

Q1) Only point at issue is the fact that  $\rho(P, Q) \neq 0$  for  $P \neq Q$ . This is proved as in Ch 4 of my book (in case  $n=2$ ) - w/ local coords, metric given as  $\sum g_{ij} dx_i \otimes dx_j$  for some +ve def symmetric matrix of functions  $(g_{ij})$ . So locally in some Euclidean ball  $B(\phi(P), \delta)$  in image of chart  $\phi$ ,  $\exists \epsilon^2 > 0$  s.t.  $g_{ij} - \epsilon^2 \delta_{ij}$  still +ve def. So if  $d(P, Q)$  denotes the Euclidean length (on image of chart  $\phi$ ), easy argument shows  $\rho(P, Q) \geq \epsilon \min\{\delta, d(P, Q)\} > 0$ .

Q2)  $M^m \hookrightarrow N^n$ . Locally have coords  $x_1, \dots, x_n$  on  $U \subset N$  s.t.  $M \cap U$  given by  $x_{m+1} = \dots = x_n = 0$ .

So  $TN$  locally trivialized by  $\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_n}$  with local sections  $\sum f_i \frac{\partial}{\partial x_i}$ ,  $f_i \in \mathcal{A}(U)$

Have  $TN|_M = \pi^{-1}(M) \subset TN$

$$\begin{array}{ccc} \downarrow & & \downarrow \pi \\ M & \subset & N \end{array}$$

locally trivialized (on  $U \cap M$ ) by  $\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_m}$  (or  $\frac{\partial}{\partial x_i}|_M$ ) with local sections of form

$\sum g_i \frac{\partial}{\partial x_i}$ , with  $g_i \in \mathcal{C}(U \cap M)$ .

Note that inclusion  $M \subset N$  induces an inclusion of  $TM$  as a subbundle of  $TN|_M$  and since  $M$  has local words  $x_1, \dots, x_m$  & hence  $TM$  locally trivialized by  $\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_m}$ , the inclusion is the obvious one).

Now any local section  $X$  of  $TN|_M$  over  $V \subset M$ , say  $\sum g_j \frac{\partial}{\partial x_j}$ , extends to a local section

$\tilde{X} = \sum f_j \frac{\partial}{\partial x_j}$  of  $TN$  over some  $U \subset N$  with  $U \cap M = V$ .

We define  $\nabla_i(X) = \nabla_i(\tilde{X})|_M$  - this is well-defined:

if  $Z = \sum f_j \frac{\partial}{\partial x_j}$  is zero on  $M$ , i.e. all the  $f_j$  vanish on  $M \cap U = V$ , then

$$\begin{aligned} \nabla_i(Z) &= \nabla_i\left(\sum_j f_j \frac{\partial}{\partial x_j}\right) = \sum_j \frac{\partial f_j}{\partial x_i} \frac{\partial}{\partial x_j} + \sum_j f_j \nabla_i\left(\frac{\partial}{\partial x_j}\right) \\ &= 0 \text{ on } V = M \cap U \text{ for } 1 \leq i \leq m. \end{aligned}$$

But in obvious notation,

$$\begin{aligned} \nabla_i(fX) &= \nabla_i(\tilde{f} \tilde{X})|_M = \frac{\partial \tilde{f}}{\partial x_i} \Big|_M X + \tilde{f} \nabla_i(\tilde{X})|_M \\ &= \frac{\partial f}{\partial x_i} X + f \nabla_i(X) \end{aligned}$$

$$\begin{aligned} \nabla_{f \frac{\partial}{\partial x_i}}(X) &= \nabla_{\tilde{f} \frac{\partial}{\partial x_i}}(\tilde{X})|_M = \tilde{f} \nabla_{\frac{\partial}{\partial x_i}}(\tilde{X})|_M \\ &= f \nabla_i(X) \text{ for } 1 \leq i \leq m \end{aligned}$$

we deduce that  $\nabla$  is a connection on  $TN|_M$

Now the metric  $g$  on  $TN$  restricts to a metric on  $TN|_M$  & hence to a metric on  $TM \subset TN|_M$ .

Denote the orthogonal projection map  $\pi: TN|_M \rightarrow TM$  (each  $T_p N$  for  $p \in M$  decomposes as an orthogonal direct sum  $T_p N = T_p M \oplus (T_p M)^\perp$  i.e.  $(TM)^\perp$  is the bundle sum by  $v \in T_p N$  ( $p \in M$ ) s.t.  $g(v, w) = 0 \forall w \in T_p M$ ).

CLAIM Setting  $\nabla^* := \pi \circ \nabla$  (i.e. for v fields  $X, Y$  on  $M$ ,  $\nabla_X^*(Y) = \pi(\nabla_X(\tilde{Y}))$  is usual notation), we have  $\nabla^*$  is the Levi-Civita connection on  $M$ .

Pf Easy check that  $\nabla^*$  is a connection on  $M$ : note that  $\nabla_i^*(Y) = \pi(\nabla_i(\tilde{Y})|_M)$  for  $i=1, \dots, m$

$$\begin{aligned} \& \text{ so } \nabla_i^*(\partial/\partial x_j) &= \pi((\nabla_i \partial/\partial x_j)|_M) \\ &= \pi((\nabla_j \partial/\partial x_i)|_M) = \nabla_j^*(\partial/\partial x_i) \end{aligned}$$

for  $i=1, \dots, m$ ,  $\nabla$  torsion free  $\Rightarrow \nabla^*$  torsion free.

Moreover for v. fields  $X, Y$  on  $M$  have

$$\begin{aligned} \partial/\partial x_i \langle X, Y \rangle_M &= \partial/\partial x_i \langle \tilde{X}, \tilde{Y} \rangle_N | _M \text{ for } i=1, \dots, m \\ &= (\langle \nabla_i \tilde{X}, \tilde{Y} \rangle_N + \langle \tilde{X}, \nabla_i \tilde{Y} \rangle) | _M \\ &= \langle \nabla_i X, Y \rangle + \langle X, \nabla_i Y \rangle \text{ where } \nabla_i X \& \nabla_i Y \\ &\text{are local sections of } TN|_M \end{aligned}$$

$$= \langle \pi(\nabla_i X), Y \rangle_M + \langle X, \pi(\nabla_i Y) \rangle_M$$

$$= \langle \nabla_i^* X, Y \rangle_M + \langle X, \nabla_i^* Y \rangle_M$$

$\Rightarrow \nabla^*$  is the Levi-Civita connection on  $M$  (by uniqueness of the connection).

Q3) Formulae for  $\Gamma_{ij}^k$  in terms of  $g$  show that the Christoffel symbols are invariant under scaling of metric & so Levi-Civita connection is invariant

Aliter If  $\nabla$  the Levi-Civita connection associated with  $g$ , it is symmetric by defn: since it's compatible with  $g$ , it's clearly also compatible with  $\lambda g$  ( $\lambda = r^2$ )

ie.  $X \langle Y, Z \rangle = \langle \nabla_X Y, Z \rangle + \langle Y, \nabla_X Z \rangle$  is still true  $\Rightarrow \nabla$  is Levi-Civita connection w.r.t  $\lambda g$ .

Thus  $\nabla_X \nabla_Y Z$  doesn't depend on scaling

$$\Rightarrow R(X, Y)Z = \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X, Y]} Z$$

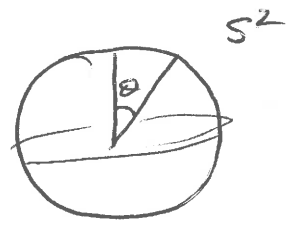
is indep of scaling of metric

So  $R(u, v, u, v) = \langle u, R(u, v)v \rangle$  scales like  $r^2$

while  $\langle u, u \rangle \langle v, v \rangle - \langle u, v \rangle^2$  scales like  $r^4$

$\Rightarrow$  sectional curvatures scale like  $1/r^2$ .

Q4) In case  $n=2$ , a unit sphere  $S^2$  has parametrization



$$\sigma(\theta, \phi) = (\sin \phi \cos \theta, \sin \phi \sin \theta, \cos \phi)$$

$$\Rightarrow \sigma_\theta = (-\sin \phi \sin \theta, \sin \phi \cos \theta, 0)$$

$$\sigma_\phi = (\cos \phi \cos \theta, \cos \phi \sin \theta, -\sin \phi)$$

$$\Rightarrow \text{metric} = d\phi^2 + \sin^2 \phi d\theta^2 \text{ on } S^2.$$

On  $\mathbb{R}^3 \setminus \{0\}$ , have coords  $x = r \sin \phi \cos \theta$

$$y = r \sin \phi \sin \theta$$

$$z = r \cos \phi$$

$$\Rightarrow dx = dr \sin \phi \cos \theta - r \sin \phi \sin \theta d\theta + r \cos \phi \cos \theta d\phi$$

$$dy = dr \sin \phi \sin \theta + r \sin \phi \cos \theta d\theta + r \cos \phi \sin \theta d\phi$$

$$dz = dr \cos \phi - r \sin \phi d\phi. \text{ So Euclidean metric}$$

$$dx^2 + dy^2 + dz^2 = dr^2 + r^2 (d\phi^2 + \sin^2 \phi d\theta^2).$$

In general, we have local coords  $u_1, \dots, u_{n-1}$  on unit sphere  $S^{n-1}$  i.e.  $\sigma(u_1, \dots, u_{n-1})$  a local parametrization,

$$\text{say } \sigma(u_1, \dots, u_{n-1}) = (x(u_1, \dots, u_{n-1}), y(u_1, \dots, u_{n-1}), z(u_1, \dots, u_{n-1})).$$

We then consider local parametrization

$$(r, u_1, \dots, u_{n-1}) \mapsto r \sigma(u_1, \dots, u_{n-1}) \text{ of } \mathbb{R}^n \setminus \{0\}.$$

Note that  $\sigma, r\sigma_{u_1}, \dots, r\sigma_{u_{n-1}}$  are lin indep (considered as tangent vectors on  $\mathbb{R}^n$  at  $P = r\sigma(u_1, \dots, u_{n-1})$ ) & moreover

$$\langle \underline{\sigma}, r \sigma_{u_i} \rangle = 0 \quad \forall i$$

(since  $\langle \underline{\sigma}, \underline{\sigma} \rangle = 1$  on  $S^{n-1}$ , on differentiating wrt  $u_i$  we get  $\langle \sigma, \sigma_{u_i} \rangle = 0 \quad \forall i$ ). So metric on  $\mathbb{R}^n \setminus \{0\}$  wrt this parametrization is given by

$$\begin{aligned} \langle \sigma, \sigma \rangle dr^2 + r^2 \sum_{i,j} \langle \sigma_{u_i}, \sigma_{u_j} \rangle du_i du_j \\ = dr^2 + r^2 dS^2 \quad \text{as claimed.} \end{aligned}$$

5) Let  $D$  denote the Levi-Civita connection on  $M$  - by QR this is given by the orthogonal projection

$$\pi : TN \rightarrow TM \quad \text{ie. } D_V = \pi \circ \nabla_V$$

$$\text{Now } \nabla_V (fW) = V(f)W + f \nabla_V W \Rightarrow$$

$$\text{II}(V, fW) = f \text{II}(V, W) \quad \text{for } V, W \text{ tangent to } M.$$

$$\begin{aligned} \text{Moreover } \text{II}(V, W) - \text{II}(W, V) &= (\nabla_V W - \nabla_W V)^\perp \\ &= [V, W]^\perp = 0 \end{aligned}$$

( $\nabla$  torsion free).

So  $\text{II} : TM \times TM \rightarrow (TM)^\perp$  symmetric bilinear

Extending the test vectors  $v, w, x, y$  to local vector fields

$V, W, X, Y$  with  $V_p = v$ , etc RTP

$$\langle \bar{R}(V, W)X, Y \rangle = \langle \bar{R}(v, w)X, Y \rangle$$

$$+ \langle \text{II}(V, X), \text{II}(W, Y) \rangle - \langle \text{II}(V, Y), \text{II}(W, X) \rangle$$

$$\text{Now } R(v, w)X = \nabla_v \nabla_w X - \nabla_w \nabla_v X - \nabla_{[v, w]} X \quad (7)$$

$$\Rightarrow \langle R(v, w)X, Y \rangle = \langle \nabla_v \nabla_w X, Y \rangle - \langle \nabla_w \nabla_v X, Y \rangle - \langle \nabla_{[v, w]} X, Y \rangle$$

Recalling that for  $D = \bar{\nabla}$  the Levi-Civita connection on  $M$ ,

Q2  $\Rightarrow D_w X$  is tangential component of  $\nabla_w X$ ,

$$\text{have } \langle \nabla_v \nabla_w X, Y \rangle = \langle \nabla_v D_w X, Y \rangle + \langle \nabla_v \Pi(w, X), Y \rangle$$

$$= \langle D_v D_w X, Y \rangle + \langle \Pi(v, D_w X), Y \rangle$$

$$+ \langle \nabla_v \Pi(w, X), Y \rangle$$

$$= \langle D_v D_w X, Y \rangle + v \langle \Pi(w, X), Y \rangle$$

metric  
connection

$$- \langle \Pi(w, X), \nabla_v Y \rangle$$

$$= \langle D_v D_w X, Y \rangle - \langle \Pi(w, X), \Pi(v, Y) \rangle$$

$$\text{Using the identity } \bar{R}(v, w)X = D_v D_w X - D_w D_v X - D_{[v, w]} X$$

$$\& \langle \nabla_{[v, w]} X, Y \rangle = \langle D_{[v, w]} X, Y \rangle$$

$$\& \langle \nabla_w \nabla_v X, Y \rangle = \langle D_w D_v X, Y \rangle - \langle \Pi(v, X), \Pi(w, Y) \rangle$$

$$\text{we obtain } \langle R(v, w)X, Y \rangle = \langle \bar{R}(v, w)X, Y \rangle$$

$$+ \langle \Pi(v, X), \Pi(w, Y) \rangle - \langle \Pi(w, X), \Pi(v, Y) \rangle$$

as required

(Q6)  $M \subset N = \mathbb{R}^n$  defined by  $f=0$  & the tangent space (8)

at  $P \in M$  is  $\text{Ker } d_P f$ , where

$$d_P f \left( \sum v_i \frac{\partial}{\partial x_i} \right) = \sum \frac{\partial f}{\partial x_i} (P) v_i$$

[usually we identify  $T_{N,P} \cong \mathbb{R}^n$  i.e.  $d_P f \left( \begin{smallmatrix} v_1 \\ \vdots \\ v_n \end{smallmatrix} \right) = \sum \frac{\partial f}{\partial x_i} (P) v_i$

Let  $\underline{x} := \sum \frac{\partial f}{\partial x_i} \frac{\partial}{\partial x_i}$  be the v field on  $\mathbb{R}^n$

corresponding to grad  $f = \begin{pmatrix} \frac{\partial f}{\partial x_1} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{pmatrix}$ , & the

$$\langle \underline{x}, v \rangle_P = \sum \frac{\partial f}{\partial x_i} (P) v_i \quad \forall v = \sum v_i \frac{\partial}{\partial x_i} \in T_{\mathbb{R}^n, P}$$

On  $M$ ,  $\underline{x}$  is non-vanishing &  $\langle \underline{x}, v \rangle = 0$

$\forall v \in T_{M,P} \Rightarrow$  it is a normal vector  $\forall P \in M$ .

Setting  $h = \left( \sum_i \left( \frac{\partial f}{\partial x_i} \right)^2 \right)^{1/2}$ , then have a smooth

field of normal unit vectors  $\underline{N} = \frac{1}{h} \underline{x}$  on  $M$ ,

with  $h \underline{N} = \sum \frac{\partial f}{\partial x_i} \frac{\partial}{\partial x_i}$ . Since both the

tangent space to  $S^{n-1}$  at  $\underline{N}(P)$  and to  $M$  at  $P$

are given by the same condition of being orthogonal to  $\underline{N}(P)$ ,

the Gauss map  $\underline{N} : M \rightarrow S^{n-1}$  induces derivative

$$d_P \underline{N} : T_{M,P} \rightarrow T_{S^{n-1}, \underline{N}(P)} = T_{M,P}$$

We now let  $\nabla$  denote the standard (trivial) connection on  $\mathbb{R}^n$  (= Levi-Civita w.r.t. Euclidean metric)

$$\text{So } \nabla(\underline{x}) \left( \frac{\partial}{\partial x_k} \right) = \nabla_{\frac{\partial}{\partial x_k}} (\underline{x})$$

$$= \sum_i \frac{\partial^2 f}{\partial x_k \partial x_i} \frac{\partial}{\partial x_i} = d(\underline{x}) \left( \frac{\partial}{\partial x_k} \right) \quad \forall k$$



ie.  $d(\underline{x})(v) = \nabla(\underline{x})(v) = \nabla_v(\underline{x}) \quad \forall v \in T_p \mathbb{R}^n$  (9)

Given now  $v, w \in T_{M,p}$  & local v fields  $V, W$  on  $M$  with  $V_p = v, W_p = w$ , recall that  $\nabla_v(W)$  was well-defined (as  $\nabla_v(\tilde{W})|_M$  for any extension  $\tilde{W}$  of  $W$ ).

$$\begin{aligned} \text{Then } \langle \nabla_v W, \underline{N} \rangle_p &= \frac{1}{h(p)} \langle \nabla_v W, \underline{x} \rangle_p \\ &= -\frac{1}{h(p)} \langle W, \nabla_v(\underline{x}) \rangle_p = -\frac{1}{h(p)} \langle W, d_p(\underline{x})v \rangle_p \\ &= -\langle W, d_p \underline{N}(v) \rangle_p \quad \text{as } \underline{x} = h \underline{N} \text{ \& } \langle W, \underline{N} \rangle_p = 0. \end{aligned}$$

& so  $\mathbb{II}(v, w) = -\langle d_p \underline{N}(v), w \rangle \underline{N}$  as desired.

For sphere  $S^{n-1} \subset \mathbb{R}^n$  of radius  $r$ , clearly have

$$\underline{N}(\underline{x}) = \frac{1}{r} \underline{x} \quad \forall \underline{x} \in S^{n-1} \quad \text{ie. } \underline{N} = \frac{1}{r} \text{id}$$

$$\text{So } \mathbb{II}(v, w) = -\frac{1}{r} \langle v, w \rangle \underline{N} \quad \forall v, w \in T_p M.$$

But sectional curvature for plane spanned by  $v, w \in T_p M$

$$\begin{aligned} & \text{is } \langle \overline{R}(v, w) w, v \rangle / (\langle v, v \rangle \langle w, w \rangle - \langle v, w \rangle^2) \\ &= \frac{(\langle \mathbb{II}(v, v), \mathbb{II}(w, w) \rangle - \langle \mathbb{II}(v, w), \mathbb{II}(v, w) \rangle)}{\langle v, v \rangle \langle w, w \rangle - \langle v, w \rangle^2} = \frac{1}{r^2} \end{aligned}$$

Q7) Suppose  $J: V \rightarrow V$  an EM of a v space  $V$

st.  $J^2 = -1$ . Then  $\exists$  basis of  $V$  w.r.t. which the

matrix of  $J$  is :

$$\left( \begin{array}{cc|cc} 0 & 1 & & \\ -1 & 0 & & \\ \hline & & 0 & 1 \\ & & -1 & 0 \\ \hline 0 & & & \\ & & & \begin{array}{cc} 0 & 1 \\ -1 & 0 \end{array} \end{array} \right)$$

In particular,  $\dim V$  is even.  
 So  $M$  has an almost complex structure  $\Rightarrow \dim M$  even  
 $= 2n$  say.

Now for any  $\theta \in \text{End TM}$ , we have

$$\nabla_x (\theta(Y)) = (\nabla_x \theta)(Y) + \theta(\nabla_x Y) \quad \& \text{ so}$$

$\nabla$  compatible with  $J$  means that  $\nabla_x (JY) = J \nabla_x Y$   
 $\forall x, Y$  (i.e.  $\Leftrightarrow \nabla J = 0$ )

Now for any Koszul connection  $\nabla$ , we can define an associated connection  $\nabla'$  by  $\nabla'(JX) = \frac{1}{2}(\nabla(JX) + J(\nabla X))$

Note then, by substituting  $X \Leftrightarrow JX$ , we get

$$J \nabla' X = \frac{1}{2}(J(\nabla X) + \nabla(JX)) = \nabla'(JX)$$

i.e.  $\nabla'$  compatible with the almost complex structure  $J$ .

Observe  $\nabla' X = \frac{1}{2}(\nabla X - J \nabla(JX))$  (\*)

May check directly this is a connection, or alternatively comment that  $\nabla' X = \nabla X - \frac{1}{2} J \nabla(JX) - \frac{1}{2} \nabla X$  is the connection  $\nabla - \frac{1}{2} J \circ \nabla J$  where  $Z$  term  $\in \Omega^1(\text{End TM})$

We should now impose the main condition that the almost complex str  $J$  is also compatible with metric  $g$

i.e.  $g(JX, JY) = g(X, Y) \quad \forall X, Y$

It will turn out that the connection we find is not unique (11)  
 as claimed = original version of question, but only that a distinguished choice may be made.

Suppose as above that  $\nabla$  is a metric connection: then

$$\begin{aligned}
 (\nabla'X, Y) + (X, \nabla'Y) &= \underline{\frac{1}{2}(\nabla X, Y) + \frac{1}{2}(\nabla JX, JY)} \\
 &+ \underline{\frac{1}{2}(X, \nabla Y) + \frac{1}{2}(JX, \nabla JY)} \quad \text{from (*)} \\
 &= \frac{1}{2}g(X, Y) + \frac{1}{2}g(JX, JY) = g(X, Y)
 \end{aligned}$$

(assuming  $J$  is metric compatible)  $\therefore \nabla'$  also a metric connection

Any other connection can be written in the form  $\nabla' + \Theta$   
 with  $\Theta \in \Omega^1(\text{End } TM)$ : conditions for this connection to  
 be compatible with  $J$  and the metric are

$$(i) \quad \Theta J = J \Theta \quad \& \quad (ii) \quad (\Theta X, Y) + (X, \Theta Y) = 0$$

There are many choices for such a  $\Theta$  (essentially we are just  
 saying that it is skew-symmetric), but there is however  
 a distinguished choice for the connection, as we can always  
 start with  $\nabla$  being the Levi-Civita connection & take the  
 corresponding  $\nabla'$ .

If we have a connection which is compatible with  
 almost complex structure  $J$ , the parallel transport  $\tau_t$   
 is also compatible with  $J$ , i.e.  $J\tau_t = \tau_t J$

On any given left space,  $J$  defines the structure of a  $v$  space over  $\mathbb{C}$  (namely  $i \cdot v := J(v)$ ) & thus the says that  $\mathbb{R}_\pm$  is an IM of complex  $v$  spaces.

Argument  $\Rightarrow$  it is also an isometry

Thus parallel transport around a closed loop yields an elt of  $GL(n, \mathbb{C}) \cap O(2n) = U(n)$ .

(Q8) Recall  $R(x, y, z, T) = R(z, T, x, y)$

and is antisymmetric in first two & last two entries  
 $\Rightarrow R$  defines a symmetric bilinear form on  $\Lambda^2 TM$

ie.  $R \in S^2(\Lambda^2 TM)^*$

When  $\dim V = 3$  for a real  $v$  space  $V$ , have that

$V \times \Lambda^2 V \rightarrow \Lambda^3 V = k$  is a perfect pairing, namely

$$(\lambda_1 e_1 + \lambda_2 e_2 + \lambda_3 e_3) \wedge (\mu_1 e_2 \wedge e_3 + \mu_2 e_3 \wedge e_1 + \mu_3 e_1 \wedge e_2)$$

$$\longmapsto (\lambda_1 \mu_1 + \lambda_2 \mu_2 + \lambda_3 \mu_3) e_1 \wedge e_2 \wedge e_3$$

ie. we have an isomorphism IM  $\Lambda^2 V \xrightarrow{\sim} V^*$

A metric (ie. inner product) on  $V$  determines an IM

$V^* \rightarrow V$  & hence an identification  $\Lambda^2 V \xrightarrow{\sim} V$

(depending only on  $\begin{matrix} \text{metric} \\ \text{orientation} \end{matrix}$ ) & so  $S^2(\Lambda^2 V)^* \cong S^2 V^*$

Now apply this to the tangent space to  $M$  at a point  $P$ .

We have a map  $c: S^2(\Lambda^2 V)^* \rightarrow S^2 V^*$

given by  $c(R) = r$  where  $r(v, w) = \sum_i R(e_i, v, e_i, w)$   
 where  $\{e_1, e_2, e_3\}$  an o-n basis

CLAIM When  $\dim V = 3$ ,  $\text{Ker } c = 0$

Pf Take  $e_1, e_2, e_3$  o.n. basis

If image  $r = c(R)$  is zero, then

$$r(e_1, e_2) = 0 \Rightarrow R(e_3, e_1, e_3, e_2) = 0$$

$$r(e_1, e_1) = 0 \Rightarrow R(e_2, e_1, e_2, e_1) + R(e_3, e_1, e_3, e_1) = 0$$

$$\text{Similarly } R(e_1, e_2, e_1, e_2) + R(e_3, e_2, e_3, e_2) = 0$$

$$\therefore R(e_3, e_1, e_3, e_1) = R(e_3, e_2, e_3, e_2)$$

$$\text{But } R(e_1, e_3, e_1, e_3) + R(e_2, e_3, e_2, e_3) = 0$$

$$\Rightarrow R(e_1, e_3, e_1, e_3) = 0 \quad \& \text{ similar symmetrized}$$

$$\text{statements } \Rightarrow R(e_1, e_3, e_2, e_3) = 0 \quad \& \text{ similar}$$

$$\text{statements } \Rightarrow R = 0.$$

Since  $c$  is linear &  $\dim S^2(\Lambda^2 V)^* = \dim S^2 V^*$ ,

have  $c$  an IM. So for  $r \in S^2 V^*$ ,  $\exists!$

$R \in S^2(\Lambda^2 V)^*$  s.t.  $c(R) = r$ .

For  $V = (TM)_p$ , this ensures that the Ricci tensor determines the full Riemannian curvature tensor

29) Clearly  $T(M \times N)_{(x,y)} = TM_x \oplus TN_y$ . Given

inner-products on  $TM_x$  &  $TN_y$ , the sum is an i.p. on

the direct sum. From this it is clear that  $g+h$  defines

a metric  $\langle, \rangle$  on  $M \times N$

Clearly  $\langle X, Y \rangle = 0$  for  $X$  a v field on  $M$   
 $Y$  a v field on  $N$

Moreover writing  $X = \sum X_i \frac{\partial}{\partial x_i}$ ,  $Y = \sum Y_j \frac{\partial}{\partial y_j}$ ,  
 for any  $f = f(x_1, \dots, x_m, y_1, \dots, y_n)$ ,

$$XYf = \sum_{i,j} X_i \frac{\partial}{\partial x_i} Y_j \frac{\partial}{\partial y_j} f = \sum X_i Y_j \frac{\partial^2 f}{\partial x_i \partial y_j} = YXf.$$

Moreover, for v fields  $X_1, X_2$  on  $M$ , the bracket (on  $M \times N$ )  
 $[X_1, X_2]$  comes from a v field on  $M$  & similar statement holds  
 for v fields  $Y_1, Y_2$  on  $N$ . Now use the formulae for the  
 Levi-Civita connection (cf Fundamental Lemma of Riemannian Geometry)

to deduce that  $\langle \nabla_X Y, Z \rangle = 0$  for any v field  $Z$   
 coming from  $M$  or  $N \Rightarrow \langle \nabla_X Y, Z \rangle_p = 0$  pointwise  
 for all  $Z_p \in T(M \times N)_p \Rightarrow \nabla_X Y = 0$

(either argue directly from Christoffel symbols).

Note that for v fields  $Y, Y'$  on  $N$ ,  $\nabla_Y Y'$  (for  
 above L-C connection on  $N$ ) comes from  $\nabla_Y Y'$  for L-C  
 connection on  $N$ . So for  $X$  v field on  $M$ ,  $Y$  a v field on  $N$ ,

$$R(X, Y)Y = \nabla_X \underbrace{\nabla_Y Y}_{Y'} - \underbrace{\nabla_Y \nabla_X Y}_0 - \underbrace{\nabla_{[X, Y]} Y}_0$$

$$\Rightarrow R(X, Y, X, Y) = \langle X, R(X, Y)Y \rangle = 0.$$

Q10) Isometries of Lorentzian form in  $O^+(n, 1)$  include

elts  $\begin{pmatrix} 1 & 0 \\ 0 & A \end{pmatrix}$  for  $A \in SO(n)$  & elts  $\begin{pmatrix} \cosh d & -\sinh d & & 0 \\ -\sinh d & \cosh d & & 0 \\ \hline & & 1 & \\ & & & \ddots \\ 0 & & & & 1 \end{pmatrix}$

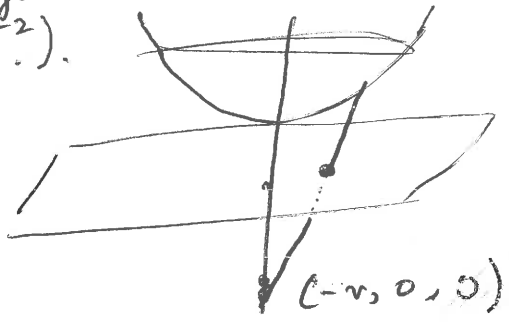
Now use elts of 1st type to send any point on  $H(r)$  to a point of the form  $(r \cos d, r \sin d, 0, \dots, 0)$  & then use 2nd type of symmetry to send it to  $Q = (r, 0, \dots, 0)$  (cf similar argument in case of  $S^n$ ). Isometries of 1st type act transitively on planes in tangent space at  $Q$  & so sectional curvatures of  $H(r)$  are all constant

= Gaussian curvature of  $H_2(r)$  (2-dim case).

(tangent spaces to  $H(r)$  split into orthogonal direct sum of tangent space to  $H_2(r)$  &  $\mathbb{R}^{n-2}$ ).

Now stereographic projection of

$H_2(r)$  from point  $(-r, 0, 0)$



onto plane  $x_0 = 0$ , identifies

$H_2(r)$  isometrically with disc of radius  $r$  in plane

with metric  $\frac{4r^4 |dw|^2}{(r^2 - |w|^2)^2}$

(cf calculation in Ch 5 of my book for case  $r=1$ ), which in turn is isometric to the Poincaré disc model of hyperbolic plane with metric scaled by  $r^2$ .

So, using result from Q3, need only show that hyperbolic plane has constant curvature  $-1$

Let us work with upper half-plane model  $H$ , with

metric  $g = \frac{|dz|^2}{y^2}$  ie.  $g_{11} = g_{22} = 1/y^2$  &  $g_{12} = g_{21} = 0$

Thus  $g'' = g^{22} = y^2$ ,  $g^{12} = 0$  for inverse metric.

$$\text{So } \Gamma''_{11} = \frac{1}{2} g'' (g_{11,1} + \dots) = 0$$

$$\Gamma''_{11} = \frac{1}{2} g^{22} (g_{12,1} + g_{12,1} - g_{11,2}) = \frac{1}{y}$$

$$\Gamma''_{12} = \frac{1}{2} g'' (g_{11,2} + \cancel{g_{21,1}} - \cancel{g_{12,1}}) = -\frac{1}{y}$$

$$\Gamma''_{12} = \Gamma''_{22} = 0, \quad \Gamma''_{22} = \frac{1}{2} g^{22} (g_{22,2}) = -\frac{1}{y}.$$

$$\therefore \nabla_1 \partial_{1x} = \frac{1}{y} \partial_{1y}, \quad \nabla_1 \partial_{1y} = -\frac{1}{y} \partial_{2x}, \quad \nabla_2 \partial_{1y} = -\frac{1}{y} \partial_{2y}$$

$$\begin{aligned} \therefore R(\partial_{1x}, \partial_{1y}) \partial_{1y} &= \nabla_1 \nabla_2 \partial_{1y} - \nabla_2 \nabla_1 \partial_{1y} \\ &= -\nabla_1 \frac{1}{y} \partial_{2y} + \nabla_2 \frac{1}{y} \partial_{2x} \\ &= +\frac{1}{y^2} \partial_{2x} - \frac{1}{y^2} \partial_{2x} - \frac{1}{y^2} \partial_{2x}. \end{aligned}$$

$$\text{So } \langle \partial_{2x}, R(\partial_{1x}, \partial_{1y}) \partial_{1y} \rangle = -\frac{1}{y^2} \cdot \frac{1}{y^2} = -\frac{1}{y^4}.$$

$$\therefore K = -\frac{1}{y^4} / \frac{1}{y^2} \cdot \frac{1}{y^2} = -1.$$

Q11) Second Bianchi (in coord coords at a point P)

$$\text{reads } \partial_{1x}^h R_{klij} + \partial_{2x}^k R_{lhij} + \partial_{3x}^l R_{hkij} = 0$$

Contract with  $g^{ij}$  & use fact that coords are coord

$$\text{to get } \partial_{1x}^h r_{ki} - \partial_{2x}^k r_{hi} + \sum_j \partial_{3x}^j R_{hkij} = 0$$

$$\text{Setting } h=i, \text{ get } \partial_{1x}^i r_{ki} - \partial_{2x}^k r_{ii} + \sum_j \partial_{3x}^j R_{ikij} = 0 \quad (*)$$

Now assume that Ricci tensor  $r = c g$ .



For some function  $c$  on  $M$ , where  $g$  denotes the metric i.e. that the Ricci curvatures are constant at each point (but maybe vary as the point varies).

With normal coords as above (so that  $g_{ij}(P) = \delta_{ij}$  & first order terms vanish) , we can sum equation (\*) over  $i$ , obtaining

$$\frac{\partial c}{\partial x^k} - n \frac{\partial c}{\partial x^k} + \sum_j \frac{\partial}{\partial x^j} c g_{kj} = 0$$

$= \frac{\partial}{\partial x^k} c$

$$\Rightarrow (2-n) \frac{\partial c}{\partial x^k} = 0 \Rightarrow \frac{\partial c}{\partial x^k} = 0 \quad \forall k$$

$\therefore dc = 0$  everywhere &  $c$  is locally constant. ( $n > 2$ ).

Assuming  $M$  is connected, deduce  $c = \text{const.}$