

Martin Hyland : Linear Logic & GOI

aim: Model dynamics of computation.

static (denotational) vs dynamic (rewriting)

Cut Rule: main protagonist.

Final view vs. Process view of Cut.

Cut-Elimination as rewriting ~~of~~ categorical;  
"op" on terms.

Model:  $\ast$ -cut. cat. + every free coalg. naturally carries the struc. of a comm. monoid s.t. every coalg.

What is the dynamics of cut?

Cut = Contract<sup>n</sup> (in Physics)

$$A \xrightarrow{f} B \cdot B \xrightarrow{g} C$$

$\Downarrow$

$$A \otimes B \xrightarrow{f \otimes g} B \otimes C \sim A \rightarrow B^* \otimes B \otimes C$$

$$A \rightarrow B^* \otimes B \otimes C \xrightarrow{ev \otimes I} I \otimes C \cong C$$

$\uparrow$   
 $\cong \quad g \circ f$

"Contract" =

Comm. + hiding.

$\therefore \text{Comp}^n = \text{tensor} + \text{"comm of hiding"}$

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simplificat<sup>n</sup>:  $\otimes = \&$

$\& = \oplus$

! = ?

Then deal with a "Compact closed Category"

- can do tensor calc. & sums = prods & self dual comonad.

Fermionic Model: Fin dim. vect<sup>n</sup> spaces.

$\otimes$  for  $\otimes$  and  $\&$

$\oplus$  for  $\&$  and  $\oplus$

(ext. power)  $\wedge$  for ! and ?

$\Delta(V)$  has an almost comm. monoid structure  
- only graded. = commutative if field has char 2

for each  $\Gamma \xrightarrow{[\Pi]} \Delta$  in LL where  $\Pi$  reps

cuts, we obtain a map of vs's

$$\Gamma \otimes \Pi \longrightarrow \Delta \otimes \Pi$$

(all depending on choices for atomic formulae).

$$\text{s.t. } \Pi \longrightarrow \Delta \otimes \Pi \otimes \Pi^* \longrightarrow \Delta$$

get "the" cut-free pf.

But: where's the dynamics? What does it mean?

Hylend

Can give a nicer model using Fermionic Fock spaces....  
But claims dynamics there will not be good.

Girard's GOI model: a precursor.

Objects  $A = (A_*, A^*)$   
          inputs      outputs

Maps  $A \rightarrow B =$

```
graph TD
  A_star[A_*] --> A_star_prime[A^*]
  B_star_prime[B^*] --> B_star[B_*]
  A_star --> B_star
  B_star_prime --> A_star_prime[A^*]
```

= partial  $\int$   $A_* + B^* \rightarrow B_* + A^*$

Composit<sup>n</sup>:  
mediated by  
feed back  
between  
 $B_*$  &  $B^*$

```
graph TD
  A_star[A_*] --> A_star_prime[A^*]
  B_star[B_*] --> B_star_prime[B^*]
  B_star --> C_star[C_*]
  C_star --> C_star_prime[C^*]
  C_star_prime --> B_star_prime
  B_star_prime --> A_star_prime
```

This cat is compact closed, but little else....  
Dynamics is externally monitored.

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The Real model:

- "Based" on his pt of SN
- Info. "flow dynamics".

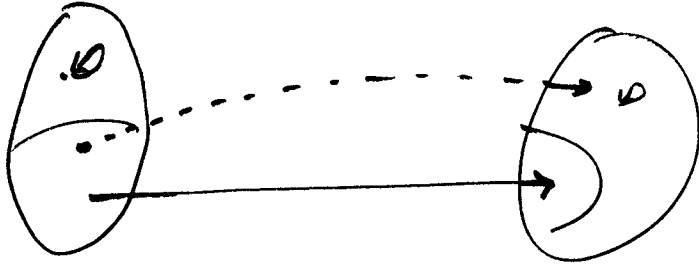
Equip  $A_*, A^*$  w/ sets of internal dynamics.

Have  $\alpha: A_* \rightarrow A^*$ ,  $\beta: A^* \rightarrow A_*$  s.t.  $\forall \alpha, \beta$

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- $\beta \alpha : A_* \rightarrow A_*$  ,  $\alpha \beta : A^* \rightarrow A^*$  passes by iteration to a stable state (Nilpotent operators)

E.g.  
of  
partial  
fns



- sets of states of dynamical system - defined on "non-idling" part:  $\dots \rightarrow$  idles & nothing happens.  
 $\therefore$  partial fns = info flow in this sense.

Now take maps = (singularity-free) dynamics as before which stabilizes w/ help of internal dynamics.

This model: still compact closed but not much else (no +, !'s are fudged) - but there is an internal control of dynamics.

Abramsky - Jagadeesan model.

Objects:  $A = (A_*, A^*)$

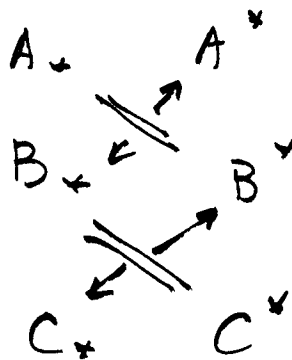
maps  $A \rightarrow B$  :  $A_*$   $\begin{matrix} \nearrow \\ \searrow \end{matrix}$   $A^*$   
 $B_*$   $\begin{matrix} \nearrow \\ \searrow \end{matrix}$   $B^*$

fns  $A_* \times B^* \rightarrow B_* \times A^*$

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Comp<sup>n</sup>:  $A \rightarrow B \rightarrow C$

mediated by  
fixed pts.



e.g.

$f: A \times S \rightarrow B \times S$  ( $f^A$  w/ states).

IF fixed pts  $\exists$ , can pass to a  $f^A$ :

~~Define~~

e.g.  $A \times S \rightarrow S$   
Define:  $A \rightarrow S \xrightarrow{\gamma} S$   
 $\sigma$

$\bar{f}: A \rightarrow B$

$a \mapsto f(a, \sigma(a))$ .

above:  $A_+ \times C^+ \times \underbrace{(B_+ \times B^+)}_{=S} \rightarrow C_+ \times A^+ \times (B_+ \times B^+)$

$\therefore$  get a  $f^A$  as  
above

Abstract derivates of A - J.

• Take cat.  $\mathbb{E}$ : from self dual cat.

$\mathbb{D} = \mathbb{E} \times \mathbb{E}^{op}$ .

• IF  $\mathbb{E}$  ecc., take comonad on  $\mathbb{D}$ .

$(U, X) \xrightarrow{G} (U, X^u)$   $\perp$  dual

monad  $(U, X) \xrightarrow{Q} (U^*, X)$

playing second in  $\Gamma^* \Delta$  —

Get compact closed cat — not much else.

Query: can we fudge?

We do control dynamics internally:  $g$  games  
are w/  $\otimes$   $\therefore$  ~~def.~~ def. by ordinal of game.

General framework:

$A \xrightarrow{f} B$ ,  $B \xrightarrow{g} C$ , ...

Other models:

- Blas's Theory of Games
- Lamarche's Seq. algebras
- Realiz. Models.
- Girard's SN