

A SYNTACTIC CHARACTERIZATION OF THE EQUALITY IN SOME MODELS FOR THE LAMBDA CALCULUS

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0. Introduction

An equality relation on the terms of the λ -calculus is an equivalence relation closed under the (syntactical) operations of application and λ -abstraction. We may distinguish between syntactic and semantic ways of introducing equality relations. β -equality is introduced syntactically; it is the least equality relation satisfying the equations for α - and β -conversion. For a more subtle way of introducing equality relations syntactically, consider the relations $=_f$ and $=_h$ of §5 of this paper. To give a semantic characterization of an equality relation, we simply take the relation ' \cdot ' has the same value in D' , where D is some model for the λ -calculus. Of course, no equality relation is of interest to the intended interpretation of the λ -calculus, unless it extends β -equality.

An equality relation is inconsistent if and only if it sets all terms equal; otherwise it is consistent. It is maximal consistent if and only if it is consistent and has no consistent proper extensions.

In this paper we consider a class of continuous lattice models for the λ -calculus, and a particular model, the Graph model. The same equality is induced by all the continuous lattice models; we shall refer to them as the Scott models (see [3], where they were first constructed). For the history of the Graph model see [4]. We shall give, in this paper, syntactic characterizations of the equality induced by the Scott models, and by the Graph model; and we shall show that the equality induced by the Scott models is the unique maximal consistent equality relation, extending the relation $=_H$, which was proved consistent in [1].

We use $x, y, z, w \dots$ for variables, and $M, N, P \dots$ for terms of the λ -calculus (with subscripts as necessary). D will refer to whatever model or models are under consideration.

The content of our Theorem 5.4 (a) has been discovered independently by C. P. Wadsworth.

1. Preliminaries

First, we collect together those facts that the reader needs to know about the Scott models. D is a complete lattice; we write \leq for the partial order, and \bigcup for the least upper bound. For each natural number n , there is $D_n \subset D$, such that

- (1) $D_n \subset D_{n+1}$,
- (2) D is the completion of the union of the D_n 's,
- (3) for each $n \in \omega$, $d \in D$, there is a maximal $c \leq d$, with $c \in D_n$; we write this c , as $(d)_n$,

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(4) (by the above) $d = \bigcup \{(d)_n \mid n \in \omega\}$,

(5) each D_{n+1} can be regarded as the set of continuous maps from D_n to D_n ; so there is defined a continuous application: $D_{n+1} \times D_n \rightarrow D_n$,

(6) D can be identified with the set of continuous maps from D to D , where $d \in D$ acts as a map by taking $c \in D$ to $d(c) = \bigcup \{d_{n+1}(c_n) \mid n \in \omega\}$,

(7) the following equations of Scott are satisfied:

$$d_{n+1}(c) = d_{n+1}(c_n) = (d(c_n))_n,$$

$$d_0(c) = d_0(\perp) = (d(\perp))_0.$$

Here \perp denotes the bottom element of the lattice D .

Details of the construction are in [3]. There a lattice isomorphic to its function space is determined by (a) the choice of D_0 , and (b) the maps $\phi: D_0 \rightarrow D_1$ and $\psi: D_1 \rightarrow D_0$. For our purpose D_0 may be chosen arbitrarily, but to ensure (7) above we take $\phi(d_0) = \lambda x. d_0$, $\psi(d_1) = d_1(\perp)$. This determines our class of continuous lattice models, the Scott models of this paper.

The natural interpretation of a term M in a Scott model D , (called its value, and written $\llbracket M \rrbracket$), is implicitly a value $\llbracket M \rrbracket_\rho$, depending on a valuation ρ of the free variables. It is defined by the induction.

$$\llbracket x \rrbracket_\rho = \rho(x),$$

$$\llbracket MN \rrbracket_\rho = \llbracket M \rrbracket_\rho(\llbracket N \rrbracket_\rho),$$

$$\llbracket \lambda x. P \rrbracket_\rho = \lambda d. \llbracket P \rrbracket_{\rho[d/x]},$$

where $\rho[d/x]$ denotes the valuation obtained from ρ by valuing x as d ; the expression $\lambda d \dots$ (is not a λ -term, but) represents a continuous map from D to D and so by (6) above can be taken as an element of D .

Now we describe the Graph model. D consists of all subsets of ω . Let us take a pairing function, defined by $(k, m) = \frac{1}{2}(k+m)(k+m+1) + m$; and if $k = 2^r + \dots + 2^r$, with $r_0 < \dots < r_n$, let e_k be the finite set $\{r_0, \dots, r_k\}$. On D , we define application and λ -abstraction as follows;

$$c(d) = \{m \mid (\exists k) (e_k \subset d \ \& \ (k, m) \in c)\}$$

$$\lambda x. \tau(x) = \{(k, m) \mid m \in \tau[e_k/x]\}.$$

For our purposes it is sufficient to take $\tau(x)$ to be a λ -term (though the definition is good whenever $\tau(x)$ is continuous in x in the sense of [4]), and then just repeating the definition we gave for the Scott models, we can define a value $\llbracket M \rrbracket$, of M in the Graph model.

For $d \in D$, we define $(d)_n = \{m \mid m \in d \ \& \ m \leq n\}$. Then the facts (1)–(4), above, hold for the Graph model (now \bigcup is real union etc.). Observe that

(a) if $k \in e_n$, then $k < n$,

(b) $m \leq (n, m)$ with equality only if $m = n = 0$,

(c) $n \leq (n, m)$ with equality only if $m = 0$ and $n = 0$ or 1.

These enable us to derive by straightforward computation the following basic

equations to correspond to (7) above;

$$d_{n+2}(c) = d_{n+2}(c_{n+1}) \subset (d(c_{n+1}))_{n+1},$$

$$d_1(c) = d_1(c_0) = (d(c_0))_0,$$

$$d_0(c) = d_0(\emptyset) = (d(\emptyset))_0.$$

This is all we need to know about the Graph model.

As in [5] we adjoin to the λ -calculus a constant term Ω , whose value shall be \perp in the Scott models, and \emptyset in the Graph model. This is a technical and heuristic device, but it adds nothing to the λ -definable elements in either model, as $\lambda x.(xx)$ ($\lambda x.(xx)$) has the same value as Ω (this is an immediate consequence of the approximation theorems of §2). Henceforth, "term" will mean "term of the extended calculus". It is clear how to define the value of an (extended) term.

2. The Approximation Theorems

We say that a term M is in normal form, if it has no β -subredexes, and no Ω -subredexes; an Ω -redex is a term of the form ΩN or $\lambda x.\Omega$. The appropriate notion of Ω -reduction is that any Ω -redex reduces to Ω . We define a set $\omega(M)$, the set of Ω -approximants to the term M , by $\omega(M) = \{L \mid L \text{ is in normal form and is obtained from some } N \text{ with } N =_{\beta} M \text{ by replacing subterms of } N \text{ by } \Omega\}$.

The purpose of this section is to show that the value $\llbracket M \rrbracket$ of M in our models is the limit (i.e. least upper bound or union respectively) of the values of the Ω -approximants of M .

We introduce the notion of an indexed term. An *indexed term* (M, I) , is a term M , together with a map I from the subterms of M to the natural numbers. The value, $\llbracket M \rrbracket_{\rho}^I$, of an indexed term (for a given valuation ρ , of the free variables) is given by

$$\llbracket x \rrbracket_{\rho}^I = (\rho(x))_{I(x)},$$

$$\llbracket \Omega \rrbracket_{\rho}^I = \perp \text{ or } \emptyset, \text{ in the Scott models or Graph model, respectively,}$$

$$\llbracket MN \rrbracket_{\rho}^I = (\llbracket M \rrbracket_{\rho}^I (\llbracket N \rrbracket_{\rho}^I))_{I(MN)},$$

$$\llbracket \lambda x.P \rrbracket_{\rho}^I = (\lambda d. \llbracket P \rrbracket_{\rho[d/x]}^I)_{I(\lambda x.P)}.$$

Here, the remarks following the similar definition in §1 apply; subscripts refer to the taking of the (finite) approximations $(d)_n$ as defined in §1. Finally, there should be no confusion caused by our using I both as an index map for MN and as its restriction to M (say).

LEMMA 2.1. *In both models, $\llbracket M \rrbracket = \bigcup \{\llbracket M \rrbracket^I \mid (M, I) \text{ is an indexed term}\}$.*

The proof is by a routine structural induction.

Now, adapting a useful idea (unpublished) of Wadsworth's which serves to simplify our original proof of (2.5), we introduce the notion of the *indexed reduction* of indexed terms. We use superscripts on terms to indicate the index associated with them (i.e. their value under I).

Indexed β -reduction

$(\lambda x. P^m)^{m+1}. Q^p$ reduces to $(P[Q^a/x])^b$, where b is the minimum of m and n , while a varies amongst substitution instances of Q and is the minimum of m, p , and the index of the x for which Q has been substituted;

$$(\lambda x. P^n)^0. Q^p \text{ reduces to } (P[\Omega^0/x])^0.$$

Indexed Ω -reduction

We define what it is for an *occurrence* of Ω to be *active* in a subterm of a term by

- (i) Ω is active in itself;
- (ii) if Ω is active in P , then it is active in $\lambda x. P$ and PN .

We remark that if Ω is active in L , then a series of Ω -reductions will reduce L to Ω . An indexed Ω -reduction consists in reducing (in one step) a maximal subterm in which a given occurrence of Ω is active to Ω . (Doing all possible Ω -reductions for a given occurrence at once simplifies the proof of (2.2)).

LEMMA 2.2. *Some indexed reduction of (M, I) terminates.*

Proof. Define $u(0) = \text{card}(\{A \mid (M, I) A \text{ is a subterm of } m \text{ which may be (indexed) } \Omega\text{-reduced}\})$,

$$u(n+1) = \text{card}(\{A \mid (M, I) A \text{ is a subterm of } m, \text{ of form } (\lambda x. P)^n. Q\}).$$

u is an eventually zero function from ω to ω . For such functions, u and v , let $u < v$ if and only if the greatest $i \in \omega$ such that $u(i) \neq v(i)$ is such that $u(i) < v(i)$. Plainly, $<$ is a well-ordering on these functions. Also, by reducing from the "inside-out", (M, I) index reduces to (M', I') with corresponding u and u' such that $u' < u$. Hence some reduction sequence terminates.

LEMMA 2.3. (a) *In the Scott models, indexed reduction preserves the value of an indexed term.*

(b) *In the Graph model, if (M, I) index reduces to (M', I') , then we have $\llbracket M \rrbracket^I \subset \llbracket M' \rrbracket^{I'}$.*

Proof. This is simply a reproof of the fact that β - (and Ω -) reduction do not alter the values of terms. One uses equations (7) of §1 (or their counterparts for the Graph model) to keep track of the indices.

LEMMA 2.4. *For any (M, I) , there is (L, J) , with $L \in \omega(M)$, and $\llbracket M \rrbracket^I \subset \llbracket L \rrbracket^J$.*

Proof. The proof is by (2.2) and (2.3), since indexed reductions terminate in Ω -approximants. (Of course, \subset can be replaced by $=$ for the Scott models in (2.4).)

THEOREM 2.5. *In both models, $\llbracket M \rrbracket = \bigcup \{\llbracket L \rrbracket \mid L \in \omega(M)\}$.*

Proof. If $L \in \omega(M)$, L is obtained from a term with the same value as M , by replacing subterms by Ω , and so $\llbracket L \rrbracket \subset \llbracket M \rrbracket$. But by (2.1) and (2.4), we have $\llbracket M \rrbracket \subset \bigcup \{\llbracket L \rrbracket \mid L \in \omega(M)\}$. Hence the result.

COROLLARY. If M has no hnf (see §3), then $\llbracket M \rrbracket$ is \perp or \emptyset .

3. Head normal forms

We define which terms, M , are *head normal forms* (we write, “ M is hnf”), by:

- (a) all variables are hnf;
- (b) if X_1, \dots, X_k are terms and x is a variable, then $xX_1 \dots X_k$ is hnf;
- (c) if P is hnf, then $\lambda x.P$ is hnf.

M has hnf if and only if there is $N =_{\beta} M$ and N is hnf. Otherwise, M has no hnf. An hnf has the form, $\lambda x_1 \dots x_k.zX_1 \dots X_l$, and z is the *head variable*. A non-hnf has the form, $\lambda x_1 \dots x_k.(\lambda y.P)X_1 \dots X_l$; the *head redex* is $(\lambda y.P)X_1$, and the (possibly infinite) reduction of a term, obtained by always reducing the head redex if any, is the *head reduction*. By the Standardization Theorem, M has hnf if and only if its head reduction terminates; and hence the set of terms with no hnf has strong closure properties (see [5]). A term has hnf if and only if its closure is soluble in the sense of Barendregt [1].

Let $\lambda x_1 \dots x_m.zX_1 \dots X_k$ and $\lambda y_1 \dots y_n.wY_1 \dots Y_l$, be two hnfs. We may assume that (say) $n \leq m$, and then by α -conversion, that each y_i is x_i . The hnfs are *similar* if and only if z is w and $(m-k) = (n-l)$. The point of this definition is that when two hnfs are not similar, then we can find a context which reduces them to distinct variables (see §4 for elucidation). Thus two dissimilar hnfs can never be set equal consistently with β -equality.

Now we define, for $k \geq 1$, (a) M and N have the same *k-normal form* (written $M =_k N$), and (b) the set of *k-pairs* of (M, N) , as follows. If both M and N have no hnf, then $M =_1 N$, and there are no 1-pairs. Otherwise, $M =_1 N$ if and only if they have similar hnfs; then let M' and N' be the hnfs obtained by head reduction; M' is $\lambda x_1 \dots x_m.zX_1 \dots X_k$ and N' is $\lambda y_1 \dots y_n.wY_1 \dots Y_l$; making the same assumptions as above, we write $M'x_1 \dots x_m =_{\beta} zX_1 \dots X_k$ and $N'x_1 \dots x_m =_{\beta} wY_1 \dots Y_l x_{n+1} \dots x_m$ which is $Y_1' \dots Y_l'$, say; then the 1-pairs of (M, N) are the (X_i, Y_i') for $i \leq k$. Now for the induction step of the definition, we set $M =_{k+1} N$ if and only if $M =_1 N$ and for any 1-pairs of (M, N) , (X, Y) say, we have $X =_k Y$; the $k+1$ -pairs of (M, N) are the k -pairs of its 1-pairs.

Remarks:

- (1) In the induction we could interchange the role of 1 and k .
- (2) If $k > 1$, then (M, N) can have k -pairs, without $M =_k N$.
- (3) $M =_k N$ means roughly that M and N are similar down to depth k (with the agreement that non-hnfs are similar).

We now introduce relations $<_k^s, k \geq 1$, and $<_k^g, k \geq 1$. The superscripts s and g indicate that the relations are useful for the Scott and Graph models, respectively.

We set $M <_1^s N$ if and only if either $M =_1 N$ or M has no hnf (i.e. $M =_1 \Omega$); and by induction, $M <_{k+1}^s N$ if and only if $M <_1^s N$ and for any 1-pairs (X, Y) we have $X <_k^s Y$.

Remarks:

(1) Plainly $M =_k N$ if and only if $M <_k^s N$ and $N <_k^s M$.

(2) Roughly, $M <_k^s N$ means that M and N are similar down to depth k , except "at subterms of M which have no hnf".

We set $M <_1^s N$ if and only if either M has no hnf or $M =_1 N$ and if we obtain by head reduction $M =_\beta \lambda x_1 \dots x_m. z X_1 \dots X_k$ and $N =_\beta \lambda x_1 \dots x_n. z Y_1 \dots Y_l$, then $m \leq n$ (i.e. M is essentially less functorial than N); again by induction, $M <_{k+1}^s N$ if and only if $M <_1^s N$ and for any 1-pairs (X, Y) , we have $X <_k^s Y$.

These relations seem the right ones with which to attempt to approximate \subset in the models, because (a) they take into account that terms with no hnf have value \perp , or \emptyset and (b) they look deeper and deeper into the terms as k increases; the definition of $<_k^s$ takes into account the fact that η -expansion increases the value of a term in the Graph model. The ensuing results make this clearer. (For the rest of this section, $<_k$ refers to the relation appropriate to the model considered).

LEMMA 3.1. *If L is a normal form, and for all k , $L <_k N$, then $\llbracket L \rrbracket \subset \llbracket N \rrbracket$.*

Proof. The proof is by induction on the structure of normal forms. We shall not need to distinguish between the models until the very end.

(i) L is Ω , and the result is trivial.

(ii) L is x ; we are assuming $x <_k N$ for all k , so in particular $N =_\beta \lambda y_1 \dots y_r. x Y_1 \dots Y_r$; by (2.5), it is sufficient to show that for any index I , for x , $\llbracket x \rrbracket^I \subset \llbracket N \rrbracket$; we do this by induction:

Case $I(x) = 0$; then $\llbracket x \rrbracket^I = (\llbracket x \rrbracket)_0 = (\llbracket \lambda y_1 \dots y_r. (x)_0 \Omega \dots \Omega \rrbracket)_0$, by the usual basic equations; thus $\llbracket x \rrbracket^I \subset \llbracket N \rrbracket$.

Case $I(x) = n+1$ (the induction step); using superscripts to indicate indices again, we have $\llbracket (x)^{n+1} \rrbracket \subset \llbracket \lambda y_1 \dots y_r. (x)^{n+1} (y_1)^n \dots (y_r)^{n-r+1} \rrbracket$, by the usual equations; (in the Scott model case we would have equality here); now for all k , $y_i <_k Y_i$, and so by induction hypothesis, $\llbracket (y_1)^n \rrbracket \subset \llbracket Y_1 \rrbracket$, ... $\llbracket (y_r)^{n-r+1} \rrbracket \subset \llbracket Y_r \rrbracket$; hence $\llbracket x \rrbracket^I \subset \llbracket N \rrbracket$.

(iii) Let L be $\lambda x_1 \dots x_m. x X_1 \dots X_r$, where the X_i are normal forms for which we already have our result. We take our models separately.

The Scott model case: we can take

$$N =_{\beta\eta} \lambda x_1 \dots x_{m+s}. x X_1 \dots X_{r+s}, \quad \text{and} \quad L =_{\beta\eta} \lambda x_1 \dots x_{m+s}. x X_1 \dots X_{r+s}$$

(where if $s > 0$, X_{r+s} is x_{m+s} and so on); for all k , $X_i <_k Y_i$ and so $\llbracket X_i \rrbracket \subset \llbracket Y_i \rrbracket$; hence $\llbracket L \rrbracket \subset \llbracket N \rrbracket$. This completes the proof in the Scott model case.

The Graph model case: we have $N =_\beta \lambda x_1 \dots x_{m+s}. x Y_1 \dots Y_{r+s}$; by the basic equations, we have $\llbracket L \rrbracket \subset \llbracket \lambda x_1 \dots x_{m+s}. x X_1 \dots X_{r+s} \rrbracket$; now we can argue as in the Scott model case. This completes the proof of Lemma (3.1).

THEOREM 3.2. *If, for all k , $M <_k N$, then $\llbracket M \rrbracket \subset \llbracket N \rrbracket$.*

Proof. If not $\llbracket M \rrbracket \subset \llbracket N \rrbracket$, then by (2.5) there is $L \in \omega(M)$ with not $\llbracket L \rrbracket \subset \llbracket N \rrbracket$. But by the Church-Rosser theorem, we find that if $L \in \omega(M)$, then for all k , $L <_k M$. Then by obvious transitivity, $L <_k N$ for all k , which will contradict (3.1).

4. Two technical lemmas

A context $C[]$ gives for every term M a term $C[M]$, which is the result of substituting M for the blank in $C[]$; in this process free variables of M may get bound (i.e. no attempt is made to prevent this). In other words $C[M]$ and $C[N]$ are obtained from M and N by the same series of applications and λ -abstractions. Equality relations as defined in §0 are closed under context substitution. The following lemmas exploit this fact to give conditions which guarantee that terms M and N cannot be set equal. They are the essential content of [2].

LEMMA 4.1. *Given M and N , with (X, Y) k -pairs of (M, N) , there is a context $C[]$, such that $C[M] =_{\beta} X(R/x, \dots)$, some substitution instance of X , while $C[N] =_{\beta} Y(R/x, \dots)$, the same substitution instance of Y ; the terms substituted are all of the form $\lambda x_1 \dots x_h. x_h x_1 \dots x_{h-1}$, for h sufficiently large; R_h will denote this term.*

Proof. We give the induction step on k , which also establishes the case $k = 1$. Suppose (X, Y) are 1-pairs of (U, V) which are $(k-1)$ -pairs of (M, N) , and we have the lemma for $(k-1)$. Thus we have a context $C_1[]$, such that

$$C_1[M] =_{\beta} U(\dots) =_{\beta} (\lambda x_1 \dots x_m. z A_1 \dots A_r)(\dots),$$

and

$$C_1[N] =_{\beta} V(\dots) = (\lambda x_1 \dots x_n. z B_1 \dots B_s)(\dots),$$

where $m \geq n$ say, and where (\dots) will continue to denote some substitutions about which we have no need to be explicit. Now,

$C_1[M]x_1 \dots x_m =_{\beta} z A_1 \dots A_r(\dots)$, and $C_1[N]x_1 \dots x_m =_{\beta} z B_1' \dots B_r'(\dots)$, and (X, Y) is (A_i, B_i') , for some i .

We separate into cases:

(a) Suppose that z is not free in X or Y , and that (\dots) does not substitute anything for z ; set $C[M]$ to be

$$(\lambda z. C_1[M]x_1 \dots x_m) (\lambda y_1 \dots y_r. y_i) =_{\beta} X(\dots),$$

and then $C[N] =_{\beta} Y(\dots)$.

(b) Suppose that z is free in X or in Y , but (\dots) does not substitute anything for z ; then set $C[M]$ to be

$$\left((\lambda z. C_1[M]x_1 \dots x_m) R_h \right) w_{r+1} \dots w_{h-1} (\lambda x_1 \dots x_{h-1}. x_i) =_{\beta} X(\dots) (R_h/z),$$

and then $C[N] =_{\beta} Y(\dots) (R_h/z)$. The primary intention of this manoeuvre is to prevent our substituting $(\lambda x_1 \dots x_r. x_i)$ into X or Y ; so we must take $h > r$.

(c) Suppose that (\dots) does substitute for z ; we may assume that R_h was substituted for z , where $h > r$; then set $C[M]$ to be $(C_1[M]w_{r+1} \dots w_{h-1}) (\lambda x_1 \dots x_{h-1}. x_i) =_{\beta} X(\dots)$, and then $C[N] =_{\beta} Y(\dots)$. This completes the proof.

The point of (4.1) is that if M and N are to be set equal (together with β -equality), then (substitution instances of) k -pairs of (M, N) must be set equal. We now prove a lemma which shows what terms can never be set equal (consistently with β -equality).

LEMMA 4.2. *If not $M <_1^s N$, and M' and N' are substitution instances of M and N of the form mentioned in (4.1), then either (a) both M and N have hnf (but these are not*

similar), and then there is a context $C[\]$, such that $C[M'] =_{\beta} x$ and $C[N'] =_{\beta} y$ where x and y are distinct variables, or (b) M has hnf but $N =_1 \Omega$, and there is a context $C[\]$, such that $C[M'] =_{\beta} x$ and $C[N'] =_1 \Omega$.

Proofs. We only do (a), as (b) is similar but easier because of the strong closure properties of non-hnfs. Cases where substitutions have been made for the head variable of the hnfs of M and N can be reduced to those we consider, by the methods of (4.1); so this leaves us with the following two cases:

Case (i): Head variables distinct; so $M =_{\beta} \lambda x_1 \dots x_m. z X_1 \dots X_k, N =_{\beta} \lambda x_1 \dots x_n. w Y_1 \dots Y_l$, z is not w and $m \geq n$, say. Since to get M' and N' , nothing has been substituted for z or w , set $C[M']$ to be $(\lambda z w. M' x_1 \dots x_m x y) (\lambda a_1 \dots a_{k+2}. a_{k+1}) (\lambda b_1 \dots b_r. b_r)$, where $r = l + m - n + 2$. Then $C[M'] =_{\beta} x$, and $C[N'] =_{\beta} y$.

Case (ii): Head variables the same;

$$M =_{\beta} \lambda x_1 \dots x_m. z X_1 \dots X_k, \quad N =_{\beta} \lambda x_1 \dots x_n. z Y_1 \dots Y_l, \quad \text{and } (m-k) \neq (n-l);$$

$m \geq n$, say; then

$$M' x_1 \dots x_m =_{\beta} z X_1' \dots X_k', \quad \text{and } N' x_1 \dots x_m =_{\beta} z Y_1' \dots Y_r',$$

where $r = m + l - n$; take $s > |r - k|$ and set $C'[M']$ to be $(\lambda z. M' x_1 \dots x_m y_1 \dots y_s) R_h$, where $h = \min(r, k) + s$; then $C'[M']$ and $C'[N']$ are suitable for applying the technique of case (i). So the proof is completed for this case also.

5. The main results

First we define (syntactically) some equality relations:

- (i) $M <_h N$ if and only if for all contexts $C[\]$, $C[M] <_1^s C[N]$; $M =_h N$ if and only if $M <_h N$ and $N <_h M$.
- (ii) $M <_f N$ if and only if for all contexts $C[\]$, $C[M] <_1^s C[N]$; $M =_f N$ if and only if $M <_f N$ and $N <_f M$.
- (iii) let $=_H$ be the equality generated by the axioms for β -equality, together with $M = N$ whenever both M and N have no hnf.

Remarks:

- (1) By (4.2), $M <_h N$ if and only if whenever $C[M]$ has hnf, then so has $C[N]$.
- (2) The main result of [2] is that if M and N are distinct $\beta\eta$ -normal forms (of the pure calculus), then there is a context $C[\]$ such that $C[M] =_{\beta} x$, while $C[N] =_{\beta} y$ (x and y distinct variables). Thus the consistency of $=_h$ and $=_f$ is assured. We prove much more below.
- (3) The consistency of $=_H$ was proved in [1].

LEMMA 5.1. (a) If $\llbracket X \rrbracket \subset \llbracket Y \rrbracket$ in the Scott models, then $X <_1^s Y$.

(b) If $\llbracket X \rrbracket \subset \llbracket Y \rrbracket$ in the Graph model, then $X <_1^s Y$.

Proof. For (a): by (4.2), if not $X <_1^s Y$, there is context $C[]$ with $C[X] =_\beta x$, while $C[Y] =_\beta y$ or Ω . Thus $\llbracket C[X] \rrbracket$ is not less than $\llbracket C[Y] \rrbracket$, so not $\llbracket X \rrbracket \subset \llbracket Y \rrbracket$. For (b): if not $X <_1^s Y$, either not $X <_1^s Y$ and we apply the argument for (a), or we have $X =_\beta \lambda x_1 \dots x_{n+r} . x X_1 \dots X_{k+r}$, and $Y =_\beta \lambda x_1 \dots x_n . x Y_1 \dots Y_k$, with $r > 0$. In this latter case, set X' to be $X x_1 \dots x_n =_\beta \lambda x_{n+1} \dots x_{n+r} . x X_1 \dots X_{k+r}$, and Y' to be $Y x_1 \dots x_n =_\beta x Y_1 \dots Y_k$. Now set $\rho(x) = \{0\}$, and then $\llbracket Y' \rrbracket = \{0\}$, while $\llbracket X' \rrbracket$ is an infinite set. Again not $\llbracket X \rrbracket \subset \llbracket Y \rrbracket$.

LEMMA 5.2. (a) If $\llbracket M \rrbracket \subset \llbracket N \rrbracket$ in the Scott models, then $M <_h N$.

(b) If $\llbracket M \rrbracket \subset \llbracket N \rrbracket$ in the Graph model, then $M <_f N$.

Proof. In either case, if the right hand side does not hold, we have a context $C[]$, and we apply (5.1) to $C[M]$ and $C[N]$.

LEMMA 5.3. (a) If $M <_h N$, then, for all k , $M <_k^s N$.

(b) If $M <_f N$, then, for all k , $M <_k^g N$.

Proof. The cases are identical, so we write $<_k$ without superscript. If there is k with not $M <_k N$, then there are k -pairs (X, Y) of (M, N) with not $X <_1 Y$. By (4.1), we have a context $C[]$, and $C[M] =_\beta X(\dots)$, $C[N] =_\beta Y(\dots)$, where (\dots) denotes various substitutions. But it is easy to see (cf. the proof of (4.2)) that $X(\dots) <_1 Y(\dots)$ cannot hold. Hence not $M <_h N$.

THEOREM 5.4. (a) For the Scott models $\llbracket M \rrbracket \subset \llbracket N \rrbracket$ if and only if $M <_h N$ if and only if, for all k , $M <_k^s N$.

(b) For the Graph model $\llbracket M \rrbracket \subset \llbracket N \rrbracket$ if and only if $M <_f N$ if and only if, for all k , $M <_k^g N$.

Proof. The proof is by (3.2), (5.2) and (5.3).

COROLLARY. (a) For the Scott models $\llbracket M \rrbracket = \llbracket N \rrbracket$ if and only if $M =_h N$.

(b) For the Graph model $\llbracket M \rrbracket = \llbracket N \rrbracket$ if and only if $M =_f N$.

This corollary presents our syntactic characterization of the equalities in our models. We prove in conclusion a remarkable further characterization of the equality in the Scott models.

THEOREM 5.5. $=_h$ (and hence the equality in the Scott models) is the unique maximal consistent equality extending $=_H$.

Proof. Consistency is clear. It remains to show that if not $M =_h N$, then adding $M = N$ to the axioms for $=_H$ produces an inconsistency. But if, say, not $M <_h N$, then there is a context $C[]$ such that $C[M]$ has hnf while $C[N]$ has no hnf. Then (in the standard combinators) $C[N] =_H Y(K)$. But a lemma of [1] shows how to derive inconsistency from the equality of any hnf with $Y(K)$. This completes the proof.

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