

(1) Show the tangent space to  $S^2$  at a point  $P = (x, y, z) \in S^2$  is the plane normal to the vector  $\overrightarrow{OP}$ , where  $O$  denotes the origin.

(2) Let  $V$  be the open subset  $\{0 < u < \pi, 0 < v < 2\pi\}$ , and  $\sigma : V \rightarrow S^2$  be given by

$$\sigma(u, v) = (\sin u \cos v, \sin u \sin v, \cos u).$$

Prove that  $\sigma$  defines a smooth parametrization on a certain open subset of  $S^2$ . [You may assume that  $\cos^{-1}$  is continuous on  $(-1, 1)$ , and that  $\tan^{-1}, \cot^{-1}$  are continuous on  $(-\infty, \infty)$ .]

(3) Show the stereographic projection map  $\pi : S \setminus \{N\} \rightarrow \mathbf{C}$ , where  $N$  denotes the north pole, defines a chart. Check that the spherical metric on  $S \setminus \{N\}$  corresponds under  $\pi$  to the Riemannian metric on  $\mathbf{C}$  given by

$$4(dx^2 + dy^2)/(1 + x^2 + y^2)^2.$$

(4) For an embedded circular cylinder  $S$  in  $\mathbf{R}^3$ , show that the first fundamental form corresponds to a locally Euclidean Riemannian metric on  $S$ . Identify the geodesics on  $S$ .

(5) Given a smooth curve  $\Gamma : [0, 1] \rightarrow S$  on an abstract surface  $S$  with a Riemannian metric, show that the length  $l$  is unchanged under reparametrizations of the form  $f : [0, 1] \rightarrow [0, 1]$ , with  $f'(t) > 0$  for all  $t \in [0, 1]$ . Prove that there exists such a reparametrization  $\tilde{\Gamma} = \Gamma \circ f$  for which  $\|d\tilde{\Gamma}/dt\|$  is constant, namely  $l$ .

(6) Let  $T$  denote the embedded torus in  $\mathbf{R}^3$  obtained by revolving around the  $z$ -axis the circle  $(x - 2)^2 + z^2 = 1$  in the  $xz$ -plane. Using the formal definition of area in terms of a parametrization, calculate the surface area of  $T$ .

(7) If one places  $S^2$  inside a (vertical) circular cylinder of radius one, prove that the radial (horizontal) projection map from  $S^2$  to the cylinder preserves areas (this is usually known as *Archimedes Theorem*). Deduce the existence of an atlas on  $S^2$ , for which the charts all preserve areas and the transition functions have derivatives with determinant one.

(8) Show that a 2-holed torus may be obtained topologically by suitably identifying the sides of a regular octagon. Indicate briefly how to extend your argument to show that a  $g$ -holed torus may be obtained topologically by suitably identifying the sides of a regular  $4g$ -gon?

(9) Let  $S \subset \mathbf{R}^3$  be the ellipsoid  $x^2/a^2 + y^2/b^2 + z^2/c^2 = 1$ . If  $V \subset \mathbf{R}^2$  denotes the region  $u^2/a^2 + v^2/b^2 < 1$ , show that the map

$$\sigma(u, v) = (u, v, c(1 - u^2/a^2 - v^2/b^2)^{\frac{1}{2}})$$

determines a smooth parametrization of a certain open subset of  $S$ . Prove that the Gaussian curvatures at the points  $(a, 0, 0), (0, b, 0), (0, 0, c)$  are all equal if and only if  $S$  is a sphere.

(10) For a surface of revolution  $S$ , corresponding to a curve  $\eta : (a, b) \rightarrow \mathbf{R}^3$  given by  $\eta(u) = (f(u), 0, g(u))$ , where  $\eta$  is parametrized in such a way that  $\|\eta'\| = 1$ , prove that the second fundamental form at a given point is given by

$$(f'g'' - f''g')du^2 + fg'dv^2.$$

Deduce that the Gaussian curvature  $K$  is given by the formula  $K = -f''/f$ .

(11) Using the results from the previous question, calculate the Gaussian curvature  $K$  of the unit sphere. For the embedded torus, as defined in Question 6, identify those points at which  $K = 0$ ,  $K > 0$  and  $K < 0$ . Verify the global Gauss–Bonnet theorem on the embedded torus.

(12) Let  $S$  be an embedded surface in  $\mathbf{R}^3$  which is closed and bounded. By considering the smallest closed ball centred on the origin which contains  $S$ , or otherwise, show that the Gaussian curvature must be strictly positive at some point of  $S$ . Deduce that the locally Euclidean metric on the torus  $T$  cannot be realised as the first fundamental form for some smooth embedding of  $T$  in  $\mathbf{R}^3$ .

(13) Show that Mercator's parametrization of the sphere (minus poles)

$$\sigma(u, v) = (\operatorname{sech} u \cos v, \operatorname{sech} u \sin v, \tanh u)$$

determines a chart (on the complement of a longitude) which preserves angles and sends meridians and parallels on the sphere to straight lines in the plane.

(14) Show that a  $g$ -holed torus ( $g > 1$ ) may be given the structure of an abstract surface with a Riemannian metric, in such a way that it is locally isometric to the hyperbolic plane. [For this question, you will need an argument similar to Q8 on this sheet, and you will need the result from Q10 on Example Sheet 2.]

(15) Let  $f(u) = e^u$ ,  $g(u) = (1 - e^{2u})^{\frac{1}{2}} - \cosh^{-1}(e^{-u})$ , where  $u < 0$ , and  $S$  be the surface of revolution corresponding to the curve  $\eta : (-\infty, 0) \rightarrow \mathbf{R}^3$  given by  $\eta(u) = (f(u), 0, g(u))$ . Show that  $S$  has constant Gauss curvature  $-1$ ;  $S$  is called the *pseudosphere*. By considering coordinates  $v$  and  $w = e^{-u}$  on  $S$ , show that the pseudosphere is locally isometric to the open subset of the upper half-plane model of the hyperbolic plane given by  $\operatorname{Im}(z) > 1$ . Identify the geodesics in this model corresponding to the meridians in  $S$ . Show that any other geodesic in  $S$  has two distinct points of the circle  $x^2 + y^2 = 1, z = 0$  as limit points.

[It is a theorem that there are no complete embedded surfaces in  $\mathbf{R}^3$  with constant negative Gauss curvature, and so in particular we cannot realise all of the hyperbolic plane as an embedded surface.]

**Note to the reader :** You should look at all the questions up to Question 12, and then any further questions you have time for.