

The following are Tripos style questions on the Geometry course, Section I consisting of short questions and Section II of long questions. Questions 1,2,4 and 6 are based on recent Tripos questions.

SECTION I

(1) Explain how to obtain, from any convex polyhedron, a decomposition of the surface of the unit sphere into spherical polygons. State the Gauss–Bonnet theorem for the area of a spherical triangle.

Show that any regular polyhedron whose faces are pentagons has the same number of faces, edges and vertices as the dodecahedron.

(2) Using the Riemannian metric $(dx^2 + dy^2)/y^2$, define the length of a curve and the area of a region in the upper half-plane $H = \{x + iy : y > 0\}$.

Find the hyperbolic area of the region $\{(x, y) \in H : 0 < x < 1, y > 1\}$.

(3) Let V be an open subset of \mathbf{R}^2 , with a Riemannian metric $E du^2 + 2F du dv + G dv^2$. State (without proof) the equations for a smooth curve $\gamma : [0, 1] \rightarrow V$ to be geodesic.

Consider now the smooth parametrization $\sigma : (0, \pi) \times (0, 2\pi) \rightarrow U \subset S^2$ given by

$$\sigma(\rho, \theta) = (\sin \rho \cos \theta, \sin \rho \sin \theta, 1 - \cos \rho),$$

where U is the open subset of the unit sphere given as the complement of the longitude $y = 0, x \geq 0$. Find the first fundamental form in these coordinates. Verify that the curves $\Gamma(t)$ with both θ and $d\rho/dt$ constant are geodesics, and that these correspond to the spherical lines through $(0, 0, 1)$.

SECTION II

(4) Show that every isometry of Euclidean space \mathbf{R}^3 is a composition of at most four reflections in planes, and that an isometry which fixes the origin is a composition of at most three reflections.

Describe geometrically the isometries g of \mathbf{R}^3 fixing the origin which require three reflections. If g does not correspond to $-I$, show that there is a unique line through the origin sent to itself under g .

Describe (geometrically) all twelve orientation-reversing isometries of a regular tetrahedron. For those which are not pure reflections, identify a line through the centre of the tetrahedron which is mapped to itself.

(5) Describe geometrically the stereographic projection map $\phi : S^2 \rightarrow \mathbf{C}_\infty$, and find a formula for it. Let A denote the matrix

$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ -1 & 0 & 0 \end{pmatrix}$$

representing a rotation of S^2 through an angle $\pi/2$ about the y -axis. Show that A corresponds under ϕ to a Möbius transformation g , where $g(\zeta) = (\zeta - 1)/(\zeta + 1)$. Prove that any rotation of S^2 corresponds under ϕ to a Möbius transformation of \mathbf{C}_∞ . Deduce that the image under ϕ of a spherical circle on S^2 is a circle or straight line in \mathbf{C}_∞ .

(6) Show that for every hyperbolic line L in the hyperbolic plane H there is a *unique* isometry of H which is the identity on L but not on all of H . Call this the *reflection* R_L .

Prove that every isometry of H is a composition of reflections.

(7) Let $S \subset \mathbf{R}^3$ be the ellipsoid $x^2/a^2 + y^2/b^2 + z^2/c^2 = 1$. If $V \subset \mathbf{R}^2$ denotes the region $u^2/a^2 + v^2/b^2 < 1$, show in detail that the map

$$\sigma(u, v) = \left(u, v, c(1 - u^2/a^2 - v^2/b^2)^{\frac{1}{2}} \right)$$

determines a smooth parametrization of a certain open subset of S .

Calculate from first principles the first and second fundamental forms (in these coordinates) at the point $P = \frac{1}{\sqrt{3}}(a, b, c) \in S$. Prove that the Gaussian curvature at the point P is given by the formula

$$K = \frac{9a^2b^2c^2}{(a^2b^2 + b^2c^2 + c^2a^2)^2}.$$

Prove furthermore that the Gaussian curvatures at the points $(a, 0, 0)$, $(0, b, 0)$, $(0, 0, c)$ are all equal if and only if S is a sphere.