

# Algebraic Geometry over Groups

H. J. R. Wilton

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## Equations over free groups

Fix  $\mathbb{F}$  a free (non-abelian) group of rank at least 2, and consider a finite set  $\Phi$  of equations

$$w_i(x_1, \dots, x_n) = 1$$

in  $n$  unknowns. Let  $G = G(\Phi)$  be the group with presentation

$$\langle x_1, \dots, x_n \mid w_i(x_1, \dots, x_n) \rangle.$$

A solution of  $\Phi$  defines a homomorphism

$$G \rightarrow \mathbb{F},$$

and, conversely, such a homomorphism defines a solution of  $\Phi$ . So the ‘variety’ associated to  $\Phi$  is really just  $\text{Hom}(G, \mathbb{F})$ . This is the object we shall attempt to describe.

## First examples

- $G = F_r$  the free group of rank  $r$ . Then

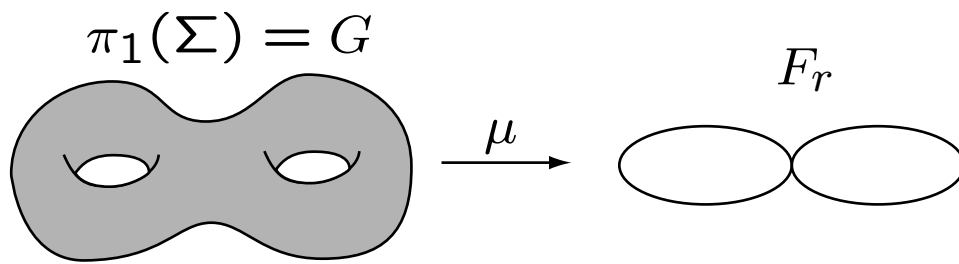
$$\text{Hom}(G, \mathbb{F}) \cong \mathbb{F}^r.$$

- $G = \mathbb{Z}^r$  the free abelian group of rank  $r$ . Let  $\mu : G \rightarrow \mathbb{Z}$  be projection onto the first factor. Any homomorphism  $f : G \rightarrow \mathbb{F}$  decomposes as

$$G \xrightarrow{\alpha} G \xrightarrow{\mu} \mathbb{Z} \rightarrow \mathbb{F}$$

for some automorphism  $\alpha$ . So we have an epimorphism

$$GL_r(\mathbb{Z}) \times \mathbb{F} \rightarrow \text{Hom}(G, \mathbb{F}).$$



- $G = \pi_1(\Sigma)$  the fundamental group of a closed orientable surface of genus  $g > 1$ , and let  $\mu : G \rightarrow F_r$  be the homomorphism induced by the inclusion of  $\Sigma$  as the boundary in the handlebody of genus  $r$ . Then every homomorphism  $G \rightarrow \mathbb{F}$  decomposes as

$$G \xrightarrow{\alpha} G \xrightarrow{\mu} F_r \rightarrow \mathbb{F}$$

for some automorphism  $\alpha$  of  $G$  arising from an automorphism of  $\Sigma$ . So we have an epimorphism

$$\text{Aut}(\Sigma) \times \mathbb{F}^r \rightarrow \text{Hom}(G, \mathbb{F}).$$

## Makanin-Razborov Diagrams

A general description of  $\text{Hom}(G, \mathbb{F})$  along these lines was first given by Makanin and Razborov.

**Theorem 1 (Makanin, Razborov)** *To every finitely generated group  $G$  there is associated a finite tree of homomorphisms from  $G$  to  $\mathbb{F}$ , called a Makanin-Razborov diagram. Each group in the tree is a limit group, and each homomorphism  $G \rightarrow \mathbb{F}$  factors through a branch of the diagram, after composing at each stage with automorphisms of the limit groups.*

## Limit groups

There are many equivalent definitions of limit groups. This one will best suit our purposes.

**Definition 2** *A group  $G$  is a limit group if, for any finite subset  $S \subset G$ , there exists a homomorphism  $f : G \rightarrow \mathbb{F}$ , such that  $f|_S$  is injective.*

Here are the simplest examples.

- Free groups
- Free abelian group
- Fundamental groups of closed surfaces of Euler characteristic less than  $-1$

The rest of this talk is devoted to explaining the proof of theorem 1 (skating over some details). Its principle assertions are about the finiteness of the tree. The next theorem shows that the tree is only finitely long.

**Theorem 3** *Let*

$$G_1 \rightarrow G_2 \rightarrow G_3 \rightarrow \dots$$

*be a sequence of epimorphisms of finitely generated groups. Then the corresponding sequence of monomorphisms*

$$\text{Hom}(G_1, \mathbb{F}) \leftarrow \text{Hom}(G_2, \mathbb{F}) \leftarrow \text{Hom}(G_3, \mathbb{F}) \leftarrow \dots$$

*eventually stabilizes.*

The proof of theorem 3 makes use of a little classical algebraic geometry.

**Theorem 4 (Hilbert's Basis Theorem)** *If  $R$  is a Noetherian ring then the polynomial ring  $R[x]$  is also Noetherian.*

*In particular, every descending sequence of algebraic varieties*

$$X_1 \supset X_2 \supset X_3 \supset \dots$$

*eventually terminates.*



**Proof of theorem 3:** Embed  $\mathbb{F} \hookrightarrow SL_2(\mathbb{R})$ . (For example, a hyperbolic metric on a punctured sphere gives an embedding  $\mathbb{F} \hookrightarrow PSL_2(\mathbb{R})$ . This lifts to  $SL_2(\mathbb{R})$ .) This induces an embedding

$$\text{Hom}(G, \mathbb{F}) \rightarrow \text{Hom}(G, SL_2(\mathbb{R})).$$

Fix a presentation

$$G = \langle g_1 \dots g_m \mid r_1, r_2, \dots \rangle.$$

A homomorphism  $f : G \rightarrow SL_2(\mathbb{R})$  is just a choice of values for the  $f(g_i)$  such that the relations  $f(r_j)$  are satisfied. In other words,

$$\text{Hom}(G, SL_2(\mathbb{R})) \hookrightarrow SL_2(\mathbb{R})^m$$

as a subvariety. (I think Richard would rather I said sub-scheme.) By Hilbert's Basis Theorem, the resulting decreasing sequence of varieties eventually stabilizes. **QED**

The remainder of the proof of theorem 1 consists of showing that the diagram is finitely wide.

**Definition 5** *Let  $G$  be a finitely generated group. A factor set is a finite set of proper quotients*

$$\{q_i : G \rightarrow L_i\}$$

*such that any homomorphism  $f : G \rightarrow \mathbb{F}$  factors as*

$$G \xrightarrow{\alpha} G \xrightarrow{q_i} L_i \rightarrow \mathbb{F},$$

*where  $\alpha$  is a ‘modular’ automorphism of  $G$ .*

I won’t define modular automorphisms, but if  $G$  isn’t a limit group then the group of modular automorphisms is trivial.

**Theorem 6** *Every non-free finitely generated group has a factor set*

$$\{q_i : G \rightarrow L_i\}$$

*with each  $L_i$  a limit group.*

## A nice reduction

There's a nice observation that reduces theorem 6 to the case of limit groups straight away. Suppose  $G$  is *not* a limit group. Then there exist elements  $g_1, \dots, g_n$  such that any homomorphism  $f : G \rightarrow \mathbb{F}$  kills one of the  $g_i$ . Now

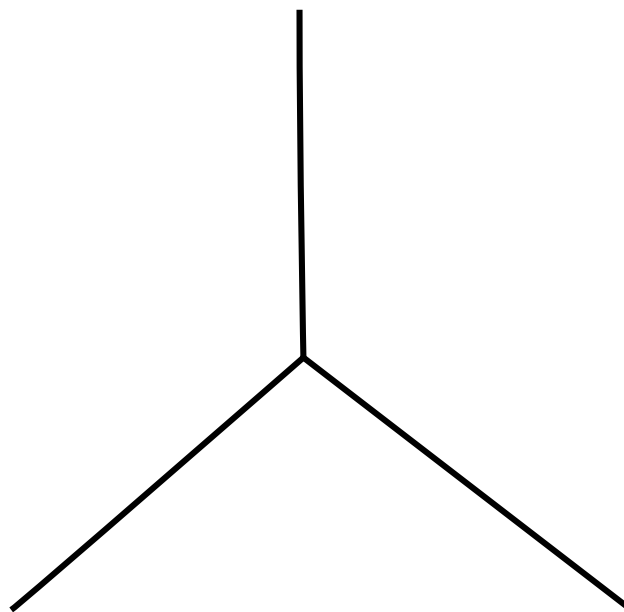
$$\{q_i : G \rightarrow L_i = G_i / \langle\langle g_i \rangle\rangle\}$$

is a factor set for  $G$ .

## Metric trees

Metric trees (also known as  $\mathbb{R}$ -trees) generalize the usual (simplicial) notion of tree. A metric space is *geodesic* if every pair of points are joined by an isometrically embedded interval.

**Definition 7** *A metric tree is a geodesic metric space  $(T, d)$  in which every geodesic triangle is isometric to a tripod.*



Simplicial trees are clearly metric trees. Here's a non-simplicial example.

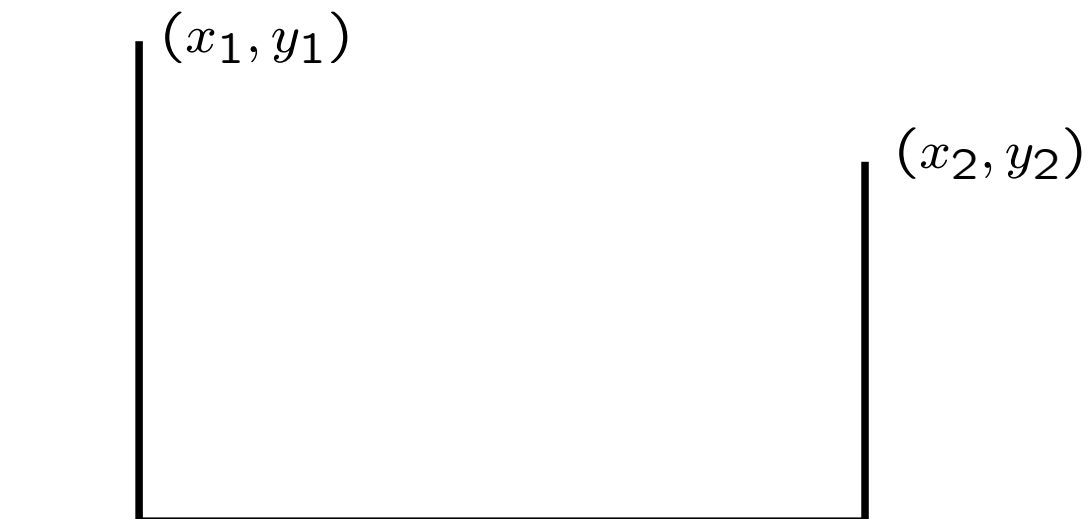
**Example 8 (The SNCF metric)** Consider the metric on  $\mathbb{R}^2$  given by

$$d((x, y_1), (x, y_2)) = |y_1 - y_2|$$

and

$$d((x_1, y_1), (x_2, y_2)) = |y_1| + |x_1 - x_2| + |y_2|$$

for  $x_1 \neq x_2$ .



## $G$ -trees

A metric tree equipped with an action of a finitely generated group  $G$  by isometries is called a  $G$ -tree. Here we review a few of the basics of the theory of group actions on trees.

A  $G$ -tree  $T$  is *trivial* if there is a point of  $T$  fixed by  $G$ .

$T$  is *minimal* if it contains no proper  $G$ -invariant subtrees.

**Lemma 9** *Every non-trivial  $G$ -tree contains a unique minimal subtree, which is a countable union of lines.*

## Cayley graphs

Let  $G$  be a group, and  $S$  a generating set. Then the *Cayley graph* of  $G$  with respect to  $S$  is the graph with vertex set  $G$  and an edge  $(g, h)$  if

$$h = gs$$

for some  $s \in S$ . The Cayley graph has a  $G$ -action inherited from left-multiplication by  $G$ , and a  $G$ -invariant metric given by counting the number of edges in the shortest path.

**Example 10** *Loops in the Cayley graph correspond to relations between the generators. So a group has a Cayley graph which is a tree if and only if it's free.*

Fix a generating set for  $\mathbb{F}$ , such that its Cayley graph  $T$  is a tree. Then a homomorphism  $f : G \rightarrow \mathbb{F}$  induces an action of  $G$  on  $T$ , where

$$g : t \mapsto f(g)t.$$

Denote the minimal  $G$ -invariant subtree of  $T$  by  $T_f$ .

## The space of trees

Let  $\mathcal{A}(G)$  be the set of non-trivial minimal  $G$ -trees. It can be endowed with a topology, known as *equivariant Gromov-Hausdorff topology*. I won't give details of this topology here.

Let  $\mathbb{P}\mathcal{A}(G)$  be the quotient space arising from identifying  $(T, d)$  with  $(T, \lambda d)$  for all  $\lambda > 0$ . The space of interest is

$$\mathcal{T}(G) \subset \mathbb{P}\mathcal{A}(G)$$

the closure of  $\{T_f | f \in \text{Hom}(G, \mathbb{F})\}$ , the subspace of  $G$ -trees arising from homomorphisms to  $\mathbb{F}$ .



## Strategy

The strategy for proving theorem 6 is now approximately as follows.

1. Show that  $\mathcal{T}(G)$  is compact.
2. Apply compactness to the open cover

$$\mathcal{U} = \{U(k) | k \in G - \{1\}\}$$

where  $U(k) = \{T | k \in \ker T\}$ .

The theorem would then follow; for by compactness,  $\mathcal{T}(G)$  is covered by

$$U(k_1), \dots, U(k_n).$$

In particular, each homomorphism  $f : G \rightarrow \mathbb{F}$  factors through one of

$$q_i : G \rightarrow L_i = G / \langle\langle k_i \rangle\rangle.$$

The slickest way to show compactness uses a technique of non-standard analysis pioneered by Gromov.

## Ultralimits

An *ultrafilter*  $\omega$  is a finitely additive set function on  $\mathbb{N}$ , such that for every  $S \subset \mathbb{N}$ ,  $\omega(S) \in \{0, 1\}$ . An ultrafilter is *principal* if any finite subset  $S \subset \mathbb{N}$  has  $\omega(S) = 1$ .

Fix  $\omega$  a non-principal ultrafilter (existence requires the axiom of choice). Let  $X$  be a topological space, and  $x_n \in X$ . Then  $x = \lim_{\omega} x_n$  is the *ultralimit* of  $x_n$  if, for every open neighbourhood  $U$  of  $x$ ,

$$\omega\{n \in \mathbb{N} \mid x_n \in U\} = 1.$$

**Lemma 11** *If  $X$  is a compact space then every sequence has an ultralimit.*

## Ultraproducts

Let  $(X_n, d_n, x_n)$  be a sequence of pointed metric spaces. Let

$$Y \subset \prod X_n$$

be the subspace consisting of sequences  $(y_n)$  with  $d_n(x_n, y_n)$  bounded. Then  $Y$  inherits a pseudo-metric given by

$$D((y_n), (z_n)) = \lim_{\omega} d_n(x_n, y_n).$$

The *ultraproduct* of the sequence  $(X_n, d_n, x_n)$ , denoted  $(X_{\omega}, d_{\omega})$ , is the associated metric space. It has the following useful properties.

**Lemma 12** *Suppose all the  $X_n$  are geodesic. Then so is  $X_{\omega}$ .*

*Suppose  $T_n$  is a sequence of trees. Then so is  $T_{\omega}$ .*

If each  $T_n$  admits a  $G$ -action then the induced action on  $Y$  descends to  $T_{\omega}$ . Furthermore, a sequence of  $G$ -trees converges to its ultralimit in the equivariant Gromov-Hausdorff topology.

It remains to show that  $T_\omega$  is non-trivial: then we can pass to the minimal invariant subtree. This is done by carefully choosing the base-point and scale factor.

Fix a generating set  $S$  for  $G$ , and define  $\sigma_n : T_n \rightarrow \mathbb{R}$  by

$$\sigma_n(x) = \max_{g \in S} d_n(x, gx).$$

Let  $\delta_n = \inf_{x \in T} \sigma_n(x)$ , and choose  $x_n \in T_n$  to minimize  $\sigma_n$ . Now modify  $T_n$  by dividing the metric by  $\delta_n$ . Let  $t = [(t_n)] \in T_\omega$ . For each  $t_n$  there exists  $g \in S$  with

$$d_n(t_n, gt_n) \geq \sigma_n(x_n) = 1$$

so, by construction, for some  $g \in S$ ,

$$d_\omega(t, gt) \geq 1.$$

## Short automorphisms

The first part of the strategy is now complete. If the second part worked, then we could get away without modular automorphisms. The problem is that  $\mathcal{U}$  doesn't cover  $\mathcal{T}(G)$ .

Fix a basis  $S$  for  $G$ . For  $f : G \rightarrow \mathbb{F}$ , define

$$|f| = \max_{g \in S} l(f(g))$$

where  $l$  is word length in  $\mathbb{F}$ . A homomorphism  $f$  is *short* if

$$|f| < |i_c \circ f \circ \alpha|$$

for all  $c \in \mathbb{F}$  and modular automorphisms  $\alpha$ . The key is the following tricky theorem of Sela.

**Theorem 13** *For a sequence of short automorphisms  $f_n : G \rightarrow \mathbb{F}$  with  $T_{f_n}$  converging to  $T$ , the limit action on  $T$  is not faithful.*

Part 2 of our strategy now works, after restricting attention to

$$\mathcal{T}'(G) \subset \mathcal{T}(G)$$

the closure of the set of  $G$ -trees arising from short homomorphisms to  $\mathbb{F}$ . This completes the proof of theorem 6, and so theorem 1.

## Further directions

This technique has proved very open to generalization, particularly in describing  $\text{Hom}(G, H)$  for other groups  $H$ .

- Sela has extended his work to cover *word hyperbolic* groups: groups whose Cayley graphs have uniformly thin triangles.
- Alibegovic has constructed Makanin-Razborov diagrams relative to limit groups.
- Groves is working on a series of papers which would generalize both of these, extending Sela's techniques to groups that are *hyperbolic relative to their maximal abelian subgroups*.