

# PROBABILITY AND MEASURE

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## 1. $\sigma$ -algebra and the monotone class Lemma

**Definition 1.1** ( $\sigma$ -algebra). *Let  $E$  be a set. A  $\sigma$ -algebra (or tribe) on  $E$  is a family  $\mathcal{A} \subset \mathcal{P}(E)$  such that*

- (i)  $E \in \mathcal{A}$
- (ii)  $A \in \mathcal{A} \Rightarrow A^c = E \setminus A \in \mathcal{A}$
- (iii)  $A_n \in \mathcal{A} \Rightarrow \bigcup_{n \geq 0} A_n \in \mathcal{A}$

**Definition 1.2** (Generating set). *Let  $\mathcal{C} \subset \mathcal{P}(E)$ , we let  $\sigma(\mathcal{C})$  be the smallest  $\sigma$ -algebra containing  $\mathcal{C}$ .*

**Definition 1.3** (Borel  $\sigma$ -algebra). *If  $E$  is a topological space, we let  $\mathcal{B}(E)$  be the  $\sigma$ -algebra generated by the open sets of  $E$ .*

**Definition 1.4** (Product  $\sigma$ -algebra). *Given  $(E_1, \mathcal{A}_1)$ ,  $(E_2, \mathcal{A}_2)$ , we let*

$$\mathcal{A}_1 \otimes \mathcal{A}_2 = \sigma(\{A_1 \times A_2, A_1 \in \mathcal{A}_1, A_2 \in \mathcal{A}_2\}).$$

**Proposition 1.5.** *If  $E_1, E_2$  are separable metric spaces, then  $\mathcal{B}(E_1) \otimes \mathcal{B}(E_2) = \mathcal{B}(E_1 \times E_2)$ .*

**Definition 1.6** (Monotone class). *A family  $\mathcal{M} \subset \mathcal{P}(E)$  is a monotone class if:*

- (i)  $E \in \mathcal{M}$
- (ii)  $A, B \in \mathcal{M}$  and  $A \subset B$  imply  $B \setminus A \in \mathcal{M}$ .
- (iii)  $A_n \in \mathcal{M}$  increasing family implies  $\bigcup_{n \geq 0} A_n \in \mathcal{M}$ .

**Definition 1.7.** *Let  $\mathcal{C} \subset \mathcal{P}(E)$ , we let  $\mathcal{M}(\mathcal{C})$  be the smallest monotone class containing  $\mathcal{C}$ .*

**Lemma 1.8.** *A monotone class is a  $\sigma$ -algebra iff it is stable by finite intersection.*

**Proposition 1.9** (Monotone class Lemma). *Let  $\mathcal{C} \subset \mathcal{P}(E)$  stable by finite intersection, then  $\mathcal{M}(\mathcal{C}) = \sigma(\mathcal{C})$ .*

## 2. Measure

**Definition 2.1** (Measure). *A (positive) measure on  $(E, \mathcal{A})$  is a map  $\mu : \mathcal{A} \rightarrow [0, \infty]$  with:*

- (i)  $\mu(\emptyset) = 0$
- (ii)  $A_n \in \mathcal{A}$  two by two disjoint then  $\mu(\bigcup_{n \geq 0} A_n) = \sum_{n \geq 0} \mu(A_n)$ .

**Proposition 2.2.** *Let  $(E, \mathcal{A}, \mu)$  be a measure space.*

- (i) *Let  $A_n$  be an increasing family  $A_n \subset A_{n+1}$  then  $\mu(\bigcup_{n \geq 0} A_n) = \lim_{n \rightarrow \infty} \mu(A_n)$ .*
- (ii) *Let  $B_n$  be a decreasing family  $B_{n+1} \subset B_n$  with  $\mu(B_0) < +\infty$  then  $\mu(\bigcap_{n \geq 0} B_n) = \lim_{n \rightarrow \infty} \mu(B_n)$ .*

**Definition 2.3** (Probability measure). *We say  $\mu$  is finite if  $\mu(E) < +\infty$ . If  $\mu(E) = 1$ , we call  $\mu$  a probability.*

**Definition 2.4** ( $\sigma$ -finite). We say  $\mu$  is  $\sigma$ -finite if there exists an increasing sequence  $E_n$  with  $\cup_{n \geq 0} E_n = E$  and  $\forall n, \mu(E_n) < +\infty$ .

**Definition 2.5** (Negligible set). A set  $N \subset E$  is negligible if there exists  $A \in \mathcal{A}$  with  $\mu(A) = 0$  such that  $N \subset A$ . A property is said to hold a.e if the set of points  $x \in E$  where it does not hold is negligible.

**Definition 2.6** (Completeness). We say  $\mu$  is complete if  $\mathcal{A}$  contains all the negligible sets.

**Proposition 2.7** (Uniqueness of measures). Let  $\mu, \nu$  be two measures on  $(E, \mathcal{A})$ .

Assume:

- (i)  $\mathcal{A} = \sigma(\mathcal{C})$  with  $\mathcal{C}$  stable by finite intersection;
- (ii)  $\forall A \in \mathcal{C}, \mu(A) = \nu(A)$ ;

then we can conclude that  $\mu = \nu$  on the full  $\sigma$ -algebra  $\mathcal{A}$  whenever one of the following two conditions holds:

- (i)  $\mu(E) = \nu(E) < +\infty$
- (ii)  $\exists$  an increasing sequence  $E_n \subset \mathcal{C}$  with  $E = \cup_{n \geq 0} E_n$  and  $\forall n, \mu(E_n) < +\infty$ .

### 3. Measurable functions

**Definition 3.1** (Measurable spaces). Let  $(E, \mathcal{A}), (F, \mathcal{B})$  be two measurable spaces. A map  $f : E \rightarrow F$  is measurable if  $\forall B \in \mathcal{B}, f^{-1}(B) \in \mathcal{A}$ .

**Proposition 3.2.** The composition of two measurable functions is measurable.

**Proposition 3.3.** Assume  $\mathcal{B} = \sigma(\mathcal{C})$ , then  $f$  is measurable iff  $\forall B \in \mathcal{C}, f^{-1}(B) \in \mathcal{A}$ .

**Proposition 3.4.** A continuous function  $f : (E, \mathcal{B}(E)) \rightarrow (F, \mathcal{B}(F))$  is measurable.

**Lemma 3.5.** Let  $f_1 : (E, \mathcal{A}) \mapsto (F_1, \mathcal{B}_1)$  and  $f_2 : (E, \mathcal{A}) \mapsto (F_2, \mathcal{B}_2)$ . Then  $f : (E, \mathcal{A}) \mapsto (F_1 \times F_2, \mathcal{B}_1 \otimes \mathcal{B}_2)$  defined by  $f(x) = (f_1(x), f_2(x))$  is measurable iff each component  $f_1, f_2$  is measurable.

**Lemma 3.6.** Let  $f, g : (E, \mathcal{A}) \rightarrow (\mathcal{R}, \mathcal{B}(\mathcal{R}))$  be two measurable functions, then the following functions are measurable:

- (i) any linear combination of  $(f, g)$ ;
- (ii)  $fg$ ;
- (iii)  $f^+ = \max(f, 0), f^- = \max(-f, 0)$ .

**Definition 3.7** ( $\limsup$ ,  $\liminf$ ). We let

$$\limsup_{n \rightarrow \infty} a_n = \lim_{n \rightarrow \infty} \downarrow \left( \sup_{k \geq n} a_k \right) = \inf_{n \geq 0} \left( \sup_{k \geq n} a_k \right)$$

and

$$\liminf_{n \rightarrow \infty} a_n = \lim_{n \rightarrow \infty} \uparrow \left( \inf_{k \geq n} a_k \right) = \sup_{n \geq 0} \left( \inf_{k \geq n} a_k \right).$$

**Proposition 3.8.** Let  $f_n$  be a sequence of measurable functions from  $(E, \mathcal{A})$  to  $(\mathbb{R}, \mathcal{B}(\mathbb{R}))$ , then:

- (i) the functions

$$\sup_{n \geq 0} f_n, \inf_{n \geq 0} f_n, \limsup_{n \rightarrow \infty} f_n, \liminf_{n \rightarrow \infty} f_n$$

are also measurable. In particular,  $(f_n \rightarrow f$  pointwise  $\Rightarrow f$  measurable);

- (ii) the set  $\{x \in E; f_n(x) \text{ has a limit as } n \rightarrow \infty\}$  is measurable.

**Definition 3.9** (Measure transported by an application). *Let  $f : (E, \mathcal{A}) \rightarrow (F, \mathcal{B})$  be a measurable function and  $\mu$  a measure on  $(E, \mathcal{A})$ . The image measure of  $\mu$  by  $f$ , noted  $f_*(\mu)$  (sometimes  $f(\mu)$ ) is the measure defined by*

$$\forall B \in \mathcal{B}, \quad f_*\mu(B) = \mu(f^{-1}(B)).$$

## 4. Integration

### 4.1. Integration of positive functions.

**Definition 4.1** (Simple function). *Let  $(E, \mathcal{A}, \mu)$  measure space. A function  $f : (E, \mathcal{A}) \rightarrow \mathbb{R}$  is called simple if*

$$f = \sum_{j=1}^N \alpha_j \mathbf{1}_{A_j}, \quad A_j \in \mathcal{A} \quad \text{and} \quad \bigsqcup_{j=1}^N A_j = E$$

for some  $\alpha_j \in \mathbb{R}$ . If the values  $\alpha_j$  are distinct, this is the canonical representation of  $f$ .

**Definition 4.2** (Integral of simple functions). *Let  $f$  simple valued in  $\mathbb{R}_+$ , we define*

$$\int f d\mu = \sum_{j=1}^n \alpha_j \mu(A_j)$$

with the convention:  $(\alpha_j = 0, \mu(A_j) = +\infty) \Rightarrow \alpha_j \mu(A_j) = 0$ . This number does not depend on the representation of  $f$ . We let  $\mathcal{E}_+$  be the set of positive ( $\geq 0$ ) simple functions.

**Definition 4.3** (Integral of a positive function). *Let  $(E, \mathcal{A}, \mu)$  measure space and  $f : (E, \mathcal{A}) \rightarrow \overline{\mathbb{R}}_+$  a positive measurable function. We define*

$$\int f d\mu = \sup_{h \in \mathcal{E}_+, h \leq f} \int h d\mu.$$

**Lemma 4.4** (Basic properties). *There holds:*

- (i)  $f \geq g \Rightarrow \int f d\mu \geq \int g d\mu$ .
- (ii)  $\mu(\{x \in E, f(x) > 0\}) = 0 \Rightarrow \int f d\mu = 0$ .

**Theorem 4.5** (Monotone convergence). *Let  $(E, \mathcal{A}, \mu)$  measure space and  $f_n : (E, \mathcal{A}) \rightarrow \overline{\mathbb{R}}_+$  an increasing sequence of positive ( $\geq 0$ ) measurable functions. Let  $f = \lim_n \uparrow f_n$ , then*

$$\int f d\mu = \lim_{n \rightarrow \infty} \uparrow \int f_n d\mu.$$

**Proposition 4.6** (Approximation by simple functions). *Let  $f$  be measurable positive, then there exists an increasing sequence  $f_n$  of positive simple functions such that  $\forall x \in E, \lim_{n \rightarrow \infty} f_n(x) = f(x)$ .*

**Proposition 4.7** (Basic properties). *All functions are assumed to be measurable positive on  $(E, \mathcal{A}, \mu)$  measure space.*

- (i)  $\forall a, b \geq 0, \int (af + bg) d\mu = a \int f d\mu + b \int g d\mu$ .
- (ii)  $\int \left( \sum_{n \geq 0} f_n \right) d\mu = \sum_{n \geq 0} \int f_n d\mu$ .
- (iii) (Markov)  $\mu(\{x \in E, f(x) \geq a\}) \leq \frac{1}{a} \int f d\mu$ .
- (iv)  $\int f d\mu < \infty \Rightarrow f < \infty \text{ a.e.}$
- (v)  $\int f d\mu = 0 \Rightarrow f = 0 \text{ a.e.}$
- (vi)  $f = g \text{ a.e.} \Rightarrow \int f d\mu = \int g d\mu$ .

**Theorem 4.8** (Fatou). *Let  $(E, \mathcal{A}, \mu)$  measure space and  $f_n$  measurable positive, then*

$$\int \left( \liminf_{n \rightarrow \infty} f_n \right) d\mu \leq \liminf_{n \rightarrow \infty} \left( \int f_n d\mu \right).$$

#### 4.2. Integration of real valued functions.

**Definition 4.9** (Integral of real valued functions). *Let  $(E, \mathcal{A}, \mu)$  measure space and  $f : E \rightarrow \mathbb{R}$ . We say that  $f$  is integrable if  $\int |f| d\mu < +\infty$  and we then define*

$$\int f d\mu = \int f^+ d\mu - \int f^- d\mu$$

where  $f^+ = \max\{f, 0\}$ ,  $f^- = \max\{-f, 0\}$ . We note  $\mathcal{L}^1(E, \mathcal{A}, \mu)$  the space of real valued integrable functions.

**Proposition 4.10** (Linearity).  *$\mathcal{L}^1(E, \mathcal{A}, \mu)$  is a vector space and  $f \rightarrow \int f d\mu$  is a linear form.*

**Proposition 4.11** (Basic properties). *Let  $f, g \in \mathcal{L}^1(E, \mathcal{A}, \mu)$ .*

- (i)  $|\int f d\mu| \leq \int |f| d\mu$ .
- (ii)  $f \leq g \Rightarrow \int f d\mu \leq \int g d\mu$ .
- (iii)  $f = g$  a.e.  $\Rightarrow \int f d\mu = \int g d\mu$ .

**Theorem 4.12** (Lebesgue's dominated convergence). *Let  $f_n \in \mathcal{L}^1(E, \mathcal{A}, \mu)$  such that:*

- (i)  $\exists f$  real valued measurable with  $\lim_{n \rightarrow \infty} f_n(x) = f(x)$  a.e.;
- (ii)  $\exists g : E \rightarrow \mathbb{R}_+ \in \mathcal{L}^1(E, \mathcal{A}, \mu)$  such that  $\forall n, |f_n(x)| \leq g(x)$  a.e..

Then  $f \in \mathcal{L}^1(E, \mathcal{A}, \mu)$  and

$$\lim_{n \rightarrow \infty} \int |f_n - f| d\mu = 0.$$

#### 4.3. Integral depending on a parameter.

**Theorem 4.13** (Continuity below the integral sign). *Let  $(E, \mathcal{A}, \mu)$  a measure space and  $(U, d)$  a metric space. Let  $f : U \times E \rightarrow \mathbb{R}$  and  $u_0 \in U$ . Assume:*

- (i)  $\forall u \in U$ , the map  $x \mapsto f(u, x)$  is measurable;
- (ii) a.e  $x \in E$ , the map  $u \mapsto f(x, u)$  is continuous at  $u_0$ ;
- (iii)  $\exists g \in \mathcal{L}_+^1(E, \mathcal{A}, \mu)$  such that  $\forall u \in U, |f(u, x)| \leq g(x)$  a.e..

Then the function  $F(u) = \int f(u, x) d\mu$  is well defined for all  $u \in U$  and continuous at  $u_0$ .

**Theorem 4.14** (Derivability below the integral sign). *Let  $(E, \mathcal{A}, \mu)$  a measure space and  $I \subset \mathbb{R}$  an open interval. Let  $f : I \times E \rightarrow \mathbb{R}$  and  $u_0 \in I$ . Assume:*

- (i)  $\forall u \in I$ , the map  $x \mapsto f(u, x)$  is in  $\mathcal{L}^1(E, \mathcal{A}, \mu)$ ;
- (ii) a.e  $x \in E$ , the map  $u \mapsto f(x, u)$  is differentiable at  $u_0$  with derivative noted  $\frac{\partial f}{\partial u}(u_0, x)$ ;
- (iii)  $\exists g \in \mathcal{L}_+^1(E, \mathcal{A}, \mu)$  such that  $\forall u \in I, |f(u, x) - f(u_0, x)| \leq g(x)|u - u_0|$  a.e..

Then the function  $F(u) = \int f(u, x) d\mu$  is differentiable at  $u_0$  with

$$F'(u_0) = \int \frac{\partial f}{\partial u}(u_0, x) d\mu.$$

## 5. Construction of measures

Proofs in this section are non examinable, but statements are examinable.

### 5.1. Lebesgue measure.

**Definition 5.1** (Outer measure). *Let  $E$  be a set. A map  $\mu^* : \mathcal{P}(E) \rightarrow [0, \infty]$  is called an outer measure if:*

- (i)  $\mu^*(\emptyset) = 0$
- (ii)  $\mu^*$  is increasing:  $A \subset B \Rightarrow \mu^*(A) \leq \mu^*(B)$ .
- (iii)  $\mu^*$  is  $\sigma$  sub additive:  $\forall A_k \subset E, \mu^*(\bigcup_{k \geq 0} A_k) \leq \sum_{k \geq 0} \mu^*(A_k)$ .

**Definition 5.2** (Measurability). *A set  $B \subset E$  is called  $\mu^*$ -measurable if*

$$\forall A \subset E, \mu^*(A) = \mu^*(A \cap B) + \mu^*(A \cap B^c).$$

We let  $\mathcal{M}(\mu^*)$  be the set of  $\mu^*$ -measurable sets.

**Theorem 5.3** (Construction of a measure from an outer measure).  *$\mathcal{M}(\mu^*)$  is a  $\sigma$ -algebra in  $E$  and the restriction of  $\mu^*$  to  $\mathcal{M}(\mu^*)$  is a complete measure.*

**Theorem 5.4** (Lebesgue measure on  $\mathbb{R}$ ). *We define*

$$\forall A \subset \mathbb{R}, \lambda^*(A) = \inf \left\{ \sum_{i \in \mathbb{N}} (b_i - a_i), A \subset \bigcup_{i \in \mathbb{N}} [a_i, b_i] \right\}.$$

Then:

- (i)  $\lambda^*$  is an outer measure on  $\mathbb{R}$ .
- (ii)  $\mathcal{B}(\mathbb{R}) \subset \mathcal{M}(\lambda^*)$ .
- (iii)  $\forall a \leq b, \lambda^*([a, b]) = \lambda^*([a, b]) = b - a$ .

The restriction of  $\lambda^*$  to  $\mathcal{M}(\lambda^*)$  is called the Lebesgue measure on  $\mathbb{R}$ .

**Definition 5.5.** Let  $(E, \mathcal{A}, \mu)$  be a measure space, we let  $\overline{\mathcal{A}} = \sigma(\mathcal{A} \cup \mathcal{N})$  where  $\mathcal{N}$  are the  $\mu$ -negligible sets of  $E$ .

**Proposition 5.6.** The Lebesgue tribe  $\mathcal{M}(\lambda^*)$  is identical to  $\overline{\mathcal{B}(\mathbb{R})}$ .

**Proposition 5.7.** Let  $f : \mathbb{R} \rightarrow \mathbb{R}$  Borelian. Let  $g : \mathbb{R} \rightarrow \mathbb{R}$  such that  $g = f$   $\lambda$ -a.e, then  $g$  is measurable for  $\overline{\mathcal{B}(\mathbb{R})}$ .

### 5.2. Link to Riemann.

**Definition 5.8** ([Riemann integrability]). *Let  $I \subset \mathbb{R}$  be an interval and  $f : I \rightarrow \mathbb{R}$  bounded. Let*

$$\begin{cases} S_-(f) = \sup \{ \int_I h(x) dx, h \text{ stair, } h \leq f \} \\ S_+(f) = \inf \{ \int_I h(x) dx, h \text{ stair, } h \geq f \}. \end{cases}$$

We say that  $f$  is Riemann integrable if

$$S_+(f) = S_-(f)$$

and then the Riemann integral of  $f$  is  $S(f) = S_{\pm}(f)$ .

**Proposition 5.9** (Relation to Riemann). *Let  $f : I \rightarrow \mathbb{R}$  Riemann integrable, then  $f$  is measurable for  $\overline{\mathcal{B}(I)}$  and  $S(f) = \int_I f d\lambda$ .*

### 5.3. An example of non measurable set.

**Proposition 5.10.** Let  $\mathbb{R}/\mathbb{Q}$  be the set of equivalence class for the relation  $x \sim y \Leftrightarrow x - y \in \mathbb{Q}$ . Let  $F = \{x_a, a \in \mathbb{R}/\mathbb{Q}\}$  where  $x_a \in [0, 1]$  is a representant of the equivalence class of  $a$ . Then  $F$  is not Lebesgue measurable.

**Remark 5.11.** The existence of  $F$  requires the axiom of choice because  $\mathbb{R}/\mathbb{Q}$  is uncountable, and this is necessary to construct Lebesgue non measurable sets.

#### 5.4. Lebesgue-Stieltjes measures.

**Proposition 5.12.** *Let  $(E, d)$  be a metric space and  $\mu$  a finite measure on  $(E, \mathcal{B}(E))$ . Then for all  $A \in \mathcal{B}(E)$ :*

$$\mu(A) = \inf\{\mu(U), \text{ } U \text{ open }, A \subset U\} = \sup\{\mu(F), \text{ } F \text{ closed }, F \subset A\}$$

**Theorem 5.13** (Lebesgue-Stieltjes). *The following hold.*

(i) *Let  $\mu$  be a finite measure on  $(\mathbb{R}, \mathcal{B}(\mathbb{R}))$ , then its distribution function*

$$\forall x \in \mathbb{R}, \text{ } F_\mu(x) = \mu([-\infty, x])$$

*is increasing, bounded, continuous on the right and  $\lim_{x \rightarrow -\infty} F_\mu(x) = 0$ .*

(ii) *Given  $F : \mathbb{R} \rightarrow \mathbb{R}$  increasing, bounded, continuous on the right and with  $\lim_{x \rightarrow -\infty} F(x) = 0$ , then there exists a unique finite Borelian measure  $\mu$  such that  $F_\mu = F$ , and then*

$$F(b) - F(a) = \mu([a, b]).$$

### 6. $L^p$ spaces

**Definition 6.1** ( $L^p(E, \mathcal{A}, \mu)$ ,  $1 \leq p < \infty$ ). *Let  $(E, \mathcal{A}, \mu)$  be a measure space.*

(i) *Given  $p \in [1, \infty[$ , we define*

$$\mathcal{L}^p(E, \mathcal{A}, \mu) = \{f : E \rightarrow \mathbb{R} \text{ measurable with } \int |f|^p d\mu < +\infty\}$$

(ii) *We define  $\|f\|_p = (\int |f|^p d\mu)^{\frac{1}{p}}$ .*

(iii) *We let  $L^p(E, \mathcal{A}, \mu) = \mathcal{L}^p(E, \mathcal{A}, \mu)/\sim$  for  $f \sim g \Leftrightarrow f = g \text{ } \mu\text{-a.e.}$*

**Definition 6.2** ( $L^\infty(E, \mathcal{A}, \mu)$ ,  $1 \leq p < +\infty$ ). *Let  $(E, \mathcal{A}, \mu)$  be a measure space.*

(i) *We define*

$$\mathcal{L}^\infty(E, \mathcal{A}, \mu) = \{f : E \rightarrow \mathbb{R} \text{ measurable, } \exists C \in \mathbb{R}_+, \text{ } |f| \leq C \text{ } \mu\text{-a.e.}\}$$

(ii) *We define  $\|f\|_\infty = \inf\{C \in \mathbb{R}_+, \text{ } |f| \leq C \text{ } \mu\text{-a.e.}\}$ .*

(iii) *We let  $L^\infty(E, \mathcal{A}, \mu) = \mathcal{L}^\infty(E, \mathcal{A}, \mu)/\sim$  for  $f \sim g \Leftrightarrow f = g \text{ } \mu\text{-a.e.}$*

**Proposition 6.3** (Hölder). *The following hold.*

(i)  $\forall 1 \leq p, p' \leq \infty, \int |fg| d\mu \leq \|f\|_p \|g\|_{p'}$  for  $\frac{1}{p} + \frac{1}{p'} = 1$ .

(ii)  $\forall 1 \leq p, p_i \leq \infty, \|\prod_{i=1}^N f_i\|_p \leq \prod_{i=1}^N \|f_i\|_{p_i}$  for  $\frac{1}{p} = \sum_{i=1}^N \frac{1}{p_i}$ .

(iii)  $\forall 1 \leq p_1, p_2 \leq \infty, \|f\|_p \leq \|f\|_{p_1}^\alpha \|f\|_{p_2}^{1-\alpha}$  for  $\frac{1}{p} = \frac{\alpha}{p_1} + \frac{1-\alpha}{p_2}$ .

**Theorem 6.4** (Riesz-Fischer). *For all  $1 \leq p \leq +\infty$ ,  $(L^p(E, \mathcal{A}, \mu), \|\cdot\|_p)$  is a Banach space (ie a complete normed vector space). For  $p = 2$ ,  $(L^2(E, \mathcal{A}, \mu), \langle \cdot, \cdot \rangle_2)$  is a Hilbert space (ie a complete space equipped with a scalar product) for the scalar product  $\langle f, g \rangle_2 = \int_E f g d\mu$ .*

**Proposition 6.5.** *Let  $f_n, f \in L^p(E, \mathcal{A}, \mu)$  with  $\lim_{n \rightarrow +\infty} \|f_n - f\|_p = 0$ . Then there exists a subsequence  $\phi(n)$  strictly increasing such that  $\lim_{n \rightarrow +\infty} f_{\phi(n)}(x) = f(x)$  for  $\mu\text{-a.e } x \in E$ .*

**Proposition 6.6** (Dense subsets). *The following holds.*

(i) *Let  $1 \leq p \leq \infty$ , then simple functions are dense in  $L^p(E, \mathcal{A}, \mu)$ .*

(ii) *Let  $1 \leq p < \infty$ , then  $\mathcal{C}_c^\infty(\mathbb{R}^d)$  is dense in  $L^p(\mathbb{R}^d, \overline{\mathcal{B}(\mathbb{R}^d)}, \lambda)$  where  $\lambda$  is the Lebesgue measure (and this is obviously false for  $p = \infty$ ).*

## 7. Product measure and Fubini's theorem

**7.1. Product measure and Fubini.** We let  $(E_1, \mathcal{A}_1)$ ,  $(E_2, \mathcal{A}_2)$  be two measurable spaces.

**Definition 7.1** (Horizontal and vertical slices of sets). *Let  $B \subset E_1 \times E_2$ .*

- (i) *For  $x \in E_1$ , the vertical slice is  $B_x = \{y \in E_2, (x, y) \in B\}$ .*
- (ii) *For  $y \in E_2$ , the horizontal slice is  $B^y = \{x \in E_1, (x, y) \in B\}$ .*

**Definition 7.2** (Horizontal and vertical slices of functions). *Let  $f : E_1 \times E_2 \rightarrow F$ .*

- (i) *For  $x \in E_1$ , we let  $f_x = f(x, \cdot) : E_2 \rightarrow F$ .*
- (ii) *For  $y \in E_2$ , we let  $f^y = f(\cdot, y) : E_1 \rightarrow F$ .*

**Theorem 7.3** (Fubini measurability). *The following hold.*

- (i) *Pick  $B \in \mathcal{A}_1 \otimes \mathcal{A}_2$ , then  $\forall x \in E_1$ ,  $B_x \in \mathcal{A}_2$  and  $\forall y \in E_2$ ,  $B^y \in \mathcal{A}_1$ .*
- (ii) *Let  $f(E_1 \times E_2, \mathcal{A}_1 \otimes \mathcal{A}_2) \rightarrow (F, \mathcal{B})$  measurable, then  $\forall x \in E_1$ ,  $f_x : (E_2, \mathcal{A}_2) \rightarrow (F, \mathcal{B})$  is measurable, and  $\forall y \in E_2$ ,  $f^y : (E_1, \mathcal{A}_1) \rightarrow (F, \mathcal{B})$  is measurable.*

**Theorem 7.4** (Construction of the product measure). *Let  $\mu, \nu$  be two  $\sigma$ -finite measures on resp.  $(E, \mathcal{A})$  and  $(F, \mathcal{B})$ .*

- (i) *There exists a unique measure  $m$  on  $(E \times F, \mathcal{A} \otimes \mathcal{B})$  such that*

$$\forall A \in \mathcal{A}, \forall B \in \mathcal{B}, m(A \times B) = \mu(A)\nu(B)$$

*with the usual convention  $0 \cdot \infty = 0$ . This measure is called the product measure and is  $\sigma$ -finite, we note it  $\mu \otimes \nu$ .*

- (ii) *For all  $C \in \mathcal{A} \otimes \mathcal{B}$ ,*

$$\mu \otimes \nu(C) = \int_E \nu(C_x) \mu(dx) = \int_F \mu(C^y) \nu(dy).$$

**Theorem 7.5** (Fubini-Tonnelli). *Let  $\mu, \nu$  be two  $\sigma$ -finite measures on resp.  $(E, \mathcal{A})$  and  $(F, \mathcal{B})$ . Let  $f : E \times F \rightarrow [0, \infty]$  a measurable function.*

- (i) *The functions  $x \in E \mapsto \int_F f(x, y) \nu(dy)$  and  $y \in F \mapsto \int_E f(x, y) \mu(dx)$  are resp.  $\mathcal{A}$ -measurable and  $\mathcal{B}$ -measurable.*
- (ii) *There holds*

$$\int_{E \times F} f d(\mu \otimes \nu) = \int_E \left[ \int_F f(x, y) \nu(dy) \right] \mu(dx) = \int_F \left[ \int_E f(x, y) \mu(dx) \right] \nu(dy).$$

**Theorem 7.6** (Fubini-Lebesgue). *Let  $\mu, \nu$  be two  $\sigma$ -finite measures on resp.  $(E, \mathcal{A})$  and  $(F, \mathcal{B})$ . Let  $f \in \mathcal{L}^1(E \times F, \mathcal{A} \otimes \mathcal{B}, \mu \otimes \nu)$ .*

- (i) *For  $\mu$  a.e  $x \in E$ ,  $f_x \in \mathcal{L}^1(F, \mathcal{B}, \nu)$  and  $\nu$  a.e  $y \in F$ ,  $f^y \in \mathcal{L}^1(E, \mathcal{A}, \mu)$ .*
- (ii) *The function  $x \mapsto \int_F f(x, y) \nu(dy)$  is well defined for  $\mu$  a.e  $x \in E$  and belongs to  $\mathcal{L}^1(E, \mathcal{A}, \mu)$ . The function  $y \mapsto \int_E f(x, y) \mu(dx)$  is well defined for  $\nu$  a.e  $y \in F$  and belongs to  $\mathcal{L}^1(F, \mathcal{B}, \nu)$ .*
- (iii) *There holds*

$$\int_{E \times F} f d(\mu \otimes \nu) = \int_E \left[ \int_F f(x, y) \nu(dy) \right] \mu(dx) = \int_F \left[ \int_E f(x, y) \mu(dx) \right] \nu(dy).$$

### 7.2. Applications.

**Definition 7.7** (Convolution). *Let  $f, g : \mathbb{R}^d \rightarrow \mathbb{R}$  measurable. For  $x \in \mathbb{R}^d$ , we define the convolution product by*

$$f \star g(x) = \int f(x - y) g(y) dy.$$

**Proposition 7.8.** *Let  $f, g \in L^1(\mathbb{R}^d, \overline{\mathcal{B}(\mathbb{R}^d)}, \lambda)$ , then for  $\lambda$  a.e  $x \in \mathbb{R}^d$ , the convolution  $f \star g(x)$  is well defined. Moreover,  $f \star g \in L^1(\mathbb{R}^d, \overline{\mathcal{B}(\mathbb{R}^d)}, \lambda)$  with*

$$\|f \star g\|_{L^1} \leq \|f\|_{L^1} \|g\|_{L^1}.$$

**Proposition 7.9** (Young's inequality). *Ler  $1 \leq r, p, q \leq +\infty$  with  $1 + \frac{1}{r} = \frac{1}{p} + \frac{1}{q}$ , then*

$$\|f \star g\|_{L^r} \leq \|f\|_{L^p} \|g\|_{L^q}.$$

**Definition 7.10** (Approximation of identity). *We say a sequence of functions  $\phi_n : \mathbb{R}^d \rightarrow \mathbb{R}$  is an approximation of identity if:*

- (i)  $\phi_n \geq 0$ ;
- (ii) *there exists  $K \subset \mathbb{R}^d$  compact such that  $\text{Supp} \phi_n \subset K$ ;*
- (iii)  $\forall \delta > 0$ ,  $\lim_{n \rightarrow \infty} \int_{|x| < \delta} \phi_n(x) dx = 0$ .

**Proposition 7.11** (Density of smooth functions in  $L^p(\mathbb{R}^d)$ ). *Let  $\phi_n$  be an approximation of identity. Let  $1 \leq p < \infty$ . Then for all  $f \in L^p(\mathbb{R}^d, \overline{\mathcal{B}(\mathbb{R}^d)}, \lambda)$ ,  $\phi_n \star f \in \mathcal{C}^\infty(\mathbb{R}^d, \mathbb{R})$  and  $\lim_{n \rightarrow \infty} \|f_n - f\|_{L^p} = 0$ .*

## 8. Properties of the Lebesgue measure

**Theorem 8.1** (Change of variables formula). *Let  $\phi : U \rightarrow D$   $\mathcal{C}^1$  diffeomorphism. Then for all Borelian function  $f : D \rightarrow \mathbb{R}_+$  or integrable  $f \in \mathcal{L}^1(D, \lambda)$ , there holds*

$$\int_D f(x) dx = \int_U f[\phi(u)] |J_\phi(u)| du.$$

**Theorem 8.2** (Measure on the sphere). *Let  $\lambda_d$  be the Lebesgue measure  $\lambda_d$  on  $\mathbb{R}^d$ . (i) For every Borelian  $A \in \mathcal{B}(S^{d-1})$ ,*

$$w_d(A) = d\lambda_d[\Gamma(A)]$$

where  $\Gamma(A) = \{rz; z \in A, r \in [0, 1]\}$ , defines a finite measure on  $S^{d-1}$ , invariante by the linear isometries of  $\mathbb{R}^d$ , and with

$$w_d(S^{d-1}) = \frac{2\pi^{\frac{d}{2}}}{\Gamma(\frac{d}{2})}.$$

(ii) For every Borelian positive (or integrable) function  $f$  on  $\mathbb{R}^d$ , there holds

$$\int_{\mathbb{R}^d} f(x) d\lambda(x) = \int_0^\infty \int_{S^{d-1}} f(rx) r^{d-1} dr dw_d(z).$$

## 9. Random variables

9.1. **Basic definitions.** We fix once and for all  $(\Omega, \mathcal{A}, P)$  probability space.

**Definition 9.1** (Random variable). *Let  $(\Omega, \mathcal{A})$  and  $(E, \mathcal{E})$ . A measurable map  $X : (\Omega, \mathcal{A}) \rightarrow (E, \mathcal{E})$  is called a random variable with value in  $E$ . If  $E = \mathbb{R}$ , we speak of real random variable,*

**Definition 9.2** (Law). *The law of a random variable  $X$  is the probability image of  $P$  by  $X$ :*

$$\forall B \in \mathcal{E}, \quad P_X(B) = P(X \in B) = P(X^{-1}(B)).$$

**Remark 9.3.** If  $E$  is countable (ie the r.v is discrete), then

$$P_X = \sum_{x \in E} P(X = x) \delta_x$$

where  $\delta_x$  is for  $x \in E$  the measure

$$\forall B \in \mathcal{E}, \quad \delta_x(B) = \begin{cases} 1 & \text{if } x \in B \\ 0 & \text{otherwise} \end{cases}$$

**Definition 9.4** (Density of a r.v). A r.v with value in  $(\mathbb{R}^d, \mathcal{B}(\mathbb{R}^d))$  is said to have a law with density  $p$  if

$$dP_X = p(x)dx \Leftrightarrow \forall B \in \mathcal{E}, \quad P_X(B) = \int_B p(x)dx.$$

( $dx$  is Lebesgue)

**Definition 9.5** (Expectation). Let  $X$  be a real r.v. We define its expectation by

$$\mathbb{E}[X] = \int_{\Omega} X(w)P(dw).$$

**Proposition 9.6.** Let  $X$  be a r.v with value in  $(E, \mathcal{E})$  and  $f : (E, \mathcal{E}) \rightarrow [0, \infty]$ , then

$$\mathbb{E}[f(X)] = \int_E f(x)P_X(dx).$$

**Proposition 9.7** (Marginals). Let  $X = (X_1, \dots, X_d)$  be a r.v. with value in  $\mathbb{R}^d$ . Assume that the law of  $X$  has density  $p(x_1, \dots, x_d)$ , then  $\forall j \in \{1, \dots, d\}$ , the law of  $X_j$  has density

$$p_j(x) = \int_{\mathbb{R}^{d-1}} p(x_1, \dots, x_{j-1}, x, x_{j+1}, \dots, x_d) dx_1 \dots dx_{j-1} dx_{j+1} \dots dx_d.$$

## 9.2. Classical laws.

**Definition 9.8** (Discrete laws). The following are classical examples of discrete laws.

(i) Uniform law. Let  $E$  be a set with  $\#E = n$ , a r.v has uniform law if  $\forall x \in E$ ,  $P(X = x) = \frac{1}{n}$ .

(ii) Bernoulli. Let  $p \in [0, 1]$ , this is the law of a r.v  $X$  with value in  $\{0, 1\}$  such that

$$P(X = 1)p, \quad P(X = 0) = 1 - p.$$

It is interpreted as the result after one throw of a biased coin which falls on head with probability  $p$ .

(iii) Binomial  $\mathcal{B}(n, p)$ ,  $n \in \mathbb{N}^*$ ,  $p \in [0, 1]$  It is the law of a r.v with values in  $\{1, \dots, n\}$  such that

$$P(X = k) = (1 - p)p^k.$$

It is interpreted as the number of heads obtained after  $n$  throws of the biased coin.

(iv) Poisson's law of parameter  $\lambda > 0$ . It is the law of a r.v with value in  $\mathbb{N}$  and

$$P(X = k) = \frac{\lambda^k}{k!} e^{-\lambda}.$$

It corresponds to the number of rare events during a long period. Mathematically, if  $X_n$  follows the law  $\mathcal{B}(n, p_n)$  and  $np_n \rightarrow \lambda$  as  $n \rightarrow +\infty$ , then

$$\lim_{n \rightarrow \infty} P(X_n = k) = \frac{\lambda^k}{k!} e^{-\lambda}.$$

**Definition 9.9** (Continuous laws). *The following are classical examples of continuous laws. Let  $X$  be a r.v with value in  $\mathbb{R}$  and density  $p(x)$ .*

- (i) Uniform law on  $[a, b]$ ,  $a < b$ :  $p(x) = \frac{1}{b-a} \mathbf{1}_{[a,b]}(x)$ .
- (ii) Exponential law with parameter  $\lambda > 0$ :  $p(x) = \lambda e^{-\lambda x} \mathbf{1}_{\mathbb{R}_+}(x)$ . Exponential laws have the "no memory" property

$$P(X > a + b) = P(X > a)P(X > b).$$

- (iii) Gaussian law  $\mathcal{N}(m, \sigma^2)$ ,  $m \in \mathbb{R}$ ,  $\sigma > 0$ :

$$p(x) = \frac{1}{\sigma \sqrt{2\pi}} \exp\left(\frac{-(x-m)^2}{2\sigma^2}\right).$$

The parameters  $m, \sigma$  are interpreted as

$$m = \mathbb{E}[X], \quad \sigma^2 = \mathbb{E}[(X - m)^2].$$

By convention, we say that a r.v. constant equal to  $m$  follows the Gaussian law  $\mathcal{N}(m, 0)$ . If  $X$  follows  $\mathcal{N}(m, \sigma^2)$ ,

$$\forall \lambda, \mu \in \mathbb{R}, \quad \lambda X + \mu \text{ follows } \mathcal{N}(\lambda m + \mu, \lambda^2 \sigma^2).$$

### 9.3. Structural definitions.

**Definition 9.10** (Distribution function). *Let  $X$  be a real r.v, its distribution function is  $F_X : \mathbb{R} \rightarrow [0, 1]$  given by*

$$F_X(t) = P(X \leq t) = P_X(]-\infty, t]), \quad \forall t \in \mathbb{R}.$$

It is increasing, continuous on the right with  $\lim_{t \rightarrow -\infty} F_X(t) = 0$ ,  $\lim_{t \rightarrow +\infty} F_X(t) = 1$ . Moreover,

$$\left| \begin{array}{ll} P(a \leq X \leq b) = F_X(b) - F_X(a^-) & \text{for } a \leq b \\ P(a < X < b) = F_X(b^-) - F_X(a) & \text{for } a < b. \end{array} \right.$$

**Definition 9.11.** *Let  $X$  be a r.v valued in  $(E, \mathcal{E})$ , the  $\sigma$ -algebra generated by  $X$  is*

$$\sigma(X) = \{X^{-1}(B), \quad B \in \mathcal{E}\}.$$

If  $(X_i)_{i \in I}$  is a family of r.v valued in  $(E_i, \mathcal{E}_i)$ , the  $\sigma$ -algebra generated by the family is the smallest  $\sigma$ -algebra which makes all  $X_i$  measurable ie

$$\sigma[(X_i)_{i \in I}] = \sigma(\{X_i^{-1}(B_i), B_i \in \mathcal{E}_i\}).$$

**Proposition 9.12.** *Let  $X$  r.v valued in  $(E, \mathcal{E})$  and  $Y$  real r.v. TFAE:*

- (i)  $Y$  is  $\sigma(X)$  measurable;
- (ii) there exists  $f : (E, \mathcal{E}) \rightarrow (\mathbb{R}, \mathcal{B}(\mathbb{R}))$  measurable such that  $Y = f(X)$ .

#### 9.4. Moments and variance.

**Remark 9.13.** Theorems of integration in probabilistic language:

- (i) Monotone convergence:  $X_n \geq 0, X_n \uparrow X \Rightarrow \mathbb{E}(X_n) \uparrow \mathbb{E}(X)$ .
- (ii) Fatou:  $X_n \geq 0 \Rightarrow \mathbb{E}[\liminf X_n] \leq \liminf \mathbb{E}[X_n]$ .
- (iii) Lebesgue:  $|X_n| \leq Z, \mathbb{E}[Z] < +\infty, X_n \rightarrow X$  a.e  $\Rightarrow \mathbb{E}[X_n] \rightarrow \mathbb{E}[X]$ .
- (iv) Hölder:  $\mathbb{E}[|XY|] \leq (\mathbb{E}[|X|^p])^{\frac{1}{p}} (\mathbb{E}[|X|^{p'}])^{\frac{1}{p'}}$  for  $\frac{1}{p} + \frac{1}{p'} = 1, 1 \leq p, p' \leq +\infty$ .
- (v)  $L^p$  embeddings:  $\|X\|_r \leq \|X\|_p$  for  $1 \leq r \leq p \leq +\infty$ .

**Definition 9.14** (variance). *Let  $X \in L^2(\Omega, \mathcal{A}, P)$ . The variance is*

$$\text{var}(X) = \mathbb{E}[(X - \mathbb{E}[X])^2]$$

and the standard deviation is

$$\sigma_X = \sqrt{\text{var}(X)}.$$

**Lemma 9.15.**  $\text{var}(X) = \inf_{a \in \mathbb{R}} \mathbb{E}[(X - a)^2]$ .

**Remark 9.16.** Classical inequalities in probabilistic language:

- (i) Markov:  $P(X \geq a) \leq \frac{\mathbb{E}[X]}{a}$ .
- (ii) Bienayme-Tchebicheff: if  $X \in L^2(\Omega, \mathcal{A}, P)$ ,  $P(|X - \mathbb{E}(X)| \geq a) \leq \frac{\text{var}(X)}{a^2}$ .

**Definition 9.17** (covariance). *Let  $X, Y \in L^2(\Omega, \mathcal{A}, P)$ , their covariance is*

$$\text{cov}(X, Y) = \mathbb{E}[(X - \mathbb{E}[X]) \mathbb{E}[(Y - \mathbb{E}[Y])]] = [XY] - \mathbb{E}[X]\mathbb{E}[Y].$$

If  $X = (X_1, \dots, X_d)$  has coordinates in  $X_i \in L^2(\Omega, \mathcal{A}, P)$ , then the matrix covariance is

$$K_X = (\text{cov}(X_i, X_j))_{1 \leq i, j \leq n}.$$

**Proposition 9.18** (Linear regression). *Let  $(X, Y_1, \dots, Y_n)$  be real r.v in  $L^2(\Omega, \mathcal{A}, P)$ .*

*Then*

$$\inf_{\beta_0, \dots, \beta_n \in \mathbb{R}} \mathbb{E}[(X - (\beta_0 + \beta_1 Y_1 + \dots + \beta_n Y_n))^2] = \mathbb{E}[(X - Z)^2]$$

where

$$Z = \mathbb{E}[X] + \sum_{j=1}^n \alpha_j (Y_j - \mathbb{E}[Y_j])$$

and  $(\alpha_j)_{1 \leq j \leq n}$  is any solution to the system

$$\sum_{j=1}^n \alpha_j \text{cov}(Y_j, Y_k) = \text{cov}(X, Y_k), \quad 1 \leq k \leq n.$$

#### 9.5. Characteristic function.

**Definition 9.19.** *Let  $f \in L^1(\mathbb{R}^d)$ , we let  $\hat{f}(\xi) = \int_{\mathbb{R}^d} e^{-ix \cdot \xi} f(x) dx$ .*

**Lemma 9.20** (Inverse Fourier transform). *Let  $f \in \mathcal{C}_c^\infty(\mathbb{R}^d)$ , then*

$$f(x) = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} e^{ix \cdot \xi} \hat{f}(\xi) d\xi.$$

**Lemma 9.21** (Plancherel). *Let  $f, g \in \mathcal{C}_c^\infty(\mathbb{R}^d)$ , then*

$$\int_{\mathbb{R}^d} f(x) \overline{g(x)} dx = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} \hat{f}(\xi) \overline{\hat{g}(\xi)} d\xi.$$

This allows us to uniquely extend the Fourier as a continuous isomorphism of  $L^2$ .

**Definition 9.22** (Characteristic function). *Let  $X$  be a r.v valued in  $\mathbb{R}^d$ , its characteristic function is the function  $\Phi_X : \mathbb{R}^d \rightarrow \mathbb{C}$  defined by*

$$\Phi_X(\xi) = \mathbb{E} \left[ e^{ix \cdot \xi} \right] = \int_{\mathbb{R}^d} e^{ix \cdot \xi} P_X(dx).$$

**Lemma 9.23** (Characteristic function of one dimensional Gaussian). *Let  $X$  be a real r.v with law  $\mathcal{N}(0, \sigma^2)$ , then*

$$\Phi_X(\xi) = e^{-\frac{\sigma^2 \xi^2}{2}}.$$

**Theorem 9.24.** *The characteristic function of a r.v valued in  $\mathbb{R}^d$  characterizes the law of this r.v. Equivalently, the Fourier transform defined on the space of probability measure on  $\mathbb{R}^d$  is injective.*

The proof relies on the following (density related) statement.

**Proposition 9.25.** *Let  $\mu, \nu$  be two probability measures on  $\mathbb{R}^d$ . Assume that for all test function  $\phi \in \mathcal{C}_b(\mathbb{R}^d)$  (ie continuous bounded and real valued),*

$$\int_{\mathbb{R}^d} \phi d\mu = \int_{\mathbb{R}^d} \phi d\nu$$

*then  $\mu = \nu$ .*

**Proposition 9.26.** *Let  $X = (X_1, \dots, X_n)$  r.v valued in  $\mathbb{R}^d$  and square integrable. Then  $\Phi_X$  is  $\mathcal{C}^2$  and*

$$\Phi_X(\xi) = 1 + i \sum_{j=1}^n \xi_j \mathbb{E}[X_j] - \frac{1}{2} \sum_{j=1}^d \sum_{k=1}^d \xi_j \xi_k \mathbb{E}[X_j X_k] + o(|\xi|^2).$$

**Definition 9.27** (Generating function). *Let  $X$  r.v valued in  $\mathbb{N}$ . The generating function of  $X$  is the function  $g_X : [0, 1] \rightarrow \mathbb{R}_+$  given by*

$$g_X(r) = \mathbb{E}[r^X] = \sum_{n \geq 0} P(X = n) r^n.$$

## 10. Independance

### 10.1. Definitions.

**Definition 10.1** (Independance of events). *We say  $n$  events  $A_1, \dots, A_n$  are independent iff for all  $\{j_1, \dots, j_p\} \subset \{1, \dots, n\}$ ,*

$$P(A_{j_1} \cap \dots \cap A_{j_p}) = P(A_{j_1}) \dots P(A_{j_p}).$$

**Lemma 10.2.** *The  $n$  events  $A_1, \dots, A_n$  are independent iff*

$$P(B_1 \cap \dots \cap B_n) = P(B_1) \dots P(B_n)$$

*whenever  $B_i \in \sigma(A_i) \equiv \{\emptyset, A_i, A_i^c, \Omega\}$ ,  $\forall i \in \{1, \dots, n\}$ .*

**Definition 10.3** (Independance of tribes). *Let  $\mathcal{B}_1, \dots, \mathcal{B}_n$  be sub  $\sigma$ -algebra of  $\mathcal{A}$ . We say they are independent iff*

$$\forall A_1 \in \mathcal{B}_1, \dots, A_n \in \mathcal{B}_n, \quad P(A_1 \cap \dots \cap A_n) = P(A_1) \dots P(A_n).$$

**Definition 10.4** (Independance of re.v). *Let  $X_1, \dots, X_n$  be r.v with values in  $(E_1, \mathcal{E}_1), \dots, (E_n, \mathcal{E}_n)$ . We say they are independent iff*

$$\forall F_1 \in \mathcal{E}_1, \dots, F_n \in \mathcal{E}_n, \quad P(\{X_1 \in F_1\} \cap \dots \cap \{X_n \in F_n\}) = P(X_1 \in F_1) \dots P(X_n \in F_n).$$

**Remark 10.5.** (i) Let  $\mathcal{B}_1, \dots, \mathcal{B}_n$  family of independent sub  $\sigma$ -algebra, then if  $X_i$   $\mathcal{B}_i$ -measurable r.v, then  $(X_1, \dots, X_n)$  are independent.

(ii) Events  $A_1, \dots, A_n$  are independent iff the sub  $\sigma$ -algebra  $(\sigma(A_1), \dots, \sigma(A_n))$  are.

**Definition 10.6.** Let  $(\mathcal{B}_i)_{i \in I}$  an arbitrary family of sub  $\sigma$ -algebra, we say that the family is independent iff  $\forall \{i_1, \dots, i_p\}$ ,  $(\mathcal{B}_1, \dots, \mathcal{B}_{i_p})$  are independent. We say a an arbitrary family  $(X_i)_{i \in I}$  of r.v is independent iff  $(\sigma(X_i))_{i \in I}$  is.

**Corollary 10.7.** Let  $(X_n)_{n \in \mathbb{N}}$  a family of independent r.v, then  $\forall p \geq 1$ ,

$$\mathcal{B}_1 = \sigma(X_1, \dots, X_p), \quad \mathcal{B}_2 = \sigma(X_{p+1}, X_{p+2}, \dots)$$

are independent.

## 10.2. Characterization of independance.

**Theorem 10.8** (Characterization with law). The r.v  $(X_1, \dots, X_n)$  are independent iff the law of  $X = (X_1, \dots, X_n)$  is the product of the law of the  $X_i$ 's:

$$P_X = P_{X_1} \otimes \dots \otimes P_{X_n}.$$

In this case, for all  $f_i \geq 0$  measurable on  $(E_i, \mathcal{E}_i)$ ,  $1 \leq i \leq n$ :

$$\mathbb{E} \left[ \prod_{i=1}^n f_i(X_i) \right] = \prod_{i=1}^n \mathbb{E} [f_i(X_i)].$$

**Corollary 10.9.** Let  $X_1, X_2$  be two  $L^2$  integrable r.v, then  $\text{cov}(X_1, X_2) = 0$ .

**Theorem 10.10** (Characterization with densities). Let  $(X_1, \dots, X_n)$  real r.v.

(i) Assume that  $\forall i \in \{1, \dots, n\}$ , the law of  $X_i$  has density  $p_i$ , and  $(X_1, \dots, X_n)$  are independant. Then the law of  $X = (X_1, \dots, X_n)$  is

$$p(x_1, \dots, x_n) = \prod_{i=1}^n p_i(x_i).$$

(ii) Conversely, assume that the law of  $X = (X_1, \dots, X_n)$  has a density of the form

$$p(x_1, \dots, x_n) = \prod_{i=1}^n q_i(x_i)$$

for some Borelian positive functions  $q_i$ . Then  $(X_1, \dots, X_n)$  are independant and  $\forall i \in \{1, \dots, n\}$ , the law of  $X_i$  has density  $p_i = C_i p_i$  for some constant  $C_i > 0$ .

**Remark 10.11.** Let  $(X_1, \dots, X_n)$  real r.v, then TFAE:

(i)  $(X_1, \dots, X_n)$  are independent.

(ii)  $\forall a_1, \dots, a_n \in \mathbb{R}$ ,  $P(X_1 \leq a_1, \dots, X_n \leq a_n) = \prod_{i=1}^n P(X_i \leq a_i)$ .

(iii) For all  $f_1, \dots, f_n$  continuous bounded from  $\mathbb{R}$  to  $\mathbb{R}_+$ ,  $\mathbb{E} \left[ \prod_{i=1}^n f_i(X_i) \right] = \prod_{i=1}^n \mathbb{E} [f_i(X_i)]$ .

(iv) The characteristic function of  $X = (X_1, \dots, X_n)$  is  $\Phi_X(\xi_1, \dots, \xi_n) = \prod_{i=1}^n \Phi_{X_i}(\xi_i)$ .

**Proposition 10.12.** Let  $\mathcal{B}_1, \dots, \mathcal{B}_n$  be sub  $\sigma$ -algebra of  $\mathcal{A}$ . Assume:

(i)  $\forall i \in \{1, \dots, n\}$ , there exists  $\mathcal{C}_i \subset \mathcal{B}_i$  monotone class stable by finite intersection with  $\sigma(\mathcal{C}_i) = \mathcal{B}_i$ ;

(ii)  $\forall C_1 \in \mathcal{C}_1, \dots, C_n \in \mathcal{C}_n$ ,  $P(C_1 \cap \dots \cap C_n) = P(C_1) \dots P(C_n)$ .

Then  $\mathcal{B}_1, \dots, \mathcal{B}_n$  are independent.

**Corollary 10.13** (Regrouping). Let  $\mathcal{B}_1, \dots, \mathcal{B}_n$  independent sub  $\sigma$ -algebra. Then for all  $0 < n_1 < \dots < n_p = n$ , the sub  $\sigma$ -algebra

$$\left| \begin{array}{l} \mathcal{D}_1 = \mathcal{B}_1 \vee \dots \vee \mathcal{B}_{n_1} \equiv \sigma(\mathcal{B}_1 \vee \dots \vee \mathcal{B}_{n_1}) \\ \mathcal{D}_2 = \mathcal{B}_{n_1+1} \vee \dots \vee \mathcal{B}_{n_2} \\ \dots \\ \mathcal{D}_p = \mathcal{B}_{n_{p-1}+1} \vee \dots \vee \mathcal{B}_{n_p} \end{array} \right.$$

are independent.

**Corollary 10.14.** *If  $(X_1, \dots, X_n)$  are independent, then the r.v*

$$Y_1 = (X_1, \dots, X_{n_1}), \dots, Y_p = (X_{n_{p-1}+1}, \dots, X_{n_p})$$

*are also independent.*

**Definition 10.15** (Independance for an infinite family). (i) *Let  $(\mathcal{B}_i)_{i \in I}$  be an arbitrary sub family of tribes of  $\mathcal{A}$ . We say that this family is independent if for all  $\{i_1, \dots, i_p\}$ ,  $(\mathcal{B}_{i_1}, \dots, \mathcal{B}_{i_p})$  is an independent family.*

(ii) *We say an arbitrary family  $(X_i)_{i \in I}$  is independent of the family of tribes  $(\sigma(X_i))_{i \in I}$  is.*

**Proposition 10.16.** *Let  $(X_n)_{n \geq 1}$  be a family of independent r.v. Then for all integer  $p \in \mathbb{N}$ , the tribes  $\mathcal{B}_1 = \sigma(X_0, \dots, X_p)$  and  $\mathcal{B}_2 = \sigma(X_{p+1}, X_{p+2}, \dots)$  are independent.*

### 10.3. Borel Cantelli.

**Lemma 10.17** (Borel Cantelli). *Let  $(A_n)_{n \in \mathbb{N}}$  a family of events, and define*

$$\begin{cases} \limsup A_n = \bigcap_{n=0}^{\infty} (\bigcup_{k=n}^{\infty} A_k) \\ \liminf A_n = \bigcup_{n=0}^{\infty} (\bigcap_{k=n}^{\infty} A_k) \end{cases}$$

(i) *If  $\sum_{n \in \mathbb{N}} P(A_n) < +\infty$ , then  $P(\limsup A_n) = 0$ . Equivalently,*

$$\text{a.s, } \{n \in \mathbb{N}, w \in A_n\} \text{ is finite.}$$

(ii) *If  $\sum_{n \in \mathbb{N}} P(A_n) = +\infty$  and the events  $A_n$  are independent, then  $P(\limsup A_n) = 1$ . Equivalently,*

$$\text{a.s, } \{n \in \mathbb{N}, w \in A_n\} \text{ is infinite.}$$

### 10.4. Sum of independent random variables.

**Definition 10.18** (Convolution of measures). *Let  $\mu, \nu$  be two probability measures on  $\mathbb{R}^d$ , then  $\mu \star \nu$  is the image of  $\mu \otimes \nu$  by the map  $(x, y) \rightarrow x + y$ . Equivalently, for any positive measurable  $\phi$ :*

$$\int_{\mathbb{R}^d} \phi(z) \mu \star \nu(dz) = \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \phi(x + y) \nu(dx) \nu(dy).$$

**Proposition 10.19.** *Let  $X, Y$  be two independent r.v with value in  $\mathbb{R}^d$ .*

- (i) *The law of  $X + Y$  is  $P_X \star P_Y$ . In particular, if  $P_X$  has density  $p_X$  and  $P_Y$  has density  $p_Y$ , then  $P_{X+Y}$  has density  $p_X \star p_Y$ .*
- (ii) *The characteristic function of  $X + Y$  is  $\Phi_{X+Y}(\xi) = \Phi_X(\xi) \Phi_Y(\xi)$ . (Equivalently, if  $\mu, \nu$  are two probability measures on  $\mathbb{R}^d$ , then  $\widehat{\mu \star \nu} = \widehat{\mu} \widehat{\nu}$ ).*
- (iii) *If  $X, Y$  are square integrable, then  $K_{X+Y} = K_X + K_Y$ . In particular, for  $d = 1$ ,  $\text{var}(X + Y) = \text{var}(X) + \text{var}(Y)$ .*

**Theorem 10.20** (Weak law of large numbers). *Let  $(X_n)_{n \geq 1}$  be a family of real valued independent r.v with same law. If  $E(X_1^2) < +\infty$ , then*

$$\frac{X_1 + \dots + X_n}{n} \xrightarrow[n \rightarrow \infty]{L^2} \mathbb{E}[X_1].$$

**Proposition 10.21.** *Let  $(X_n)_{n \geq 1}$  be a family of real valued independent r.v with same law. If  $\mathbb{E}(X_1^4) < +\infty$ , then*

$$\text{a.s } \frac{X_1 + \dots + X_n}{n} \rightarrow \mathbb{E}[X_1].$$

**Definition 10.22** (Convolution semi group). *A family of probability measures  $(\mu_t)_{t \in I}$  is said to be a convolution semi group if*

$$\left| \begin{array}{l} \mu_0 = \delta_0 \\ \mu_t \star \mu_{t'} = \mu_{t+t'}, \quad \forall t, t' \in I \end{array} \right.$$

**Lemma 10.23.** *For  $(\mu_t)_{t \in I}$  to be a convolution semi group, it is enough that:*

- (i) *if  $I = \mathbb{N}$ ,  $\hat{\mu}_t(\xi) = [\phi(\xi)]^t$ ,  $\forall t \in I$ .*
- (ii) *if  $I = \mathbb{R}$ ,  $\hat{\mu}_t(\xi) = e^{-t\phi(\xi)}$ ,  $\forall t \in I$ .*

**Examples.**

- (i) For  $I = \mathbb{N}$  and  $n > 0$ , let  $\mu_n$  be the binomial law  $B(n, p)$  (where  $p \in [0, 1]$  has been fixed), then  $\mu_{n+m} = \mu_n \star \mu_m$  can be seen by computing  $\hat{\mu}_n(\xi) = (pe^{i\xi} + 1 - p)^n$ .
- (ii) For  $I = \mathbb{R}_+$ ,  $t \in \mathbb{R}_+$ , let  $\mu_t$  be the Poisson law of parameter  $t$ , then

$$\hat{\mu}_t(\xi) = \sum_{k=0}^{+\infty} \frac{t^k}{k!} e^{ik\xi} e^{-t} = e^{-t(1-e^{i\xi})},$$

- (iii) For  $I = \mathbb{R}_+$ ,  $t > 0$ , let  $\mu_t$  be the Gaussian law  $\mathcal{N}(0, t)$ , then

$$\hat{\mu}_t(\xi) = e^{-\frac{t\xi^2}{2}}.$$

**Important consequences.** Let  $X, Y$  be two independent real r.v.

- (i) If  $X$  follows Poisson of parameter  $\lambda$  and  $Y$  follows Poisson of parameter  $\lambda'$ , then  $X + Y$  follows Poisson of parameter  $\lambda + \lambda'$ .
- (ii) If  $X$  follows the Gaussian law  $\mathcal{N}(m, \sigma^2)$  and  $X'$  follows the Gaussian law  $\mathcal{N}(m', (\sigma')^2)$ , then  $X + X'$  follows the Gaussian law  $\mathcal{N}(m + m', \sigma^2 + (\sigma')^2)$ .

## 11. Convergence of random variables

11.1. **Convergence in probability.** We have already introduced

$$X_n \xrightarrow[n \rightarrow \infty]{a.s.} X \Leftrightarrow P\left(\{x \in \Omega : \lim_{n \rightarrow \infty} X_n(w) = X(x)\}\right) = 1$$

and for  $1 \leq p < +\infty$

$$X_n \xrightarrow[n \rightarrow \infty]{L^p} X \Leftrightarrow \lim_{n \rightarrow \infty} \mathbb{E}[|X - X_n|^p] = 0.$$

**Definition 11.1** (Convergence in probability). *We say  $X_n$  converges to  $X$  in probability*

$$X_n \xrightarrow[n \rightarrow \infty]{(P)} X$$

*if*

$$\forall \varepsilon > 0, \quad \lim_{n \rightarrow \infty} P(|X_n - X| > \varepsilon) = 0.$$

**Proposition 11.2** (Completeness). *Let  $\mathcal{L}_{\mathbb{R}^d}^0(\Omega, \mathcal{A}, P)$  be the quotient of the space of all r.v with value in  $\mathbb{R}^d$  quotiented by the equivalence relation  $X \sim Y \Leftrightarrow X = Y$  a.s.. Then:*

- (i)  $d(X, Y) = \mathbb{E}[|X - Y| \wedge 1]$  defines a distance on  $\mathcal{L}_{\mathbb{R}^d}^0(\Omega, \mathcal{A}, P)$ , and this metric space is complete.
- (ii)  $\lim_{n \rightarrow \infty} d(X_n, X) = 0 \Leftrightarrow X_n \xrightarrow[n \rightarrow \infty]{(P)} X$ .

**Lemma 11.3.** *If  $X_n$  converges a.s to  $X$  (or in  $L^p$ ), then it also converges in probability. Conversely, if  $X_n$  converges in probability to  $X$ , then there exists a subsequence  $X_{n_k}$  which converges a.s to  $X$ .*

### 11.2. Strong law of large numbers.

**Theorem 11.4** (Kolmogorov's 0-1 law). *Let  $(X_n)_{n \geq 1}$  be a sequence of independent r.v. Let for  $n \geq 1$*

$$\mathcal{B}_n = \sigma(X_k, k \geq n),$$

*then the asymptotic tribe*

$$\mathcal{B}_\infty = \cap_{n \geq 1} \mathcal{B}_n$$

*is rough in the sense that*

$$\forall B \in \mathcal{B}_\infty, \quad P(B) \in \{0, 1\}.$$

**Theorem 11.5** (Strong law of large numbers, a.e version). *Let  $(X_n)_{n \geq 1}$  be a sequence of real independent r.v. with same law and  $\mathbb{E}[|X_1|] < +\infty$ , then*

$$\frac{X_1 + \dots + X_n}{n} \xrightarrow[n \rightarrow \infty]{a.s.} \mathbb{E}[X_1].$$

### 11.3. Convergence in law.

**Definition 11.6** (Test function). (i) *We let  $\mathcal{C}_b(\mathbb{R}^d)$  be the space of continuous bounded functions from  $\mathbb{R}^d \rightarrow \mathbb{R}$  equipped with the sup norm*

$$\|\phi\|_{L^\infty} = \sup_{x \in \mathbb{R}^d} |\phi(x)|.$$

(ii) *We let  $\mathcal{C}_c(\mathbb{R}^d)$  the subset of  $\mathcal{C}_b(\mathbb{R}^d)$  of continuous functions with compact support (where we recall  $\text{Supp}(f) = \overline{\{x \in \mathbb{R}^d, f(x) \neq 0\}}$ .)*

**Definition 11.7** (Convergence in law). (i) *We say a sequence  $(\mu_n)_{n \geq 1}$  of probability measures over  $\mathbb{R}^d$  converges in distribution to a probability measure  $\mu$  ( $\mu_n \xrightarrow[n \rightarrow \infty]{(D)} \mu$ ) iff*

$$\forall \phi \in \mathcal{C}_b(\mathbb{R}^d), \quad \lim_{n \rightarrow \infty} \int \phi d\mu_n = \int \phi d\mu.$$

(ii) *We say a sequence of r.v.  $(X_n)_{n \geq 1}$  with value in  $\mathbb{R}^d$  converges in law (or in distribution) to  $X$  iff  $P_{X_n} \xrightarrow[n \rightarrow \infty]{(D)} P_X$ . Equivalently,*

$$\forall \phi \in \mathcal{C}_b(\mathbb{R}^d), \quad \lim_{n \rightarrow \infty} \mathbb{E}[\phi(X_n)] = \mathbb{E}[\phi(X)].$$

**Lemma 11.8.** *Let  $(\mu_n, \mu)$  be probability measures on  $\mathbb{R}^d$ . TFAE:*

- (i)  $\mu_n \xrightarrow[n \rightarrow \infty]{(D)} \mu$ ;
- (ii)  $\forall G$  open,  $\liminf \mu_n(G) \geq \mu(G)$ ;
- (iii)  $\forall F$  closed,  $\limsup \mu_n(F) \leq \mu(F)$ ;
- (iv)  $\forall B$  Borelian with  $\mu(\partial B) = 0$ ,  $\lim_{n \rightarrow \infty} \mu_n(B) = \mu(B)$  where  $\partial B = \overline{B} \setminus \mathring{B}$ .

**Proposition 11.9.** *A sequence of r.v.  $(X_n)_{n \geq 1}$  with value in  $\mathbb{R}^d$  converges in law to  $X$  iff the distribution functions  $F_{X_n}(x)$  converges to  $F_X(x)$  at every point  $x$  where  $F_X$  is continuous.*

**Proposition 11.10** (Weakening test functions). *Let  $(\mu_n)_{n \geq 1}, \mu$  be probability measures over  $\mathbb{R}^d$ . Let  $H$  be a subspace of  $\mathcal{C}_b(\mathbb{R}^d)$  which closure (for the sup norm) contains  $\mathcal{C}_c(\mathbb{R}^d)$ . Then TFAE:*

- (i)  $\mu_n \xrightarrow[n \rightarrow \infty]{(D)} \mu$ .
- (ii)  $\forall \phi \in \mathcal{C}_c(\mathbb{R}^d), \lim_{n \rightarrow \infty} \int \phi d\mu_n = \int \phi d\mu$ .
- (iii)  $\forall \phi \in H, \lim_{n \rightarrow \infty} \int \phi d\mu_n = \int \phi d\mu$ .

**Theorem 11.11** (Levy). (i) A sequence of probability measures  $(\mu_n)_{n \geq 1}$  converges in distribution to a probability measure  $\mu$  iff

$$\forall \xi \in \mathbb{R}^d, \quad \lim_{n \rightarrow \infty} \widehat{\mu_n}(\xi) = \widehat{\mu}(\xi).$$

(ii) A sequence of r.v.  $(X_n)_{n \geq 1}$  with value in  $\mathbb{R}^d$  converges in law (or in distribution) to  $X$  iff

$$\forall \xi \in \mathbb{R}^d, \quad \lim_{n \rightarrow \infty} \Phi_{X_n}(\xi) = \Phi_X(\xi).$$

#### 11.4. Central limit theorem.

**Theorem 11.12** (Scalar central limit theorem). Let  $(X_n)_{n \geq 1}$  be a sequence of real r.v independent with same law,  $X_1 \in L^2$ . Let  $\sigma^2 = \text{var}(X_1)$ , then

$$\frac{X_1 + \cdots + X_n - n\mathbb{E}[X_1]}{\sqrt{n}} \xrightarrow[n \rightarrow \infty]{\text{(law)}} \mathcal{N}(0, \sigma^2).$$

Equivalently,  $\forall a < b$ ,

$$\lim_{n \rightarrow \infty} \mathbb{P}(X_1 + \cdots + X_n \in (n\mathbb{E}[X_1] + a\sqrt{n}, n\mathbb{E}[X_1] + b\sqrt{n})) = \frac{1}{\sigma\sqrt{2\pi}} \int_a^b e^{-\frac{x^2}{2\sigma^2}} dx.$$

**Definition 11.13** (Gaussian centered vector). Let  $C$  be a square  $d \times d$  symmetric positive matrix, with real valued entries. A square integrable r.v valued in  $\mathbb{R}^d$  is said to be a centered Gaussian vector with covariance  $C$  if

$$\forall \xi \in \mathbb{R}^d, \quad \Phi_X(\xi) = e^{-\frac{1}{2}\xi^t C \xi}.$$

We also say that  $X$  follows the law  $\mathcal{N}(0, C)$ .

**Remark 11.14.**  $X \sim \mathcal{N}(0, C) \Rightarrow (\mathbb{E}[X] = 0, K_X = C)$ .

**Lemma 11.15** (Existence of Gaussian centered vectors). Let  $A = \sqrt{C}$  and  $(Y_i)_{1 \leq i \leq d}$  independent real r.v following the law  $\mathcal{N}(0, 1)$ , then  $X = AY$  follows  $\mathcal{N}(0, C)$ .

**Theorem 11.16** (Vectorial central limit theorem). Let  $(X_n)_{n \geq 1}$  be a sequence of r.v valued in  $\mathbb{R}^d$  independent with same law,  $X_1 \in L^2$ ,  $C = K_{X_1}$ , then

$$\frac{X_1 + \cdots + X_n - n\mathbb{E}[X_1]}{\sqrt{n}} \xrightarrow[n \rightarrow \infty]{\text{(law)}} \mathcal{N}(0, C).$$

## 12. Ergodic theory

### 12.1. Basic results.

**Definition 12.1.** Let  $(E, \mathcal{E}, \Gamma)$  be a measure space.

(i) A map  $\theta : E \rightarrow E$  is called measure preserving if:  $\forall A \in \mathcal{E}, \quad \Gamma(\theta^{-1}(A)) = \Gamma(A)$ . In this case,

$$\forall f \in L^1, \quad \int_E f d\Gamma = \int_E f \circ \theta d\Gamma.$$

(ii) A measurable function  $f$  is called  $\theta$ -invariant if  $f = f \circ \theta$ .

(iii) A set  $A \in \mathcal{E}$  is called  $\theta$ -invariant if  $\theta^{-1}(A) = A$ . The family  $\mathcal{E}_\theta$  of  $\theta$ -invariant sets is a  $\sigma$ -algebra and  $f$  invariant iff  $f$  is  $\mathcal{E}_\theta$ -measurable.

**Definition 12.2.** The map  $\theta$  is called ergodic if

$$A \in \mathcal{E}_\theta \Rightarrow (\Gamma(A) = 0 \text{ or } \Gamma(E \setminus A) = 0).$$

**Remark 12.3.**  $f$   $\theta$ -invariant for  $\theta$  ergodic implies  $f$  constant  $\Gamma$ -a.e.

**Theorem 12.4** (Birkhoff). *Let  $(E, \mathcal{E}, \Gamma)$  be  $\sigma$ -finite,. Let  $\theta$  be a measure preserving map. Given  $f \in L^1$ , let*

$$\begin{cases} S_0(f) = 0 \\ S_n(f) = \sum_{k=0}^{n-1} f \circ \theta^k, \end{cases}$$

*then  $\exists \bar{f} \in L^1$   $\theta$ -invariant such that*

$$\frac{S_n(f)}{n} \xrightarrow[n \rightarrow \infty]{} \bar{f} \quad \Gamma \text{ a.e.}$$

**Lemma 12.5** (Ergodic Lemma). *Under the assumptions of Birkhoff's theorem, let  $S^*(f) = \sup_{n \geq 0} S_n(f)$ , then*

$$\int_{S^*(f) > 0} f d\Gamma \geq 0.$$

**Theorem 12.6** (Von Neumann's). *Assume  $\Gamma(E) < +\infty$ . Pick  $1 \leq p < +\infty$ ,  $\theta$ -meaure preserving and  $f \in L^p$ . Then*

$$\frac{S_n(f)}{n} \xrightarrow[n \rightarrow \infty]{L^p} \bar{f}$$

*for some  $\bar{f} \in L^p$   $\theta$ -invariant.*

12.2. **Application to iid.** Consider the infinite product space

$$E = \mathbb{R}^{\mathbb{N}} = \{(x_n)_{n \geq 1}, x_n \in \mathbb{R}\}$$

equipped with the cylindrical  $\sigma$ -algebra  $\sigma(\mathcal{C})$  generated by cylinders

$$\mathcal{C} = \{A = \prod_{n=1}^{+\infty} A_n, A_n \in \mathcal{B}, A_n = \mathbb{R} \text{ for some } n \geq N\}.$$

Given  $(X_n)_{n \geq 1}$  real valued independent r.v on  $(\Omega, \mathcal{F}, \mathbb{P})$  with law  $m$ , the map

$$X : \Omega \rightarrow E, \quad X(w) = (X_1(w), X_2(w), \dots)$$

is measurable and the image measure  $\Gamma = P_X$  is the unique measure  $\sigma(\mathcal{C})$  satisfying

$$\Gamma(\prod_{n=1}^{+\infty} A_n) = \prod_{n=1}^{+\infty} m(A_n).$$

**Definition 12.7.** *The product space  $(E = \mathbb{R}^{\mathbb{N}}, \sigma(\mathcal{C}), \Gamma)$  is called the canonical model associated to the sequence of iid  $X(n)_{n \geq 0}$ .*

**Lemma 12.8.** *The shift map*

$$\theta : E \rightarrow E, \quad \theta(x_1, x_2, \dots) = (x_2, x_3, \dots)$$

*is  $\Gamma$ -measure preserving and ergodic.*

By applying Von Neuman to

$$f : E \rightarrow \mathbb{R}, \quad f(x) = x_1,$$

we obtain the  $L^1$  version of the strong law of large numbers.

**Theorem 12.9** (Strong Law of Large Numbers,  $L^1$  version). *Let  $(X_n)_{n \geq 1}$  be real valued independent r.v with same law and  $\mathbb{E}[|X_1|] < +\infty$ , then*

$$\mathbb{E} \left[ \left| \frac{X_1 + \dots + X_n}{n} - \mathbb{E}[X_1] \right| \right] \xrightarrow[n \rightarrow \infty]{} 0.$$