variety over k , i.e. an integral, separated scheme of finite type over k . Let \mathcal{E} be a rank $n \geq 2$ vector bundle on S , i.e. a locally free \mathcal{O}_S -module of rank n . Our convention is that the projective bundle of \mathcal{E} is the morphism

$$p : \mathbf{P}(\mathcal{E}) = \text{Proj}_S(\text{Sym}^\bullet(\mathcal{E}^*)) \rightarrow S.$$

A quadric fibration is determined by a line bundle \mathcal{L} on S and a nonzero section

$$s \in \Gamma(\mathbf{P}(\mathcal{E}), \mathcal{O}_{\mathbf{P}(\mathcal{E})}(2) \otimes p^*\mathcal{L}) = \Gamma(S, \text{Sym}^2(\mathcal{E}^*) \otimes \mathcal{L}).$$

Namely, the zero locus of s on $\mathbf{P}(\mathcal{E})$ defines a subvariety Q , and the restriction $\pi : Q \rightarrow S$ of $p : \mathbf{P}(\mathcal{E}) \rightarrow S$ is the associated *quadric fibration*, which if flat is of relative dimension $n - 2$. Below we will be specifically interested in flat quadric fibrations of relative dimension 2, which we refer to as *quadric surface fibrations*.

Note that the section of $\mathrm{Sym}^2(\mathcal{E}^*) \otimes \mathcal{L}$ defining a quadric fibration corresponds to a morphism $q : \mathcal{E} \rightarrow \mathcal{E}^* \otimes \mathcal{L}$. Taking the determinant gives rise to a section of $\det(\mathcal{E}^*)^2 \otimes \mathcal{L}^n$ whose vanishing defines the *discriminant locus* $D \subset S$, which is a divisor provided $\pi : Q \rightarrow S$ is generically smooth. The fibration $\pi : Q \rightarrow S$ is said to have *simple degeneration* if the fiber over every closed point of S is a quadric of corank ≤ 1 . We note that if $\pi : Q \rightarrow S$ is flat and generically smooth and S is smooth over k , then the discriminant divisor D is smooth over k if and only if Q is smooth over k and π has simple degeneration [1, Proposition 1.6].

2.2. Twisted K3 surfaces. Let V_1 and V_2 be 3-dimensional vector spaces over k . We denote by H_i the hyperplane class on $\mathbf{P}(V_i)$; by abuse of notation, we denote by the same letter the pullback of H_i to any variety mapping to $\mathbf{P}(V_i)$. Let

$$\pi : Y \rightarrow \mathbf{P}(V_1) \times \mathbf{P}(V_2)$$

be the double cover of $\mathbf{P}(V_1) \times \mathbf{P}(V_2)$ ramified over a smooth divisor Z in the linear system $|2H_1 + 2H_2|$. Let $\mathrm{pr}_i : \mathbf{P}(V_1) \times \mathbf{P}(V_2) \rightarrow \mathbf{P}(V_i)$ be the i -th projection, and let $\pi_i = \mathrm{pr}_i \circ \pi : Y \rightarrow \mathbf{P}(V_i)$.

Lemma 2.1. *Let $\mathcal{E}_1 = (V_2 \otimes \mathcal{O}) \oplus \mathcal{O}(H_1)$ on $\mathbf{P}(V_1)$ and $\mathcal{E}_2 = (V_1 \otimes \mathcal{O}) \oplus \mathcal{O}(H_2)$ on $\mathbf{P}(V_2)$. Then for $i = 1, 2$ there is a commutative diagram*

$$\begin{array}{ccc} Y & \xrightarrow{j_i} & \mathbf{P}(\mathcal{E}_i) \\ \pi_i \downarrow & \swarrow p_i & \\ \mathbf{P}(V_i) & & \end{array}$$

where j_i is a closed immersion with $j_1^* \mathcal{O}_{\mathbf{P}(\mathcal{E}_1)}(1) = \mathcal{O}_Y(H_2)$ and $j_2^* \mathcal{O}_{\mathbf{P}(\mathcal{E}_2)}(1) = \mathcal{O}_Y(H_1)$. Moreover, Y is cut out on $\mathbf{P}(\mathcal{E}_i)$ by a section of $\mathcal{O}_{\mathbf{P}(\mathcal{E}_i)}(2) \otimes \mathcal{O}(2H_i)$, so that π_i is a quadric surface fibration.

Proof. Consider the case $i = 1$. The morphism $j_1 : Y \rightarrow \mathbf{P}(\mathcal{E}_1)$ is given by the π_1 -very ample line bundle $\mathcal{O}_Y(H_2)$. More precisely, using $\pi_* (\mathcal{O}_Y) = \mathcal{O} \oplus \mathcal{O}(-H_1 - H_2)$, we find

$$\begin{aligned} \pi_{1*}(\mathcal{O}_Y(H_2)) &= \mathrm{pr}_{1*}(\mathcal{O}(H_2) \oplus \mathcal{O}(-H_1)) \\ &= (V_2^* \otimes \mathcal{O}) \oplus \mathcal{O}(-H_1) \\ &= \mathcal{E}_1^*. \end{aligned}$$

Working locally on $\mathbf{P}(V_1)$, we see the canonical map $\pi_1^* \mathcal{E}_1^* = \pi_1^* \pi_{1*}(\mathcal{O}_Y(H_2)) \rightarrow \mathcal{O}_Y(H_2)$ is surjective and the corresponding morphism $j_1 : Y \rightarrow \mathbf{P}(\mathcal{E}_1)$ is an immersion. By construction $j_1^* \mathcal{O}_{\mathbf{P}(\mathcal{E}_1)}(1) = \mathcal{O}_Y(H_2)$. Moreover, if ζ denotes the class of $\mathcal{O}_{\mathbf{P}(\mathcal{E}_1)}(1)$ in $\mathrm{Pic}(\mathbf{P}(\mathcal{E}_1))$, then it is easy to compute

$$[Y] = 2\zeta + 2H_1 \in \mathrm{Pic}(\mathbf{P}(\mathcal{E}_1))$$

by using the intersection numbers $H_1^2 H_2^2 = 2$ and $H_1 H_2^3 = 0$ on Y . So Y is indeed a quadric surface fibration, cut out by a section of $\mathcal{O}_{\mathbf{P}(\mathcal{E}_1)}(2) \otimes \mathcal{O}(2H_1)$ on $\mathbf{P}(\mathcal{E}_1)$. \square

Let D_i denote the discriminant divisor of $\pi_i : Y \rightarrow \mathbf{P}(V_i)$. It follows from the lemma that D_i is defined by a section of $\det(\mathcal{E}_i^*)^2 \otimes \mathcal{O}(8H_i) = \mathcal{O}(6H_i)$, i.e. $D_i \subset \mathbf{P}(V_i)$ is a sextic curve. Let $f_i : X_i \rightarrow \mathbf{P}(V_i)$ be the double cover of $\mathbf{P}(V_i)$ ramified over D_i . If D_i is smooth (equivalently, if π_i has simple degeneration), then X_i is a smooth K3 surface. Moreover, X_i comes equipped with an Azumaya algebra \mathcal{A}_i , as follows.

In general, consider a generically smooth quadric surface fibration $\pi : Q \rightarrow S$ over a smooth k -variety S , with smooth discriminant divisor and simple degeneration. Let $\mathcal{F} \rightarrow S$ be the relative Fano variety of lines of π . It follows from [7, Proposition 3.3] that Stein factorization gives morphisms

$$\mathcal{F} \xrightarrow{g} X \xrightarrow{f} S,$$

where g is an étale locally trivial \mathbf{P}^1 -bundle over X and f is the double cover of S branched along the discriminant divisor D . The morphism g corresponds to an Azumaya algebra \mathcal{A} on X .

Applying this discussion to $\pi_i : Y \rightarrow \mathbf{P}(V_i)$, we see that if D_i is smooth, then X_i is equipped with an Azumaya algebra \mathcal{A}_i . Of course \mathcal{A}_i represents a Brauer class $\alpha_i \in \mathrm{Br}(X_i)$, so we can regard the pair (X_i, \mathcal{A}_i) as a twisted K3 surface.

3. DERIVED EQUIVALENCE OF THE TWISTED K3 SURFACES

In this section, we prove the twisted K3 surfaces (X_i, \mathcal{A}_i) of the previous section are derived equivalent. Our proof works over any field k of characteristic not equal to 2, and gives an explicit functor inducing the equivalence. The key tool is Kuznetsov's semiorthogonal decomposition of the derived category of a quadric fibration [9].

3.1. Conventions. All triangulated categories appearing below will be k -linear, and functors between them will be k -linear and exact.

For a variety X , we denote by $D^b(X)$ the bounded derived category of coherent sheaves on X , regarded as a triangulated category. More generally, for any sheaf of \mathcal{O}_X -algebras \mathcal{A} which is coherent as an \mathcal{O}_X -module, we denote by $D^b(X, \mathcal{A})$ the bounded derived category of coherent sheaves of right \mathcal{A} -modules on X . We note that if \mathcal{A} is an Azumaya algebra corresponding to a Brauer class $\alpha \in \mathrm{Br}(X)$, then the bounded derived category of α -twisted sheaves $D^b(X, \alpha)$ is equivalent to $D^b(X, \mathcal{A})$.

As a rule, all functors we consider are derived. More precisely, for a morphism of varieties $f : X \rightarrow Y$, we simply write $f_* : D^b(X) \rightarrow D^b(Y)$ for the derived pushforward (provided f is proper) and $f^* : D^b(Y) \rightarrow D^b(X)$ for the derived pullback (provided f has finite Tor-dimension). Similarly, for $\mathcal{F}, \mathcal{G} \in D^b(X)$, we write $\mathcal{F} \otimes \mathcal{G} \in D^b(X)$ for the derived tensor product.

3.2. Semiorthogonal decompositions. One way to understand the derived category of a variety (or more generally a triangulated category) is by “decomposing” it into simpler pieces. This is formalized by the notion of a semiorthogonal decomposition, which plays a central role in the rest of this section. We summarize the rudiments of this theory; see e.g. [3] and [4] for a more detailed exposition.

Definition 3.1. Let \mathcal{T} be a triangulated category. A *semiorthogonal decomposition*

$$\mathcal{T} = \langle \mathcal{A}_1, \dots, \mathcal{A}_n \rangle$$

is a sequence of full triangulated subcategories $\mathcal{A}_1, \dots, \mathcal{A}_n$ of \mathcal{T} — called the *components* of the decomposition — such that:

- (1) $\mathrm{Hom}(\mathcal{F}, \mathcal{G}) = 0$ for all $\mathcal{F} \in \mathcal{A}_i, \mathcal{G} \in \mathcal{A}_j$ if $i > j$.
- (2) For any $\mathcal{F} \in \mathcal{T}$, there is a sequence of morphisms

$$0 = \mathcal{F}_n \rightarrow \mathcal{F}_{n-1} \rightarrow \dots \rightarrow \mathcal{F}_1 \rightarrow \mathcal{F}_0 = \mathcal{F},$$

such that $\mathrm{Cone}(\mathcal{F}_i \rightarrow \mathcal{F}_{i-1}) \in \mathcal{A}_i$.

Semiorthogonal decompositions are closely related to the notion of an *admissible subcategory* of a triangulated category. Such a subcategory $\mathcal{A} \subset \mathcal{T}$ is by definition a full triangulated subcategory such that the inclusion $i : \mathcal{A} \hookrightarrow \mathcal{T}$ admits right and left adjoints $i^! : \mathcal{T} \rightarrow \mathcal{A}$ and $i^* : \mathcal{T} \rightarrow \mathcal{A}$. For X a smooth proper variety over k , the components of any semiorthogonal decomposition of $D^b(X)$ are in fact admissible subcategories.

The simplest examples of admissible subcategories come from exceptional objects. An object $\mathcal{F} \in \mathcal{T}$ of a triangulated category is called *exceptional* if

$$\mathrm{Hom}(\mathcal{F}, \mathcal{F}[p]) = \begin{cases} k & \text{if } p = 0, \\ 0 & \text{if } p \neq 0. \end{cases}$$

If X is a proper variety and $\mathcal{F} \in D^b(X)$ is exceptional, then the full triangulated subcategory $\langle \mathcal{F} \rangle \subset D^b(X)$ generated by \mathcal{F} is admissible and equivalent to the derived category of a point via $D^b(\mathrm{Spec}(k)) \rightarrow D^b(X) : V \mapsto V \otimes \mathcal{F}$. To simplify notation, we write \mathcal{F} in place of $\langle \mathcal{F} \rangle$ when $\langle \mathcal{F} \rangle$ appears as a component in a semiorthogonal decomposition, i.e. instead of $D^b(X) = \langle \dots, \langle \mathcal{F} \rangle, \dots \rangle$ we write $D^b(X) = \langle \dots, \mathcal{F}, \dots \rangle$.

Example 3.2. It is easy to see any line bundle on projective space \mathbf{P}^n is exceptional as an object of $D^b(\mathbf{P}^n)$. In fact, Beilinson [2] showed $D^b(\mathbf{P}^n)$ has a semiorthogonal decomposition into $n + 1$ line bundles, namely

$$D^b(\mathbf{P}^n) = \langle \mathcal{O}, \mathcal{O}(1), \dots, \mathcal{O}(n) \rangle.$$

Given one semiorthogonal decomposition of a triangulated category \mathcal{T} , others can be obtained via mutation functors. If $i : \mathcal{A} \hookrightarrow \mathcal{T}$ is the inclusion of an admissible subcategory, the *left* and *right mutation functors* $L_{\mathcal{A}} : \mathcal{T} \rightarrow \mathcal{T}$ and $R_{\mathcal{A}} : \mathcal{T} \rightarrow \mathcal{T}$ are defined by the formulas

$$L_{\mathcal{A}}(\mathcal{F}) = \mathrm{Cone}(ii^!\mathcal{F} \rightarrow \mathcal{F}) \quad \text{and} \quad R_{\mathcal{A}}(\mathcal{F}) = \mathrm{Cone}(\mathcal{F} \rightarrow ii^*\mathcal{F})[-1],$$

where $ii^!\mathcal{F} \rightarrow \mathcal{F}$ and $\mathcal{F} \rightarrow ii^*\mathcal{F}$ are the counit and unit morphisms of the adjunctions. These functors satisfy the following basic properties.

Lemma 3.3. *The mutation functors $L_{\mathcal{A}}$ and $R_{\mathcal{A}}$ annihilate \mathcal{A} . Moreover, they restrict to mutually inverse equivalences*

$$L_{\mathcal{A}}|_{\perp_{\mathcal{A}}} : \perp_{\mathcal{A}} \xrightarrow{\sim} \mathcal{A}^{\perp} \quad \text{and} \quad R_{\mathcal{A}}|_{\mathcal{A}^{\perp}} : \mathcal{A}^{\perp} \xrightarrow{\sim} \perp_{\mathcal{A}},$$

where \mathcal{A}^\perp and ${}^\perp\mathcal{A}$ are the right and left orthogonal categories to \mathcal{A} , i.e. the full subcategories of \mathcal{T} defined by

$$\begin{aligned}\mathcal{A}^\perp &= \{\mathcal{F} \in \mathcal{T} \mid \text{Hom}(\mathcal{G}, \mathcal{F}) = 0 \text{ for all } \mathcal{G} \in \mathcal{A}\}, \\ {}^\perp\mathcal{A} &= \{\mathcal{F} \in \mathcal{T} \mid \text{Hom}(\mathcal{F}, \mathcal{G}) = 0 \text{ for all } \mathcal{G} \in \mathcal{A}\}.\end{aligned}$$

The following lemma describes the action of mutation functors on a semiorthogonal decomposition.

Lemma 3.4. *Let $\mathcal{T} = \langle \mathcal{A}_1, \dots, \mathcal{A}_n \rangle$ be a semiorthogonal decomposition with admissible components. Then for $1 \leq i \leq n-1$ there is a semiorthogonal decomposition*

$$\mathcal{T} = \langle \mathcal{A}_1, \dots, \mathcal{A}_{i-1}, L_{\mathcal{A}_i}(\mathcal{A}_{i+1}), \mathcal{A}_i, \mathcal{A}_{i+2}, \dots, \mathcal{A}_n \rangle,$$

and for $2 \leq i \leq n$ there is a semiorthogonal decomposition

$$\mathcal{T} = \langle \mathcal{A}_1, \dots, \mathcal{A}_{i-2}, \mathcal{A}_i, R_{\mathcal{A}_i}(\mathcal{A}_{i-1}), \mathcal{A}_{i+1}, \dots, \mathcal{A}_n \rangle.$$

We will also need the following lemma, which allows us to compute the effect of a mutation functor in a special case. It follows easily from Serre duality.

Lemma 3.5. *Let X be a smooth projective variety over k , and let $D^b(X) = \langle \mathcal{A}_1, \dots, \mathcal{A}_n \rangle$ be a semiorthogonal decomposition. Then $L_{\langle \mathcal{A}_1, \dots, \mathcal{A}_{n-1} \rangle}(\mathcal{A}_n) = \mathcal{A}_n \otimes \omega_X$, where $\mathcal{A}_n \otimes \omega_X$ denotes the image of \mathcal{A}_n under the autoequivalence $\mathcal{F} \mapsto \mathcal{F} \otimes \omega_X$ of $D^b(X)$.*

3.3. Derived categories of quadric fibrations. Let $\pi : Q \rightarrow S$ be a quadric fibration associated to a rank n vector bundle \mathcal{E} and a section of $\text{Sym}^2(\mathcal{E}^*) \otimes \mathcal{L}$, as in Section 2.1. Then there is an associated *even Clifford algebra* $\mathcal{C}\ell_0$, which is a sheaf of algebras on S given as a certain quotient of the tensor algebra $T^\bullet(\mathcal{E} \otimes \mathcal{E} \otimes \mathcal{L}^*)$. For the precise definition, see [1, Section 1.5] (cf. [9, Section 3.3]). We note that $\mathcal{C}\ell_0$ admits an \mathcal{O}_S -module filtration of length $\lfloor \frac{n}{2} \rfloor$ with associated graded pieces $\wedge^{2i} \mathcal{E} \otimes (\mathcal{L}^*)^i$.

In case the fibration $\pi : Q \rightarrow S$ is flat and S is smooth over k , Kuznetsov [9] established a semiorthogonal decomposition of $D^b(Q)$ into a copy of $D^b(S, \mathcal{C}\ell_0)$ and a number of copies of $D^b(S)$. In fact, Kuznetsov stated his result under the assumption that k is algebraically closed of characteristic 0, but as explained in [1, Theorem 2.11], the proof works without this hypothesis.

Theorem 3.6 ([9, Theorem 4.2]). *Let $\pi : Q \rightarrow S$ be a flat quadric fibration of relative dimension $n-2$ over a smooth k -variety S . Let $\mathcal{O}_Q(1)$ denote the restriction of $\mathcal{O}_{\mathbf{P}(\mathcal{E})}(1)$ to Q . Then the functor $\pi^* : D^b(S) \rightarrow D^b(Q)$ is fully faithful, and there is a fully faithful functor $\Phi : D^b(S, \mathcal{C}\ell_0) \rightarrow D^b(Q)$ such that there is a semiorthogonal decomposition*

$$D^b(Q) = \langle \Phi(D^b(S, \mathcal{C}\ell_0)), \pi^* D^b(S) \otimes \mathcal{O}_Q(1), \dots, \pi^* D^b(S) \otimes \mathcal{O}_Q(n-2) \rangle.$$

Remark 3.7. The functor $\Phi : D^b(S, \mathcal{C}\ell_0) \rightarrow D^b(Q)$ is given by an explicit Fourier–Mukai kernel, see [9, Section 4].

Now assume $\pi : Q \rightarrow S$ is a generically smooth quadric surface fibration over a smooth k -variety S , with smooth discriminant divisor and simple degeneration. As in the discussion at the end of Section 2.2, the double cover $f : X \rightarrow S$ ramified over D

is equipped with an Azumaya algebra \mathcal{A} . In terms of this data, we have the following alternative description of $D^b(S, \mathcal{E}_0)$, see [1, Proposition B.3] or [10, Lemma 4.2].

Lemma 3.8. *In the above situation, there is an isomorphism $f_*\mathcal{A} \cong \mathcal{E}_0$. In particular, pushforward by f induces an equivalence $f_* : D^b(X, \mathcal{A}) \xrightarrow{\sim} D^b(S, \mathcal{E}_0)$.*

3.4. Derived equivalence. Let $\pi : Y \rightarrow \mathbf{P}(V_1) \times \mathbf{P}(V_2)$ be as in Section 2.2. Assume the discriminant divisors D_i of the quadric fibrations $\pi_i : Y \rightarrow \mathbf{P}(V_i)$ are smooth, so that we get associated twisted K3 surfaces (X_i, \mathcal{A}_i) . Let $\mathcal{E}_{0,i}$ denote the even Clifford algebra of the quadric fibration $\pi_i : Y \rightarrow \mathbf{P}(V_i)$. Then Lemma 3.8 gives an equivalence $f_{i*} : D^b(X_i, \mathcal{A}_i) \xrightarrow{\sim} D^b(\mathbf{P}(V_i), \mathcal{E}_{0,i})$. Finally, let $\Phi_i : D^b(\mathbf{P}(V_i), \mathcal{E}_{0,i}) \rightarrow D^b(Y)$ be the fully faithful functor from Theorem 3.6. In this setup, we prove the following result.

Theorem 3.9. *Assume D_1 and D_2 are smooth. Then there is an equivalence*

$$D^b(X_1, \mathcal{A}_1) \simeq D^b(X_2, \mathcal{A}_2)$$

given by the composition

$$f_{2*}^{-1} \circ \Phi_2^* \circ R_{\mathcal{O}_Y(H_2)} \circ L_{\mathcal{O}_Y(H_1)} \circ \Phi_1 \circ f_{1*} : D^b(X_1, \mathcal{A}_1) \rightarrow D^b(X_2, \mathcal{A}_2),$$

where

- $L_{\mathcal{O}_Y(H_1)}$ is the left mutation functor through $\langle \mathcal{O}_Y(H_1) \rangle \subset D^b(Y)$,
- $R_{\mathcal{O}_Y(H_2)}$ is the right mutation functor through $\langle \mathcal{O}_Y(H_2) \rangle \subset D^b(Y)$,
- Φ_2^* is the left adjoint of Φ_2 ,
- f_{2*}^{-1} is the inverse of the equivalence $f_{2*} : D^b(X_2, \mathcal{A}_2) \xrightarrow{\sim} D^b(\mathbf{P}(V_2), \mathcal{E}_{0,2})$.

The theorem is an immediate consequence of the following proposition. We note that the proposition holds without assuming smoothness of the discriminant divisors D_i .

Proposition 3.10. *There is an equivalence*

$$D^b(\mathbf{P}(V_1), \mathcal{E}_{0,1}) \simeq D^b(\mathbf{P}(V_2), \mathcal{E}_{0,2})$$

given by the composition

$$\Phi_2^* \circ R_{\mathcal{O}_Y(H_2)} \circ L_{\mathcal{O}_Y(H_1)} \circ \Phi_1 : D^b(\mathbf{P}(V_1), \mathcal{E}_{0,1}) \rightarrow D^b(\mathbf{P}(V_2), \mathcal{E}_{0,2}).$$

Proof. Set $\mathcal{C}_i = \Phi_i(D^b(\mathbf{P}(V_i), \mathcal{E}_{0,i})) \subset D^b(Y)$. Theorem 3.6 gives semiorthogonal decompositions

$$\begin{aligned} D^b(Y) &= \langle \mathcal{C}_1, \pi_1^* D^b(\mathbf{P}(V_1)) \otimes \mathcal{O}(H_2), \pi_1^* D^b(\mathbf{P}(V_1)) \otimes \mathcal{O}(2H_2) \rangle, \\ D^b(Y) &= \langle \mathcal{C}_2, \pi_2^* D^b(\mathbf{P}(V_2)) \otimes \mathcal{O}(H_1), \pi_2^* D^b(\mathbf{P}(V_2)) \otimes \mathcal{O}(2H_1) \rangle. \end{aligned}$$

Recall Beilinson's decomposition $D^b(\mathbf{P}(V_i)) = \langle \mathcal{O}, \mathcal{O}(H_i), \mathcal{O}(2H_i) \rangle$ (see Example 3.2). In each of the above decompositions of $D^b(Y)$, we replace the first copy of $D^b(\mathbf{P}(V_i))$ by Beilinson's decomposition and the second copy by the same decomposition twisted

by $\mathcal{O}(H_i)$:

$$\begin{aligned} D^b(Y) = \langle \mathcal{C}_1, \mathcal{O}(H_2), \mathcal{O}(H_1 + H_2), \mathcal{O}(2H_1 + H_2), \\ \mathcal{O}(H_1 + 2H_2), \mathcal{O}(2H_1 + 2H_2), \mathcal{O}(3H_1 + 2H_2) \rangle, \end{aligned} \quad (3.1)$$

$$\begin{aligned} D^b(Y) = \langle \mathcal{C}_2, \mathcal{O}(H_1), \mathcal{O}(H_1 + H_2), \mathcal{O}(H_1 + 2H_2), \\ \mathcal{O}(2H_1 + H_2), \mathcal{O}(2H_1 + 2H_2), \mathcal{O}(2H_1 + 3H_2) \rangle. \end{aligned} \quad (3.2)$$

We perform a sequence of mutations that identifies the categories generated by the exceptional objects in (3.1) and (3.2).

First consider (3.1). Mutate $\mathcal{O}(3H_1 + 2H_2)$ to the far left of the decomposition. Note that Y is smooth with canonical class $K_Y = -2H_1 - 2H_2$, so by Lemma 3.5 the result of the mutation is

$$\begin{aligned} D^b(Y) = \langle \mathcal{O}(H_1), \mathcal{C}_1, \mathcal{O}(H_2), \mathcal{O}(H_1 + H_2), \mathcal{O}(2H_1 + H_2), \\ \mathcal{O}(H_1 + 2H_2), \mathcal{O}(2H_1 + 2H_2) \rangle. \end{aligned}$$

Left mutating \mathcal{C}_1 through $\mathcal{O}(H_1)$ then gives a decomposition

$$\begin{aligned} D^b(Y) = \langle L_{\mathcal{O}(H_1)}\mathcal{C}_1, \mathcal{O}(H_1), \mathcal{O}(H_2), \mathcal{O}(H_1 + H_2), \mathcal{O}(2H_1 + H_2), \\ \mathcal{O}(H_1 + 2H_2), \mathcal{O}(2H_1 + 2H_2) \rangle. \end{aligned} \quad (3.3)$$

By the same argument, we obtain from (3.2) a similar decomposition

$$\begin{aligned} D^b(Y) = \langle L_{\mathcal{O}(H_2)}\mathcal{C}_2, \mathcal{O}(H_2), \mathcal{O}(H_1), \mathcal{O}(H_1 + H_2), \mathcal{O}(H_1 + 2H_2), \\ \mathcal{O}(2H_1 + H_2), \mathcal{O}(2H_1 + 2H_2) \rangle. \end{aligned} \quad (3.4)$$

Up to permutation, the exceptional objects in the decompositions (3.3) and (3.4) agree, hence they generate the same subcategory of $D^b(Y)$. It follows that $L_{\mathcal{O}(H_1)}\mathcal{C}_1$ and $L_{\mathcal{O}(H_2)}\mathcal{C}_2$ coincide, as both are the right orthogonal to the same subcategory. Now the proposition follows since $R_{\mathcal{O}(H_2)} \circ L_{\mathcal{O}(H_2)} \cong \text{id}$ on ${}^\perp\langle \mathcal{O}(H_2) \rangle$ by Lemma 3.3. \square

Remark 3.11. The equivalence $D^b(X_1, \alpha_1) \simeq D^b(X_2, \alpha_2)$ of Theorem 3.9 implies other relations between X_1 and X_2 . For instance, over $k = \mathbf{C}$ it implies the Picard numbers of X_1 and X_2 agree. Indeed, it suffices to note that the equivalence induces an isomorphism of twisted transcendental lattices $T(X_1, \alpha_1) \cong T(X_2, \alpha_2)$, whose ranks are the same as the usual transcendental lattices (see [8]).

4. EQUATIONS FOR THE TWISTED K3 SURFACES AND LOCAL INVARIANTS

Let k be a number field. Then for any place v of k , class field theory provides an embedding $\text{inv}_v : \text{Br}(k_v) \rightarrow \mathbf{Q}/\mathbf{Z}$ (which is an isomorphism for nonarchimedean v). Now let X be a smooth, projective, geometrically integral variety over k . Any subset $S \subset \text{Br}(X)$ cuts out a subset $X(\mathbf{A}_k)^S \subset X(\mathbf{A}_k)$ of the adelic points of X , given by

$$X(\mathbf{A}_k)^S = \left\{ (x_v) \in X(\mathbf{A}_k) \mid \sum_v \text{inv}_v \alpha(x_v) = 0 \text{ for all } \alpha \in S \right\}.$$

For fixed $(x_v) \in X(\mathbf{A}_k)$ and $\alpha \in \text{Br}(X)$, the evaluation $\alpha(x_v) = 0$ for all but finitely many v , so the above sum is well-defined. Moreover, class field theory gives inclusions

$$X(k) \subset X(\mathbf{A}_k)^S \subset X(\mathbf{A}_k).$$

Hence, if $X(\mathbf{A}_k)^S$ is empty for some S , then X has no k -points. We note that if $X(\mathbf{A}_k)^S$ is empty but $X(\mathbf{A}_k)$ is not, then S is said to give a *Brauer–Manin obstruction* to the Hasse principle. See [12, 5.2] for more details.

In this section, we describe conditions on the $(2, 2)$ divisor $Z \subset \mathbf{P}(V_1) \times \mathbf{P}(V_2)$ from Section 2.2, which allow us to control the local invariants $\text{inv}_v \alpha_1(x_v)$ for any v -adic point $x_v \in X_1(k_v)$. In the end, we will see that if $k = \mathbf{Q}$ and enough conditions are met, then

$$\text{inv}_v \alpha_1(x_v) = \begin{cases} 0 & \text{if } v \text{ is finite,} \\ \frac{1}{2} & \text{if } v \text{ is real,} \end{cases}$$

for all $x_v \in X_1(k_v)$. Hence $X_1(\mathbf{A}_k)^{\alpha_1}$ is empty and X_1 has no k -points. Our discussion follows [6] very closely, and differs only in the treatment of the 2-adic place (see Lemma 4.5).

4.1. Equations for the twisted K3 surfaces. Let the notation be as in Section 2.2 (in particular k may be any field of characteristic not equal to 2).

Choose coordinates x_0, x_1, x_2 on $\mathbf{P}(V_1)$ and y_0, y_1, y_2 on $\mathbf{P}(V_2)$. The equation defining Z can be written as

$$\begin{aligned} &A(x_0, x_1, x_2)y_0^2 + B(x_0, x_1, x_2)y_0y_1 + C(x_0, x_1, x_2)y_0y_2 + \\ &D(x_0, x_1, x_2)y_1^2 + E(x_0, x_1, x_2)y_1y_2 + F(x_0, x_1, x_2)y_2^2, \end{aligned} \tag{4.1}$$

where A, \dots, F are degree 2 homogeneous polynomials in the x_i , or as

$$\begin{aligned} &A'(y_0, y_1, y_2)x_0^2 + B'(y_0, y_1, y_2)x_0x_1 + C'(y_0, y_1, y_2)x_0x_2 + \\ &D'(y_0, y_1, y_2)x_1^2 + E'(y_0, y_1, y_2)x_1x_2 + F'(y_0, y_1, y_2)x_2^2. \end{aligned} \tag{4.2}$$

where A', \dots, F' are degree 2 homogeneous polynomials in the y_i . The first or second expression is useful depending on whether we regard Y as a quadric fibration over $\mathbf{P}(V_1)$ or $\mathbf{P}(V_2)$. The following lemma summarizes the computations of [6, Section 3].

Lemma 4.1. (1) *Let*

$$M = \begin{pmatrix} 2A & B & C \\ B & 2D & E \\ C & E & 2F \end{pmatrix}$$

Then the discriminant curve $D_1 \subset \mathbf{P}(V_1)$ is defined by $\det(M) = 0$, and X_1 is defined in the weighted projective space $\mathbf{P}(1, 1, 1, 3)$ with coordinates x_0, x_1, x_2, w by

$$w^2 = -\frac{1}{2} \det(M).$$

The analogous statements hold for $D_2 \subset \mathbf{P}(V_2)$ and X_2 with M replaced by

$$M' = \begin{pmatrix} 2A' & B' & C' \\ B' & 2D' & E' \\ C' & E' & 2F' \end{pmatrix}.$$

(2) Define

$$M_A = 4DF - E^2, \quad M_D = 4AF - C^2, \quad M_F = 4AD - B^2.$$

Assume $D_1 \subset \mathbf{P}(V_1)$ is smooth, so that we have a twisted K3 surface (X_1, α_1) . Then the image of α_1 under the injection $\mathrm{Br}(X_1) \rightarrow \mathrm{Br}(k(X_1))$ (where $k(X_1)$ is the function field of X_1) can be represented by any of the following Hilbert symbols:

$$(-M_F, A), \quad (-M_D, A), \quad (-M_F, D), \quad (-M_A, D), \quad (-M_D, F), \quad (-M_A, F).$$

Defining M'_A, M'_D, M'_F , similarly, the analogous statement holds for $\alpha_2 \in \mathrm{Br}(X_2)$.

From now on, we assume $D_1 \subset \mathbf{P}(V_1)$ is smooth, so that (X_1, α_1) is defined.

4.2. Conditions controlling the local invariants. The following result holds by Proposition 4.1 and Lemma 4.2 of [6]. It allows us to control local invariants at finite places of bad reduction, assuming the place is not 2-adic and the singularities are mild.

Proposition 4.2. *Let F be a finite extension of \mathbf{Q}_p for $p \neq 2$, and denote by \mathcal{O}_F the ring of integers of F . Let X be a K3 surface over F . Let $\mathcal{X} \rightarrow \mathrm{Spec}(\mathcal{O}_F)$ be a flat, proper morphism from a regular scheme \mathcal{X} , with generic fiber $\mathcal{X}_\eta \cong X$. Assume the singular locus of the geometric special fiber $\mathcal{X}_{\bar{s}}$ consists of less than 8 points, each of which is an ordinary double point. If $X(F) \neq \emptyset$, then for any 2-power torsion Brauer class $\alpha \in \mathrm{Br}(X)[2^\infty]$, the map $X(F) \rightarrow \mathrm{Br}(F)$ given by evaluation of α is constant. In particular, $\alpha(x) = 0$ for all $x \in X(F)$ if this holds for a single x .*

The next result is [6, Lemma 4.4]. It guarantees that the local invariants of $\alpha_1 \in \mathrm{Br}(X_1)$ vanish at finite places of good reduction, away from the prime 2.

Lemma 4.3. *Let k be a number field. Let v be a finite place of good reduction for X_1 which is not 2-adic. Then $\mathrm{inv}_v \alpha_1(x) = 0$ for all $x \in X_1(k_v)$.*

We are left to control the real and 2-adic invariants of $\alpha_1 \in \mathrm{Br}(X_1)$. The following result, which is [6, Corollary 4.6], gives conditions which guarantee α_1 is nontrivial at any real point of X_1 .

Lemma 4.4. *Let $k = \mathbf{Q}$. Assume the polynomials A, \dots, F from (4.1), when regarded as quadratic forms, satisfy:*

- (1) A, D , and F are negative definite,
- (2) B, C , and E are positive definite.

If ∞ denotes the real place, then $\mathrm{inv}_\infty \alpha_1(x) = 1/2$ for all $x \in X_1(\mathbf{R})$.

The following lemma improves [6, Lemma 4.7], giving conditions such that α_1 is trivial at every 2-adic point of X_1 .

Lemma 4.5. *Let $k = \mathbf{Q}$. Write the polynomials $A, \dots, F \in \mathbf{Q}[x_0, x_1, x_2]$ from (4.1) as*

$$\begin{aligned} A &= A_1x_0^2 + A_2x_0x_1 + A_3x_0x_2 + A_4x_1^2 + A_5x_1x_2 + A_6x_2^2, \\ B &= B_1x_0^2 + B_2x_0x_1 + B_3x_0x_2 + B_4x_1^2 + B_5x_1x_2 + B_6x_2^2, \\ C &= C_1x_0^2 + C_2x_0x_1 + C_3x_0x_2 + C_4x_1^2 + C_5x_1x_2 + C_6x_2^2, \\ D &= D_1x_0^2 + D_2x_0x_1 + D_3x_0x_2 + D_4x_1^2 + D_5x_1x_2 + D_6x_2^2, \\ E &= E_1x_0^2 + E_2x_0x_1 + E_3x_0x_2 + E_4x_1^2 + E_5x_1x_2 + E_6x_2^2, \\ F &= F_1x_0^2 + F_2x_0x_1 + F_3x_0x_2 + F_4x_1^2 + F_5x_1x_2 + F_6x_2^2. \end{aligned}$$

Suppose the coefficients of A, \dots, F satisfy:

- (1) *The 2-adic valuation of $A_1, B_1, C_6, D_4, E_4,$ and F_6 is 0.*
- (2) *The 2-adic valuation of all other coefficients is > 0 .*

Then $\text{inv}_2 \alpha_1(x) = 0$ for all $x \in X_1(\mathbf{Q}_2)$.

Proof. Let $x = [x_0, x_1, x_2, w]$ be a point of $X_1(\mathbf{Q}_2) \subset \mathbf{P}(1, 1, 1, 3)(\mathbf{Q}_2)$. By scaling the coordinates, we may assume $x_0, x_1, x_2 \in \mathbf{Z}_2$ and at least one of the x_i is a unit. By Lemma 4.1, the Hilbert symbols

$$(B^2 - 4AD, A), \quad (E^2 - 4DF, D), \quad (C^2 - 4AF, F)$$

all represent the image of α_1 in $\text{Br}(k(X))$. According to whether $x_0, x_1,$ or x_2 is a 2-adic unit, the first, second, or third of these representatives can be used to see $\text{inv}_2 \alpha_1(x) = 0$.

For instance, suppose x_0 is a 2-adic unit. Then by our assumptions on coefficients,

$$A(x) \quad \text{and} \quad B(x)^2 - 4A(x)D(x)$$

are also 2-adic units. In particular, they are nonzero, so

$$(B(x)^2 - 4A(x)D(x), A(x))_2$$

represents $\alpha_1(x) \in \text{Br}(\mathbf{Q}_2)$. Recall (see for example [11, p. 20, Theorem 1]) that if $s, t \in \mathbf{Z}_2^\times$, then

$$(s, t)_2 = (-1)^{\frac{s-1}{2} \frac{t-1}{2}}.$$

But by our assumptions

$$B(x)^2 - 4A(x)D(x) \equiv 1 \pmod{4},$$

so the formula gives

$$(B(x)^2 - 4A(x)D(x), A(x))_2 = 1.$$

Thus $\alpha_1(x) = 0 \in \text{Br}(\mathbf{Q}_2)$.

The same argument works when x_1 or x_2 is a 2-adic unit, using the other representatives for α_1 from above. \square

5. PROOF OF THEOREM 1.2

Consider the following quadrics in $\mathbf{Z}[x_0, x_1, x_2]$:

$$\begin{aligned} A &= -5x_0^2 + 4x_0x_2 - 4x_1^2 + 2x_1x_2 - 4x_2^2, \\ B &= 5x_0^2 + 2x_0x_1 - 2x_0x_2 + 2x_1^2 + 2x_1x_2 + 4x_2^2, \\ C &= 4x_0^2 + 2x_0x_1 - 4x_0x_2 + 2x_1^2 - 2x_1x_2 + 5x_2^2, \\ D &= -4x_0^2 - 2x_0x_1 - x_1^2 - 2x_1x_2 - 4x_2^2, \\ E &= 4x_0^2 + 3x_1^2 + 4x_2^2, \\ F &= -4x_0^2 + 4x_0x_1 + 2x_0x_2 - 2x_1^2 - 4x_1x_2 - 5x_2^2. \end{aligned}$$

Inserting these polynomials in (4.1) gives the equation of a (2,2) divisor

$$Z \subset \mathbf{P}(V_1) \times \mathbf{P}(V_2),$$

which we regard as a variety over \mathbf{Q} . As in Section 2.2, Z gives rise to a branched double cover $\pi : Y \rightarrow \mathbf{P}(V_1) \times \mathbf{P}(V_2)$, which is a quadric fibration via projection to each factor. Lemma 4.1 gives explicit equations for the discriminant curves $D_i \subset \mathbf{P}(V_i)$, and the Jacobian criterion can be used to check the D_i are smooth. Hence, by Section 2.2, we get associated twisted K3 surfaces (X_i, α_i) , which we will use to prove Theorem 1.2.

Remark 5.1. The quadrics A, \dots, F above were found using the algorithm described in [6, Section 6], modified in two ways. First, we omitted the steps related to checking the geometric Picard number of X_1 is 1, since it was not our goal to produce an example with this property. Second, instead of using [6, Lemma 4.7] to constrain the quadrics, we used our Lemma 4.5, which results in much smaller coefficients. Indeed, the equations for X_1 and X_2 are:

$$\begin{aligned} w^2 &= -4x_0^6 - 308x_0^5x_1 - 190x_0^4x_1^2 - 278x_0^3x_1^3 - 203x_0^2x_1^4 - 40x_0x_1^5 - 28x_1^6 \\ &\quad + 18x_0^5x_2 + 460x_0^4x_1x_2 + 276x_0^3x_1^2x_2 + 474x_0^2x_1^3x_2 + 40x_0x_1^4x_2 \\ &\quad + 98x_1^5x_2 - 25x_0^4x_2^2 - 820x_0^3x_1x_2^2 - 247x_0^2x_1^2x_2^2 - 374x_0x_1^3x_2^2 \\ &\quad - 2x_1^4x_2^2 + 20x_0^3x_2^3 + 652x_0^2x_1x_2^3 + 14x_0x_1^2x_2^3 + 270x_1^3x_2^3 \\ &\quad - 20x_0^2x_2^4 - 562x_0x_1x_2^4 - 105x_1^2x_2^4 - 8x_0x_2^5 + 166x_1x_2^5 - 4x_2^6, \\ w^2 &= 236y_0^6 - 740y_0^5y_1 + 1268y_0^4y_1^2 - 1092y_0^3y_1^3 + 624y_0^2y_1^4 - 164y_0y_1^5 \\ &\quad + 32y_1^6 - 616y_0^5y_2 + 416y_0^4y_1y_2 - 96y_0^3y_1^2y_2 - 976y_0^2y_1^3y_2 + 548y_0y_1^4y_2 \\ &\quad - 288y_1^5y_2 + 1236y_0^4y_2^2 - 456y_0^3y_1y_2^2 + 1484y_0^2y_1^2y_2^2 - 356y_0y_1^3y_2^2 \\ &\quad + 676y_1^4y_2^2 - 1332y_0^3y_2^3 - 804y_0^2y_1y_2^3 - 372y_0y_1^2y_2^3 - 1024y_1^3y_2^3 + 1036y_0^2y_2^4 \\ &\quad + 768y_0y_1y_2^4 + 812y_1^2y_2^4 - 472y_0y_2^5 - 388y_1y_2^5 + 40y_2^6. \end{aligned}$$

In contrast, most of the coefficients appearing in the corresponding equations in [6] have 5 or 6 digits. Smaller coefficients are crucial in making a computer search for points of X_2 feasible.

The following proposition is reduced to a series of computations by the results in Section 4.2. We postpone its proof to the end of the section.

Proposition 5.2. (1) $X_1(\mathbf{Q}_v) \neq \emptyset$ for all places v , or equivalently $X_1(\mathbf{A}_{\mathbf{Q}}) \neq \emptyset$.
 (2) The local invariants of the class $\alpha_1 \in \text{Br}(X_1)$ satisfy

$$\text{inv}_v \alpha_1(x_v) = \begin{cases} 0 & \text{if } v \text{ is finite,} \\ \frac{1}{2} & \text{if } v \text{ is real,} \end{cases}$$

for all $x_v \in X_1(\mathbf{Q}_v)$. In particular, α_1 obstructs the existence of \mathbf{Q} -points on X_1 , and hence gives a Brauer–Manin obstruction to the Hasse principle.

Using the proposition, we construct the examples which prove Theorem 1.2. The necessary computations that appear below were carried out using Magma¹.

5.1. Example over \mathbf{Q} . Using the equation for X_2 given by Lemma 4.1, it can be checked that $x = [1, 1, 1, 0] \in \mathbf{P}(1, 1, 1, 3)$ is a \mathbf{Q} -point of X_2 . Let $\beta = \alpha_2(x) \in \text{Br}(\mathbf{Q})$, let β_i be the constant class given by the image of β under $\text{Br}(\mathbf{Q}) \rightarrow \text{Br}(X_i)$, and set $\alpha'_i = \beta_i^{-1}\alpha_i$.

Then there is a \mathbf{Q} -linear equivalence $\text{D}^b(X_1, \alpha'_1) \simeq \text{D}^b(X_2, \alpha'_2)$ induced by the equivalence $\text{D}^b(X_1, \alpha_1) \simeq \text{D}^b(X_2, \alpha_2)$ of Theorem 3.9. By Proposition 5.2, X_1 has no \mathbf{Q} -point, so a fortiori the pair (X_1, α'_1) has no \mathbf{Q} -point. On the other hand, by construction x is a \mathbf{Q} -point of (X_2, α'_2) .

5.2. Example over \mathbf{Q}_2 . Replace the pairs (X_i, α_i) defined above over \mathbf{Q} by their base changes to \mathbf{Q}_2 . It can be checked that $x = [-3, -1, 1, \sqrt{357008}] \in \mathbf{P}(1, 1, 1, 3)$ is a \mathbf{Q}_2 -point of X_2 (note that Hensel’s lemma can be used to see 357008 is a 2-adic square). One then checks that $\beta = \alpha_2(x) = (B(x)^2 - 4A(x)D(x), A(x))_2$ is nontrivial. Let β_i be the constant class given by the image of β under $\text{Br}(\mathbf{Q}) \rightarrow \text{Br}(X_i)$, and set $\alpha'_i = \beta_i^{-1}\alpha_i$.

Then there is a \mathbf{Q}_2 -linear equivalence $\text{D}^b(X_1, \alpha'_1) \simeq \text{D}^b(X_2, \alpha'_2)$ induced by the equivalence of Theorem 3.9. By Proposition 5.2, $\alpha_1(y)$ is trivial for any $y \in X_1(\mathbf{Q}_2)$, and hence $\alpha'_1(y) = \alpha_2^{-1}(x)\alpha_1(y)$ is nontrivial (since $\alpha_2(x)$ is). Thus (X_1, α'_1) has no \mathbf{Q}_2 -points. On the other hand, by design x is a point of (X_2, α'_2) .

5.3. Example over \mathbf{R} . Replace the pairs (X_i, α_i) by their base changes to \mathbf{R} . Then Theorem 3.9 still gives an \mathbf{R} -linear equivalence $\text{D}^b(X_1, \alpha_1) \simeq \text{D}^b(X_2, \alpha_2)$. Moreover, Proposition 5.2 shows $\alpha_1(x)$ is nontrivial for any $x \in X_1(\mathbf{R})$, so (X_1, α_1) has no \mathbf{R} -points. On the other hand, using Lemma 4.1, it can be checked that the point

$$x = [4, 3, 3, \sqrt{5204}] \in \mathbf{P}(1, 1, 1, 3)$$

lies on X_2 and that $\alpha_2(x) = (B(x)^2 - 4A(x)D(x), A(x))_{\infty}$ is trivial. Hence x is an \mathbf{R} -point of (X_2, α_2) .

5.4. Proof of Proposition 5.2.

¹Code available at <http://www.math.brown.edu/~kenascher/magma/magma.html>.

5.4.1. *Local points.* We first check that $X_1(\mathbf{Q}_v) \neq \emptyset$ for all v . This is obvious when $v = \infty$. Let $v = p$ be a finite prime of good reduction with $p > 22$. Then if $(X_1)_p$ is a smooth reduction of X_1 at p , there is an \mathbf{F}_p -point of $(X_1)_p$ by the Weil conjectures. This lifts to a \mathbf{Q}_p -point of X_1 by Hensel's lemma.

It therefore suffices to check that $X_1(\mathbf{Q}_p) \neq \emptyset$ for primes p of bad reduction for X_1 and for all primes $p < 22$. A Gröbner basis calculation as in [6, Section 5.1] can be used to show the primes of bad reduction for X_1 are:

$$2, 5, 7, 307, 4591, 27077, 371857, 6902849, 104388233, \\ 541264119547919951, 6097863609641310921149279, \\ 2616678388926286398002864469014842817095009312844790479$$

In the table below, we list for each prime p of bad reduction and each $p < 22$ the (x_0, x_1, x_2) coordinates of a \mathbf{Q}_p -point of X_1 . (By Lemma 4.1, (x_0, x_1, x_2) gives a \mathbf{Q}_p -point if $-\frac{1}{2} \det(M)(x_0, x_1, x_2)$ is a square in \mathbf{Q}_p , which can be checked using Hensel's lemma).

p	(x_0, x_1, x_2)
2	(-1,0,-1)
3	(-1,-1,1)
5	(-1,-1,0)
7	(-1,-1,1)
11	(-1,-1,0)
13	(-1,-1,1)
17	(-1,-1,-1)
19	(-1,-1,-1)
307	(-1,-1,-1)
4591	(-1,-1,0)
27077	(-1,-1,-1)
371857	(-1,-1,-1)
6902849	(-1,0,0)
104388233	(-1,-1,-1)
541264119547919951	(-1,-1,1)
6097863609641310921149279	(-1,1,-1)
2616678388926286398002864469014842817095009312844790479	(-1,-1,0)

5.4.2. *Local invariants.* One computes that for each prime $p \neq 2$ of bad reduction, X_{1, \mathbf{Q}_p} satisfies the assumptions of Proposition 4.2. Moreover, using the representatives for α_1 given in Lemma 4.1, it can be computed that α_1 is trivial when evaluated at the \mathbf{Q}_p -points specified in the table above. We conclude by Proposition 4.2 that $\text{inv}_v \alpha_1(x_v) = 0$ at the non-2-adic finite places v of bad reduction. On the other hand, at the non-2-adic finite places of good reduction, we also have $\text{inv}_v \alpha_1(x_v) = 0$ by Lemma 4.3.

Finally, it is straightforward to check the quadrics A, \dots, F satisfy the hypotheses of Lemmas 4.4 and 4.5. The conclusions of these lemmas give Proposition 5.2(2) at the real and 2-adic places. \square

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