GEOMETRY — Example Sheet 3

1. Let U be an open subset of \mathbb{R}^2 with the Riemannian metric

$$ds^2 = E \, dx_1^2 + 2F \, dx_1 \, dx_2 + G \, dx_2^2$$

For any point $P \in U$, show that there is a $\lambda > 0$ and a neighbourhood N of P with

$$(E - \lambda) dx_1^2 + 2F dx_1 dx_2 + (G - \lambda) dx_2^2$$

a Riemannian metric on N. [Hint: A real matrix $\begin{pmatrix} a & b \\ b & d \end{pmatrix}$ is positive definite if and only if a > 0 and $ad - b^2 > 0$.] If U is path-connected, we define the distance between two points of U as the infimum of the lengths

of all curves in U between those two points. Give an example where this distance is not realised as the length of any curve in U between the two points.

2. Consider the Riemannian metric

$$ds^{2} = \frac{dx_{1}^{2} + dx_{2}^{2}}{1 - (x_{1}^{2} + x_{2}^{2})}$$

on the unit disc D. Prove that diameters of the disc are length minimising curves and hence geodesics. Show that the distance between points is bounded but areas are unbounded.

3. Let $U = \{(x_1, x_2) \in \mathbb{R}^2 : |x_1|, |x_2| < 1\}$ and consider the two Riemannian metrics

$$\frac{dx_1^2}{(1-x_1^2)^2} + \frac{dx_2^2}{(1-x_2^2)^2} \quad \text{and} \quad \frac{dx_1^2}{(1-x_2^2)^2} + \frac{dx_2^2}{(1-x_1^2)^2}$$

on U. Prove that there is no isometry between the two spaces but that an area preserving diffeomorphism does exist.

[Consider the length of curves going out to the boundary.]

- 4. For the unit sphere S in \mathbb{R}^3 , find the unit normal at a point x, the tangent plane at x and the intersection of planes parallel to the tangent plane with S.
- 5. Show that

$$\boldsymbol{r}: (0,\pi) \times (0,2\pi) \to \mathbb{R}^3$$
; $(u,v) \mapsto (\sin u \cos v, \sin u \sin v, \cos u)$

is a surface parametrisation. Describe the image. What is the corresponding Riemannian metric?

- 6. Let T denote the torus obtained by rotating the circle $\{(x, 0, z) \in \mathbb{R}^3 : (x-2)^2 + z^2 = 1\}$ about the z-axis. Describe a surface parametrisation for T and hence calculate its area.
- 7. Prove directly that the hyperbolic lines satisfy the differential equations for geodesics in the hyperbolic plane.
- 8. For a > 0, let C(a) be the cone:

$$C(a) = \{(x, y, z) \in \mathbb{R}^3 : z^2 = a(x^2 + y^2) \text{ and } z > 0\}.$$

Find a parametrisation for C(a) and hence find the geodesics on C(a). When a = 3, show that no (infinite) geodesic intersects itself. When a > 3, show that there are

- geodesics that intersect themselves. 9. Let $\sigma = (\sigma_1, \sigma_2) : (a, b) \to \{(x, y) \in \mathbb{R}^2 : y > 0\}$ be a unit speed curve in the upper half-plane that
- does not intersect itself and maps the open interval (a, b) homeomorphically onto its image. The surface of revolution R is then obtained by rotating σ about the x-axis. Show that

$$(s,t) \mapsto (\sigma_1(t), \sigma_2(t) \cos s, \sigma_2(t) \sin s)$$

is a surface parametrisation for part of R. Calculate the Riemannian metric and the second fundamental form. Hence show that the Gaussian curvature is given by

$$K = -\frac{\sigma_2''(t)}{\sigma_2(t)} \ .$$

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10. Using the formulae from the previous question, calculate the Gaussian curvature for a sphere, for the hyperboloid of one sheet:

$$x^2 + y^2 - z^2 = +1$$

and the hyperboloid of two sheets:

$$x^2 + y^2 - z^2 = -1 \; .$$

For the torus described in question 6, mark the points where the Gaussian curvature K satisfies K < 0; K = 0 and K > 0.

- 11. Let R be a surface in \mathbb{R}^3 that is closed and bounded. Explain why there is a point Q of R at a maximal distance d from the origin. By considering the sphere S centred on the origin and of radius d, or otherwise, show that the Gaussian curvature of R is strictly positive at Q. Hence the closed and bounded surface R can not have Gaussian curvature less than or equal to 0 at every point.
- 12. Let $f : \mathbb{R}^2 \to \mathbb{R}$ be a smooth function with

$$f(0,0) = 0$$
, $\frac{\partial f}{\partial x}(0,0) = 0$, $\frac{\partial f}{\partial y}(0,0) = 0$.

Let r be the surface parametrisation:

$$\boldsymbol{r}: (x,y) \mapsto (x,y,f(x,y))$$

Show that the Riemannian metric at the origin is $ds^2 = dx^2 + dy^2$ and the second fundamental form is

$$\frac{\partial^2 f}{\partial x^2} \, dx^2 + 2 \frac{\partial^2 f}{\partial x \, \partial y} \, dx \, dy + \frac{\partial^2 f}{\partial y^2} \, dy^2$$

(for a suitable choice of the unit normal) where all of the partial derivatives are evaluated at (0,0). Deduce that the Gaussian curvature at the origin is

$$K = \frac{\partial^2 f}{\partial x^2} \frac{\partial^2 f}{\partial y^2} - \left(\frac{\partial^2 f}{\partial y^2}\right)^2$$

Now suppose that $g : \mathbb{R}^2 \to \mathbb{R}$ is another smooth function with g(0,0) = 0 and $g(x,y) \ge f(x,y)$ for every $(x,y) \in \mathbb{R}^2$. Show that

$$\frac{\partial g}{\partial x}(0,0) = 0$$
, $\frac{\partial g}{\partial y}(0,0) = 0$

Show further that

$$\frac{\partial^2 g}{\partial x^2} u^2 + 2 \frac{\partial^2 g}{\partial x \, \partial y} \, uv + \frac{\partial^2 g}{\partial y^2} \, v^2 \geqslant \frac{\partial^2 f}{\partial x^2} \, u^2 + 2 \frac{\partial^2 f}{\partial x \, \partial y} \, uv + \frac{\partial^2 f}{\partial y^2} \, v^2$$

at (0,0) and deduce that

$$\begin{pmatrix} \frac{\partial^2 g}{\partial x^2} & \frac{\partial^2 g}{\partial x \partial y} \\ \frac{\partial^2 g}{\partial x \partial y} & \frac{\partial^2 g}{\partial y^2} \end{pmatrix} \geqslant \begin{pmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial x \partial y} & \frac{\partial^2 f}{\partial y^2} \end{pmatrix}$$

at (0, 0).

Does this imply that the Gaussian curvature of the graph of g at the origin is greater than or equal to the Gaussian curvature of the graph of f at the origin.

Please send any comment or corrections to t.k.carne@dpmms.cam.ac.uk .

Supervisors can obtain an annotated version of this example sheet from DPMMS.