Part IB GEOMETRY (Lent 2015): Example Sheet 3

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1. Show the tangent space to S^2 at a point $P = (x, y, z) \in S^2$ is the plane normal to the vector \overrightarrow{OP} , where O denotes the origin.

2. Let V be the open subset $\{0 < u < \pi, 0 < v < 2\pi\}$, and $\sigma: V \to S^2$ be given by

 $\sigma(u, v) = (\sin u \cos v, \sin u \sin v, \cos u).$

Prove that σ defines a smooth parametrization on a certain open subset of S^2 . [You may assume \cos^{-1} is continuous on (-1, 1), and \tan^{-1} , \cot^{-1} are continuous on $(-\infty, \infty)$.]

3. Show the stereographic projection map $\pi : S \setminus \{N\} \to \mathbb{C}$, where N denotes the north pole, defines a chart. Check that the spherical metric on $S \setminus \{N\}$ corresponds under π to the Riemannian metric on \mathbb{C} given by $4(dx^2 + dy^2)/(1 + x^2 + y^2)^2$.

4. Let T denote the embedded torus in \mathbb{R}^3 obtained by revolving around the z-axis the circle $(x-2)^2 + z^2 = 1$ in the xz-plane. Using the formal definition of area in terms of a parametrization, calculate the surface area of T.

5. If one places S^2 inside a (vertical) circular cylinder of radius one, prove that the radial (horizontal) projection map from S^2 to the cylinder preserves areas (this is usually known as *Archimedes Theorem*). Deduce the existence of an atlas on S^2 , for which the charts all preserve areas and the transition functions have derivatives with determinant one.

6. Using the geodesic equations, show directly that the geodesics in the hyperbolic plane are hyperbolic lines parametrized with constant speed. [Hint: In the upper half-plane model, prove that a geodesic curve between any two points of the positive imaginary axis L^+ is of the form claimed.]

7. For a > 0, let $S \subset \mathbb{R}^3$ be the circular half-cone defined by $z^2 = a(x^2 + y^2)$, z > 0, considered as an embedded surface. Show that S minus a ray through the origin is isometric to a suitable region in the plane. [Intuitively: you can glue a piece of paper to form a cone, without any crumpling of the paper.] When a = 3, give an explicit formula for the geodesics on S and show that no geodesic intersects itself. When a > 3, show that there are geodesics (of infinite length) which intersect themselves.

8. Let $S \subset \mathbb{R}^3$ denote the graph of a smooth function F (defined on some open subset of \mathbb{R}^2), given therefore by the equation z = F(x, y). Show that S is a smooth embedded surface, and that its curvature at a point $(x, y, z) \in S$ is the value taken at (x, y) by

$$(F_{xx}F_{yy} - F_{xy}^2)/(1 + F_x^2 + F_y^2)^2.$$

9. For a surface of revolution S, corresponding to an embedded curve $\eta : (a, b) \to \mathbb{R}^3$ given by $\eta(u) = (f(u), 0, g(u))$, where η' is never zero, η is homeomorphic onto its image, and f(u) is always positive, prove that the Gaussian curvature K is given by the formula

$$K = \frac{(f'g'' - f''g')g'}{f((f')^2 + (g')^2)^2}.$$

In the case when η is parametrized in such a way that $\|\eta'\| = 1$, prove that K is given by the formula K = -f''/f. Verify that the unit sphere has constant curvature 1.

10. Using the results from the previous question, calculate the Gaussian curvature K for the hyperboloid of one sheet $x^2 + y^2 = z^2 + 1$, and the hyperboloid of two sheets $x^2 + y^2 = z^2 - 1$. Describe the qualitative properties of the curvature in these cases (sign and behavior near infinity), and explain what you find using pictures of these surfaces.

For the embedded torus, as defined in Question 4, identify those points at which K = 0, K > 0 and K < 0. Verify the global Gauss–Bonnet theorem on the embedded torus.

11. Suppose we have a Riemannian metric of the form $|dz|^2/h(r)^2$ on some open disc $D(0; \delta)$ centred at the origin in \mathbb{C} (possibly all of \mathbb{C}), where h(r) > 0 for all $r < \delta$. Show that the curvature K of this metric is given by the formula $K = hh'' - (h')^2 + hh'/r$.

12. Show that the embedded surface S with equation $x^2 + y^2 + c^2 z^2 = 1$, where c > 0, is homeomorphic to the sphere. Deduce from the Gauss–Bonnet theorem that

$$\int_0^1 (1 + (c^2 - 1)u^2)^{-3/2} du = c^{-1}.$$

Can you find a direct verification of this formula?

13. Given a smooth curve $\Gamma : [0,1] \to S$ on an abstract surface S with a Riemannian metric, show that the length l is unchanged under reparametrizations of the form $f : [0,1] \to [0,1]$, with f'(t) > 0 for all $t \in [0,1]$. Prove that if $\Gamma'(t) \neq 0$ for all t, then Γ can be reparametrized to a curve with constant speed.

14. Show that Mercator's parametrization of the sphere (minus poles)

 $\sigma(u, v) = (\operatorname{sech} u \cos v, \operatorname{sech} u \sin v, \tanh u)$

determines a chart (on the complement of a longitude) which preserves angles and sends meridians and parallels on the sphere to straight lines in the plane.

15. Let S be an embedded surface in \mathbb{R}^3 which is closed and bounded. By considering the smallest closed ball centred on the origin which contains S, or otherwise, show that the Gaussian curvature must be strictly positive at some point of S. Deduce that the locally Euclidean metric on the torus T cannot be realized as the first fundamental form of a smooth embedding of T in \mathbb{R}^3 .

16. Show that the surface obtained by attaching 2 handles to a sphere (i.e. the surface of a 'doughnut with 2 holes') may be obtained topologically by suitably identifying the sides of a regular octagon. Indicate briefly how to extend your argument to show that a 'sphere with g handles' Σ_g may be obtained topologically by suitably identifying the sides of a regular 4g-gon.

Show that Σ_g (g > 1) may be given the structure of an abstract surface with a Riemannian metric, in such a way that it is locally isometric to the hyperbolic plane. [For this question, you will need the result from Q10 on Example Sheet 2.]

Note to the reader: You should look at all the questions up to Question 12, and then any further questions you have time for.